UNIVERSIDADE FEDERAL DO RIO GRANDE DO NORTE DEPARTAMENTO DE INFORMÁTICA E MATEMÁTICA APLICADA (DIMAP) PROGRAMA DE PÓS-GRADUAÇÃO EM SISTEMAS E COMPUTAÇÃO

Proof of laws from the operational semantics of *Circus*

Samuel Lincoln Magalhães Barrocas

Orientador: Prof. Dr. Marcel Vinícius Medeiros Oliveira

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Appendix A

Circus Denotational Semantics

On this annex, we will show some used Denotational Semantics laws of *Circus*. All these laws were extracted from [6].

Definition A.1. *Variable Block Denotational Definition: var $x : T \bullet A = \exists x, x' : T \cdot A$

Proof The law was created on document [6]..

Definition A.2. **Prefixing Denotational Definition* $l \rightarrow Skip = R$ (true \vdash doC (l, C) \land vars' = vars)

Where

- 1 is a communication
- doC is defined on **B**.32
- v is the set of variables of the state space (not including either ok, wait, ref or tr)

The definition was created on [6].

Definition A.3. *Skip Denotational Definition:

 $Skip = R(true \vdash tr' = tr \land \neg wait' \land v' = v)$

The definition was created on [6].

Definition A.4. *Assignment Denotational Definition: x := e = R (true $\vdash x' = e \land u' = u \land \neg$ wait')

Where $u = v - \{x\}$. The definition was created on [6].

Definition A.5. *If-Guarded Command Denotational Definition: if $[] i \bullet g_i \to A_i$ fi = $R ((\bigvee i \bullet g_i) \land (\bigwedge i \bullet g_i \Rightarrow \neg A_i \overset{f}{f}) \vdash \bigvee i \bullet (g_i \land A_i \overset{f}{f}))$

The definition lies on [6].

Definition A.6. *Specification Statement Denotational Definition:

 $w: [pre, post] = R(pre \vdash post \land \neg wait' \land tr' = tr \land u' = u)$

The definition lies on [6].

Appendix B

Proofs of rules of the Operational Semantics of *Circus*

On this appendix we will show the proofs of Soundness of the rules of the Operational Semantics of *Circus* we developed for this thesis. The rules were proved sound with respect to the Denotational Semantics of *Circus*, that is the theory of *Circus* in the Unifying Theories of Programming.

Each proof can be of a lemma, a theorem, a law or a rule from the Operational Semantics of *Circus*. Each proof has a sequence of sub-goals, that are intermediate expressions that compose the proof, and tactics, that transform a sub-goal on another sub-goal. The format of each proof is shown as follows:

Sub-goal 1 Op [Tactic] ... Op [Tactic] Sub-goal n

Each tactic is highlighted in **bold**, and each operator **Op** can be either "=", " \Rightarrow " or " \sqsubseteq ". When the tactic uses either a theorem, a lemma, a rule or a definition, it will indicate what theorem, lemma, rule or definition it is and having an hyperlink to it.

B.1 Proving the Soundness of a rule

To prove that a rule of the Operational Semantics of *Circus* is sound with respect to the Denotational Semantics of *Circus* (the theory of *Circus* on the Unifying Theories of Programming) means that the transition from the rule is a predicate that is **true**. We will

exemplify a proof of Soundness for the rule of the Guard construct. The rule for Guard construct was created by [3] and proved correct on this PhD thesis (see table B.1). The rule is shown as follows:

 $\frac{c \quad (s \ ; \ g)}{(c \mid s \models g \ \& \ A) \xrightarrow{\tau} (c \land (s \ ; \ g) \mid s \models A)}$

Thus, what we want is to show that the silent transition

$$(c \mid s \models g \& A) \xrightarrow{\tau} (c \land (s ; g) \mid s \models A)$$

is a predicate that is **true**. The factors that above the line, c and s; g, are provisos of the proof: a proviso is an expression that is assumed **true** for the proof. So, the rule assumes that c is **true** and that s; g is **true**.

Before proving the expression above, we will create a theorem and prove it: it is called Refinement Equal Sides:

Theorem - Refinement Equal Sides:

 $EXPR \sqsubseteq EXPR$

Proof:

 $EXPR \sqsubseteq EXPR$

(The expression we want to prove is the one above. A refinement expression $E1 \sqsubseteq E2$ equals $[E2 \Rightarrow E1]$, where the brackets mean universal quantification on the free-variables of the expression:) = [EXPR \Rightarrow EXPR]

(Now we apply a Predicate Calculus: an implication expression consists on a disjunction
("or" operator) between the negation of the left side and the right side:)
= [¬ EXPR ∨ EXPR]
= [true]
= true

We start our proof with the first sub-goal, which is the expression itself:

Proof:

 $(c \mid s \models g \& A) \xrightarrow{\tau} (c \land (s ; g) \mid s \models A)$

(As we saw from the definitions of Silent and Labelled Transition (see ?? and ??), a transition on the Operational Semantics is, in fact, a predicate expression on the UTP. So, the first tactic that we will apply on the proof is to transform the operational representation of the transition into its denotational predicate expression, resulting on the predicate shown below)

 $= \forall w . (c \land c \land (s ; g)) \Rightarrow ((Lift (s) ; g \& A) \sqsubseteq (Lift (s) ; A))$

(Our second tactic deals with the presence of variable w being universally quantified. When we prove that a given predicate is true, we prove that it is true for all possible values of its variables. So, during a proof, the whole expression is quantified, including w. So we can abstract the occurrence of w:)

 $= (c \land c \land (s ; g)) \Rightarrow ((Lift (s) ; g \& A) \sqsubseteq (Lift (s) ; A))$

(We have, as an assumption, that c is true. So, our tactic now is to replace all occurrences of c by true)

 $= (true \land true \land (s ; g)) \Rightarrow ((Lift (s) ; g \& A) \sqsubseteq (Lift (s) ; A))$

(*Our tactic now is to apply a predicate calculus such that true* \land *P equals P*) = (true \land (s ; g)) \Rightarrow ((Lift (s) ; g & A) \sqsubseteq (Lift (s) ; A))

(We apply, again, the same tactic: true $\land P$ equals P) = ((s ; g)) \Rightarrow ((Lift (s) ; g & A) \sqsubseteq (Lift (s) ; A))

(We now divide the proof in two parts: one in which we prove the above expression is true for g being **true**, and the other in which we prove that the above expression is **true** for g being false. If we prove that, for both cases, the above expression is true, then it is true for any value of g)

Part 1 - for g = true:

 $(s;g) \Rightarrow ((Lift(s);g \& A) \sqsubseteq (Lift(s);A)))$

(We simply replace g by true) = (s ; true) \Rightarrow ((Lift (s) ; true & A \sqsubseteq (Lift (s) ; A))

(This tactic now transforms expression true & A into A using a theorem called True Guard, that says that g & A = A. This theorem lies on [6]) = (s; true) \Rightarrow ((Lift (s); A) \sqsubseteq (Lift (s); A)

 $= (s ; true) \Rightarrow ((Lift (s) ; A) \sqsubseteq (Lift (s) ; A))$

(Now we apply the theorem we have proved correct: Refinement Equal Sides)
= (s ; true) ⇒ true

(We apply now Predicate Calculus: when the consequent of an implication is true, then the whole expression is true:) = true

Part 2 - for g = false:

 $(s;g) \Rightarrow ((Lift(s);g\&A) \sqsubseteq (Lift(s);A)))$

(We simply replace g by false) = (s; false) \Rightarrow ((Lift (s); false & A) \sqsubseteq (Lift (s); A))

(We remove w from the expression using a similar strategy from Part 1:) = (s; false) \Rightarrow ((Lift (s); false & A) \sqsubseteq (Lift (s); A))

(*There is a theorem, on* [4], *that says that s; false equals false. So we make the replacement:*) = false \Rightarrow ((Lift (s) ; false & A) \sqsubseteq (Lift (s) ; A))

(By Predicate Calculus, if we have false on the antecedent of an implication, then the whole expression is true) = true

The proof for rule of Guard is shown at 11.

Beyond the proofs of soundness that we have made for the rules of *Circus* (some of which created by ourselves), we also encompass, on this document, previous results on the soundness of the Operational Semantics of Woodcock's Operational Semantics. We will show a summary of rules.

| Rule (CML/Circus Actions) | Created by | Proved by | | | | | | |
|---------------------------------------|------------------------------|--------------------------|--|--|--|--|--|--|
| Assignment | (Woodcock et al 2013) | (Woodcock et al 2013) | | | | | | |
| Input (Prefixing) | (Woodcock et al 2013) | (Woodcock et al 2013) | | | | | | |
| Output (Prefixing) | (Woodcock et al 2013) | (Woodcock et al 2013) | | | | | | |
| Variable Block Begin | (Woodcock et al 2013) | Samuel Barrocas | | | | | | |
| Variable Block Visible | (Woodcock et al 2013) | Samuel Barrocas | | | | | | |
| Variable Block End | (Woodcock et al 2013) | Samuel Barrocas | | | | | | |
| Sequence Progress | (Woodcock et al 2013) | Samuel Barrocas | | | | | | |
| Sequence End | (Woodcock et al 2013) | Samuel Barrocas | | | | | | |
| Internal Choice Left | (Woodcock et al 2013) | (Woodcock et al 2013) | | | | | | |
| Internal Choice Right | (Woodcock et al 2013) | (Woodcock et al 2013) | | | | | | |
| Guard | (Woodcock et al 2013) | Samuel Barrocas | | | | | | |
| External Choice Begin | (Woodcock et al 2013) | (Woodcock et al 2013) | | | | | | |
| External Choice End | (Woodcock et al 2013) | (Woodcock et al 2013) | | | | | | |
| External Choice Skip | (Woodcock et al 2013) | (Woodcock et al 2013) | | | | | | |
| Ext. Choice Silent Left | (Woodcock et al 2013) | Samuel Barrocas | | | | | | |
| Ext. Choice Silent Right | (Woodcock et al 2013) | Samuel Barrocas | | | | | | |
| Parallel Begin | (Woodcock et al 2013) | (Woodcock et al 2013) | | | | | | |
| ¹ Parallel Ind. Left (PIL) | (Woodcock et al 2013) | Samuel Barrocas | | | | | | |
| ² Parallel Indep. Right | (Woodcock et al 2013) | Samuel Barrocas | | | | | | |
| Parallel Synchronised | (Woodcock et al 2013) | Samuel Barrocas | | | | | | |
| Parallel End | (Woodcock et al 2013) | (Woodcock et al 2013) | | | | | | |
| Hiding Internal | (Woodcock et al 2013) | Samuel Barrocas | | | | | | |
| Hiding Visible | (Woodcock et al 2013) | Samuel Barrocas | | | | | | |
| Hiding Skip | Samuel Barrocas | Samuel Barrocas | | | | | | |
| Recursion | (Woodcock et al 2013) | Samuel Barrocas | | | | | | |
| If-Guarded-Command | Samuel Barrocas | Samuel Barrocas | | | | | | |
| Call Action No Params | Samuel Barrocas | Samuel Barrocas | | | | | | |
| Call Action W/Params | Samuel Barrocas | Samuel Barrocas | | | | | | |
| Rename Action | Samuel Barrocas | Samuel Barrocas | | | | | | |
| Alphabetised Par. Act. | Samuel Barrocas | Not proved (future work) | | | | | | |
| Parameter Action Call | Samuel Barrocas | Samuel Barrocas | | | | | | |
| Iterated Actions | Samuel Barrocas | Samuel Barrocas | | | | | | |
| Parameter Action | Samuel Barrocas | Samuel Barrocas | | | | | | |
| Specification Statement | Samuel Barrocas | Samuel Barrocas | | | | | | |
| Schema Action | Samuel Barrocas ³ | Samuel Barrocas | | | | | | |

| Circus process | Created by | Proved by | | | | | |
|--------------------------------------|------------------------------|-----------------|--|--|--|--|--|
| Basic Process Begin | Samuel Barrocas ⁴ | Samuel Barrocas | | | | | |
| Basic Process Reduction | Samuel Barrocas | Samuel Barrocas | | | | | |
| Hiding Advance | Samuel Barrocas | Samuel Barrocas | | | | | |
| Hiding Basic Process | Samuel Barrocas | Samuel Barrocas | | | | | |
| Rename Advance | Samuel Barrocas | Samuel Barrocas | | | | | |
| Rename Basic Process | Samuel Barrocas | Samuel Barrocas | | | | | |
| Compound Process Left | Samuel Barrocas | Samuel Barrocas | | | | | |
| Compound Process Right | Samuel Barrocas | Samuel Barrocas | | | | | |
| Call process with normal parameters | Samuel Barrocas | Samuel Barrocas | | | | | |
| Call process with indexed parameters | Samuel Barrocas | Samuel Barrocas | | | | | |
| Call process with generic parameters | Samuel Barrocas | Samuel Barrocas | | | | | |
| Iterated Processes | Samuel Barrocas | Samuel Barrocas | | | | | |

¹ and ²: in the case of Parallel Independent Left and Parallel Independent Right, (Woodcock et al 2013) created a section to prove the soundness of these rules, but did not prove it; ³: this rule was adapted from [1] and proved correct on this PhD thesis;

B.2 Auxiliary Definitions, Lemmas, Theorems and Laws

This appendix shows all definitions, lemmas, theorems and laws used on (or created by) this document. Those marked with a * consist on definitions that were created or quoted by other authors (quoted after each definition). Those without * were created on this document. We will begin showing Auxiliary Definitions.

B.2.1 Auxiliary Definitions

Definition B.1. *getAssignments* is an auxiliary function (created for this document) that calculates the sequence of assignments of a node whose program text is a process. When the parameter of getAssignments is a Circus action Act, it returns the assignments s of the node whose program text is Act:

 $\frac{(c_1 \mid s_1 \models A_1) \xrightarrow{a} (c_2 \mid s_2 \models A_2)}{\text{getAssignments } (A_1) = s_1 \land \text{getAssignments } (A_2) = s_2}$

For Example:

(*true* | { } $\models a \rightarrow STOP$) \xrightarrow{a} (*true* | { } $\models STOP$) getAssignments ($a \rightarrow STOP$) = { }

When the parameter is a Circus process, getAssignments has the following definition:

- getAssignments (begin state ST = [decl | inv] Act end) = getAssignments (Act)
- getAssignments (Call) = getAssignments (Content(Call))
- getAssignments (P₁ bop P₂) = getAssignments (P₁) ∧ getAssignments (P₂), where bop is a binary operator (either an external choice, internal choice, interleaving, parallelism and etc)
- getAssignments ($P \setminus CS$) = getAssignments (P)
- getAssignments (P [RenamingPairs]) = getAssignments (P)
- getAssignments (ITOP Decl P) = getAssignments (IteratedExpansion (P, Decl, ITOP))
- getAssignments (P [N+]) = getAssignments (GenericContent (P, [N+]))

Definition B.2. ***pre** *is* an unary function that calculates the precondition of a given Z Schema. This calculation is performed by guaranteeing that there is a future state and by hiding the output variables of the schema (those that have a "!" after their names on the definition of the schema):

pre Schema = \exists State'. Schema \setminus Outputs

This definition lies on [9].

Definition B.3. *IteratedExpansion* is a function that unfolds an iterated operator applied to an action or to a process. It has three parameters: the first parameter is the process itself, the second is the declaration of the variables used to iterate the process (or the action), and the third is a flag indicating what is the operator applied to the iteration. The type of the iterating variables must be finite, or infinite with range previously specified. For Example:

IteratedExpansion (a.x \rightarrow Skip, x : {0, 1, 2, 3}, EXTCHOICE) = a.0 \rightarrow Skip \Box a.1 \rightarrow Skip \Box a.2 \rightarrow Skip \Box a.3 \rightarrow Skip

Definition B.4. *Body* is a function that unfolds the body of a call action. For Example:

process $P \cong$ begin $A \cong a \rightarrow Skip$ • Aend

Body $(A) = a \rightarrow Skip$.

Body can also be used for processes. For Example:

Body(P) =

begin $A \cong a \rightarrow Skip$ • Aend **Definition B.5.** *IndexedContent* works as **Body**, but is applied to processes with indexed parameters. **process** $P \cong$ **begin** • *request*? $x \rightarrow$ *response*! $x \rightarrow$ *Skip* **end process** $Q \cong x : \{0, 1\} \odot P$ *IndexedContent* $(Q, [0]) = Q \lfloor 0 \rfloor$ **= begin** • *request_0.0*? $x \rightarrow$ *response_0.0*! $0 \rightarrow$ *Skip* **end**

Definition B.6. *ParamContent* works as *Body*, but is applied to processes with normal parameters. For Example:

process $P \cong x : \mathbb{N}; y : \mathbb{N} \bullet$ **begin** • $a.x.y \to Skip$ end

ParamContent (P, [1, 2]) = begin • $a.1.2 \rightarrow Skip$ end

Definition B.7. *GenericContent* works as *Content*, but is applied to processes with generic parameters. GenericContent (*P*, [*N*+]) takes process *P* and a list of generic types [*N*+] as parameters. For Example:

channel [C] singleevent : C **process** $P[T] \cong$ begin • singleevent [T]?x \rightarrow Skip end **process** Inst \cong $P[\mathbb{N}]$

On the specification above,

GenericContent (P, [\mathbb{N}]) = **begin** • singleevent [\mathbb{N}]?x \rightarrow Skip end

Definition B.8. A = Body(A), provided that A is a call.

Definition B.8 says that any call action A equals its body. Given:

process $P \cong$ **begin** $A \cong a \rightarrow Skip$ • Aend

The call action A equals $a \rightarrow Skip$, which is Body (A) (def. B.4). Thus, A = Body (A).

Definition B.9. A(N+) = ParamContent (A, [N+]), provided that A is a parameterised call.

Definition B.9 says that any parameterised call action A equals its body having the parameters replaced by their call expressions. Given:

process $P \cong$ **begin** $A \cong x : \mathbb{N} \bullet a.x \to Skip$ $\bullet A(0)$ **end**

The call action A (0) equals $a.0 \rightarrow Skip$, which is ParamContent (A, [0]) (def. B.6). Thus, A (0) = ParamContent (A, [0]).

Definition B.10. $A \lfloor N+ \rfloor =$ IndexedContent (A, [N+]), provided that A is an indexed call. *Given:*

process $P \cong$ **begin** $A \cong x : \mathbb{N} \bullet a.x \to Skip$ $\bullet A \lfloor 0 \rfloor$ **end**

The indexed call action A $\lfloor 0 \rfloor$ equals a_0.0 \rightarrow Skip, which is IndexedContent (A, [0]) (def. B.5). Thus, A $\lfloor 0 \rfloor$ = IndexedContent (A, [0]).

Definition B.11. P[N+] = GenericContent (P, [N+]), provided that P is a call. Given the example on B.7,

 $P[\mathbb{N}] =$ begin • singleevent $[\mathbb{N}]?x \rightarrow Skip$ end,

which is GenericContent (P, [\mathbb{N}]). Thus, P [\mathbb{N}] equals GenericContent (P, [\mathbb{N}]).

Definition B.12. *Used*C* is a function that gets a Circus action as parameter and returns a set of channels that are used within that action. For Example: Used*C* ($\mu X \bullet (turnOn \rightarrow X) \sqcap (turnOff \rightarrow X)$) = {turnOn, turnOff}

This definition was created on [6].

Definition B.13. *initials is a function that gets a Circus action as parameter and returns a set of events that are initially offered by the action. For Example: initials (turnOn \rightarrow Skip) = {turnOn} initials (turnOn \rightarrow Skip \Box turnOff \rightarrow Skip) = {turnOn, turnOff}

This definition was created on [6].

Definition B.14. *Refinement Definition:

 $P \sqsubseteq Q = [Q \Rightarrow P] = \forall v : FREEV . Q \Rightarrow P$

On the expression above, the FREEV set represents the set of free (non-quantified) variables on the expression between brackets. The brackets mean universal quantification on the free-variables.

The definition above lies on [4, 6]

Definition B.15. **Reactive Skip* $II_{rea} = (\neg ok \land tr \le tr') \lor (ok' \land tr' = tr \land wait' = wait \land ref' = ref \land v' = v)$

This definition was quoted from [6].

Definition B.16. *State Assignment

A Configuration State assignment is defined on [3] as a total function that maps the programming variables in the alphabet to (possibly loose) constants. That leads us to the formula

 $(x := c) = (x' = c \land v' = v),$

where c is a (possibly loose) constant (the value of c is determined as an expression that appears on the constraint of the configuration). The v' = v factor (v is the set of all non-used variables by the assignment) comes from the fact that the function is total, and all the variables on the state space that were not used by the assignment (including the observational variables *ok*, *tr*, *wait* and *ref*) must have their values mapped to their current values. A consequence of this description is that another possible definition is

 $(x := c) = x' = c \land wait' = wait \land ok' = ok \land tr' = tr \land ref' = ref \land nalocalvars' = nalocalvars,$

Where nalocalvars is the set of all program (non-observational) variables (except x, because x lies on the assignment) of the state space. We can generalise the definition above for any assignment s using a **factor f** such that, for example, if

s = (x, y := 0, 1)

then $\mathbf{f} = \mathbf{f}(\alpha, \alpha') = (x' = 0 \land y' = 1)$.

So, for any Configuration State Assignment s,

 $s = s \ (\alpha, \alpha') = f \land wait' = wait \land ok' = ok \land tr' = tr \land ref' = ref \land nalocalvars' = nalocalvars.$

Definition B.17. *Reactive Design Assignment

 $v :=_{RD} e = Lift (v := e); Skip$

This definition was created on [3].

Definition B.18. *Conditional

 $P \lhd b \rhd Q = (b \land P) \lor (\neg b \land Q)$

This definition was quoted from document [8].

Definition B.19. *R1

 $R1(P) = P \wedge tr \leq tr'$

This definition lies on documents [3, 6].

Definition B.20. *R2

 $R2 (P (tr, tr')) = P (\langle \rangle, tr' - tr) = P [\langle \rangle, (tr' - tr) / tr, tr']$

This definition lies on document [6]..

Definition B.21. *R3

 $R3(P) = II_{rea} \lhd wait \triangleright P$

This definition lies on documents [3, 6]. The Conditional operator is defined on B.18 and H_{rea} (Reactive Skip) is defined on B.15.

Definition B.22. *R

 $R(P) = R1 \circ R2 \circ R3(P)$

This definition lies on document [6]..

Definition B.23. *Design

 $P \vdash Q = (P \land ok) \Rightarrow (Q \land ok')$

This definition lies on document [6, 8].

Definition B.24. *Lift

Lift (s) = R1 \circ R3 (true \vdash s \wedge tr' = tr $\wedge \neg$ wait')

This definition is original from the document [3]. All definitions, lemmas, theorems, laws and rules from CML can be used for *Circus* [5].

Definition B.25. *Silent Transition:

 $(c_1 \mid s_1 \models A_1) \xrightarrow{\tau} (c_2 \mid s_2 \models A_2)$ = $\forall w . c_1 \land c_2 \Rightarrow Lift(s_1); A_1 \sqsubseteq Lift(s_2); A_2$

This definition is original from the document [3]. All definitions, lemmas, theorems, laws and rules from CML can be used for *Circus* [5].

Definition B.26. *Labelled Transition: $(c_1 | s_1 \models A_1) \xrightarrow{l} (c_2 | s_2 \models A_2)$ = $\forall w. c_1 \land c_2 \Rightarrow Lift(s_1); A_1 \sqsubseteq (Lift(s_2); 1 \rightarrow A_2) \Box (Lift(s_1); A_1)$ This definition is original from the document [3]. All definitions, lemmas, theorems, laws and rules from CML can be used for Circus [5].

Definition B.27. Syntactic Transition (for processes):

$$(c_{1} \models P_{1}) \rightsquigarrow (c_{2} \models P_{2})$$

$$=$$

$$\forall w. c_{1} \land c_{2} \Rightarrow$$

$$\left((Lift(getAssignments(P_{1})); P_{1} \sqsubseteq Lift(getAssignments(P_{2})); P_{2}) \\ \land Lift(getAssignments(P_{1})) = Lift(getAssignments(P_{2})) \end{array} \right)$$

$$(c_{1} \models P_{1}) \rightsquigarrow (c_{2} \mid s \models BasicProc)$$

$$=$$

$$\forall w. c_{1} \land c_{2} \Rightarrow$$

$$\left(((Lift(getAssignments(P_{1})); P_{1} \sqsubseteq Lift(s); BasicProc)) \\ \land Lift(getAssignments(P_{1})) = Lift(s) \end{array} \right)$$

The definition of the getAssignments function is on B.1.

The definition of Syntactic Transition B.27 was created on this document.

Definitions B.25, B.26 and B.27 define advances on the program. These advances are refinements between *Circus* denotational expressions: when these refinement expressions are proved correct with respect to the theory of *Circus* on the Unifying Theories of Programming (UTP), it means that the advances of the program whose definitions are these refinement expressions are correct and satisfy the theory.

Definition B.28. **let* [3] *let* $x \bullet A = A$

This definition is original from the document [3]. All definitions, lemmas, theorems, laws and rules from CML can be used for *Circus* [5].

Definition B.29. *loc [3] loc $s \bullet P = Lift(s)$; P

This definition is original from the document [3]. All definitions, lemmas, theorems, laws and rules from CML can be used for *Circus* [5].

Definition B.30. *Extra Choice

 $A_1 \boxplus A_2 = A_1 \Box A_2$

This definition is original from the document [3]. All definitions, lemmas, theorems, laws and rules from CML can be used for *Circus* [5]. The Extra Choice symbol (\boxplus) appears on the rules of External Choice on the Operational Semantics of [3] as "[+]".

Definition B.31. Extra Statement

V : [Pre, Post] = V [:] [Pre, Post]

This definition was created on this thesis. The role of this definition is to represent the intermediate state between the initial state of the Specification Statement (the one in which the Program Text equals V : [Pre, Post]) and an intermediate state where precondition Pre is a factor on the constraint of the final state (the one in which the Program Text equals V [:] [Pre, Post]). This behaviour lies on Attached Rule 30.

Definition B.32. *doC

 $doC(l, C) = (tr' = tr \land (l, C) \notin ref' \lhd wait' \triangleright tr' = tr \land \langle (l, C) \rangle)$

Where

- 1 is a channel;
- *C* is a communication;
- $\langle (l, C) \rangle$ is a trace that is concatenated to tr;

This function is used on the Denotational definition of the prefixing operator.

The definition was created on [6].

Definition B.33. *A* ; *B* = $\exists v0 \cdot A [v, v0] \land B [v0, v']$

The above definition was made on [4] and is referenced on [6].

Definition B.34. *UTP Variable Declaration

(var x); $P = \exists x . P$ The definition was created on [8].

Definition B.35. *Substitution:

 $A_c^b = A [b / ok'][c / wait]$

The definition lies on [6]. It is referenced on the denotational definition of other constructs of *Circus*, like If-Guarded Command A.5. When Substitution is referenced, it has factors as A_f^f and A_f^t . On these cases, f means **false** and t means **true**.

Definition B.36. *Disjunction Reactive Designs:

 $R (P1 \vdash Q1) \lor R (P2 \vdash Q2) = R (P1 \land P2 \vdash P1 \lor P2)$

The definition lies on [7].

Definition B.37. *External Choice Denotational Definition:

 $A_1 \Box A_2 = R \left((\neg A_1_f^f \land \neg A_2_f^f) \vdash ((A_1_f^t \land A_2_f^t) \lhd tr' = tr \land wait' \rhd (A_1_f^t \lor A_2_f^t)) \right)$

The definition lies on [6].

Definition B.38. *CSP1:

 $CSP1 (P) = P \lor (\neg ok \land tr \le tr')$

The definition lies on [6].

Definition B.39. *CSP2:

CSP2(P) = P; $((ok \Rightarrow ok') \land tr' = tr \land wait' = wait \land ref' = ref \land v' = v)$

The definition lies on [6].

Definition B.40. *CSP3:

CSP3(P) = Skip; P

The definition lies on [6].

B.2.2 Auxiliary Lemmas

Lemma B.1. Refinement Healthiness Conditions $(II_{rea} \lhd wait \triangleright X) (\langle \rangle, tr' - tr)$ $\sqsubseteq (II_{rea} \lhd wait \rhd false) (\langle \rangle, tr' - tr)$ Proof *For wait = true* $((II_{rea})(\langle\rangle, tr' - tr))$ $\subseteq (II_{rea}) (\langle \rangle, tr' - tr))$ = [Refinement Equal Sides 1] true *For wait* = *false* $X(\langle\rangle, tr' - tr)$ \sqsubseteq (false) ($\langle \rangle$, tr' - tr) = [Predicate Calculus] $X(\langle\rangle, tr' - tr) \sqsubseteq false$ = [Refinement Definition **B.14** and Predicate Calculus] true

Lemma B.2. Refinement Healthiness Conditions with R1

$$R(X) \sqsubseteq R(false)$$

Proof:

$$R(X) \sqsubseteq R(false)$$

= [Definitions of R1 B.19, R2 B.20 and R3 B.21]
 $(tr \le tr' \land (II_{rea} \lhd wait \rhd X)(\langle \rangle, tr' - tr))$

 $\sqsubseteq (tr \le tr' \land (II_{rea} \lhd wait \triangleright false)(\langle \rangle, tr' - tr))$ = [Refinement Healthiness Conditions B.1 and Refinement Monotonic 6] true

Lemma B.3. *Expanded Reactive Design Refined by Reactive Ok Negation* $(R((\neg Ap \land ok) \Rightarrow (Ap \land ok')) \sqsubseteq R(\neg ok))$

Proof:

For ok = true:

 $(R((\neg Ap \land true) \Rightarrow (Ap \land ok')) \sqsubseteq R(\neg true))$ [Predicate Calculus] (R((\ Ap \land true) \Rightarrow (Ap \land ok')) \sqsubseteq R(false)) [Refinement Healthiness Condition with R1 B.2] true

For ok = false:

 $(R((\neg Ap \land false) \Rightarrow (Ap \land ok')) \sqsubseteq R(\neg false))$ = [Predicate Calculus] $(R(false \Rightarrow (Ap \land ok')) \sqsubseteq R(true))$ = [Predicate Calculus] $(R(true) \sqsubseteq R(true))$ = [Refinement Equal Sides 1] true

Lemma B.4. *Refinement Implication For Substitution Equivalence* $(A \sqsubseteq A \Box B) \Rightarrow (A \sqsubseteq B),$

provided that $A_f^f = A_f^t$ and $B_f^f = B_f^t$

Proof:

$$Be Ap = Ap_{f}^{f} = Ap_{f}^{t}, and Bp = Bp_{f}^{f} = Bp_{f}^{t}$$

 $(A \sqsubseteq A \Box B) \Rightarrow (A \sqsubseteq B)$ = [External Choice Denotational Definition B.37 + Assumption] $(R(\neg Ap \vdash Ap) \sqsubseteq R((\neg Ap \land \neg Bp) \vdash ((Ap \land Bp) \lhd tr' = tr \land wait' \rhd (Ap \lor Bp)))))$ \Rightarrow $(R(\neg Ap \vdash Ap) \sqsubseteq R(\neg Bp \vdash Bp))$

$$For Bp = true:$$

 $(R(\neg Ap \vdash Ap) \sqsubseteq R((\neg Ap \land \neg true) \vdash ((Ap \land true) \lhd tr' = tr \land wait' \rhd (Ap \lor true))))$ \Rightarrow $(R(\neg Ap \vdash Ap) \sqsubseteq R(\neg true \vdash true))$ = [Predicate Calculus] $(R(\neg Ap \vdash Ap) \sqsubseteq R(false \vdash (Ap \lhd tr' = tr \land wait' \rhd true)))$ \Rightarrow $(R(\neg Ap \vdash Ap) \sqsubseteq R(false \vdash true))$ = [Predicate Calculus] $(R(\neg Ap \vdash Ap) \sqsubseteq R(false \vdash (Ap \lhd tr' = tr \land wait' \rhd true)))$ \Rightarrow $(R(\neg Ap \vdash Ap) \sqsubseteq R(false))$ = [Refinement Healthiness Condition with R1 B.2] $(R(\neg Ap \vdash Ap) \sqsubset R(false \vdash (Ap \lhd tr' = tr \land wait' \rhd true)))$ \Rightarrow true = [Predicate Calculus] true

For Bp = false:

$$(R(\neg Ap \vdash Ap) \sqsubseteq R((\neg Ap \land \neg false) \vdash ((Ap \land false) \lhd tr' = tr \land wait' \rhd (Ap \lor false)))))$$

$$\Rightarrow$$

$$(R(\neg Ap \vdash Ap) \sqsubseteq R(\neg false \vdash false))$$

$$= [Predicate Calculus]$$

$$(R(\neg Ap \vdash Ap) \sqsubseteq R((\neg Ap \land \neg false) \vdash ((Ap \land false) \lhd tr' = tr \land wait' \rhd (Ap \lor false)))))$$

$$\Rightarrow$$

$$(R(\neg Ap \vdash Ap) \sqsubseteq R(\neg false \vdash false))$$

= [Predicate Calculus] $(R(\neg Ap \vdash Ap) \sqsubset R((\neg Ap \land true) \vdash ((Ap \land false) \lhd tr' = tr \land wait' \triangleright (Ap \lor false)))$ \Rightarrow $(R(\neg Ap \vdash Ap) \sqsubseteq R(true \vdash false))$ = [Predicate Calculus] $(R(\neg Ap \vdash Ap) \sqsubseteq R(\neg Ap \vdash (false \lhd tr' = tr \land wait' \rhd Ap)))$ \Rightarrow $(R(\neg Ap \vdash Ap) \sqsubset R(true \vdash false))$ = [Definition of Conditional **B.18** + Predicate Calculus] $(R(\neg Ap \vdash Ap) \sqsubset R(\neg Ap \vdash (\neg (tr' = tr \land wait') \land Ap)))$ \Rightarrow $(R(\neg Ap \vdash Ap) \sqsubseteq R(true \vdash false))$ = [Design Definition **B.23**] $(R(\neg Ap \vdash Ap) \sqsubseteq R(\neg Ap \vdash (\neg (tr' = tr \land wait') \land Ap)))$ \Rightarrow $(R((\neg Ap \land ok) \Rightarrow (Ap \land ok')) \sqsubseteq R(\neg ok))$ = [Expanded Reactive Design Refined by Reactive Ok Negation **B.3**] $(R(\neg Ap \vdash Ap) \sqsubset R(\neg Ap \vdash (\neg (tr' = tr \land wait') \land Ap)))$ \Rightarrow true = [Predicate Calculus] true

Lemma B.5. *Lift Substitution Equivalence* $(Lift(s))_{f}^{f} = (Lift(s))_{f}^{t}$

Proof:

 $\begin{aligned} (Lift(s))_{f}^{f} \\ &= [Definition \ of \ Lift \ B.24] \\ (R1 \circ R3(true \vdash s \land tr' = tr \land \neg wait'))_{f}^{f} \\ &= [Definitions \ of \ R1 \ B.19 \ and \ R3 \ B.21] \\ (tr \leq tr' \land (II_{rea} \lhd wait \triangleright (true \vdash s \land tr' = tr \land \neg wait')))_{f}^{f} \\ &= [Substitution \ B.35] \\ tr \leq tr' \land (II_{rea}_{f} \lhd false \triangleright (true \vdash s \land tr' = tr \land \neg wait')) \\ &= [Definition \ of \ Conditional \ B.18 \ and \ Predicate \ Calculus] \\ tr \leq tr' \land (true \vdash s \land tr' = tr \land \neg wait') \end{aligned}$

= [Definition of Conditional B.18 and Predicate Calculus] $tr \leq tr' \land (II_{rea} {}^{t}_{f} \lhd false \triangleright (true \vdash s \land tr' = tr \land \neg wait'))$ = [Substitution B.35] $tr \leq tr' \land (II_{rea} \lhd wait \triangleright (true \vdash s \land tr' = tr \land \neg wait')) {}^{t}_{f}$ = [Definitions of R1 B.19 and R3 B.21] $(R1 \circ R3(true \vdash s \land tr' = tr \land \neg wait')) {}^{t}_{f}$ = [Definition of Lift B.24] $(Lift(s)) {}^{t}_{f}$

Lemma B.6. *Healthy True Refinement:* $\forall x . R(true) \sqsubseteq R(x)$

Proof $\forall x . R (true) \sqsubseteq R(x)$ = [Quantifier $\forall x \text{ can be omitted}]$ $R (true) \sqsubseteq R(x)$

For x = true: $(R (true) \sqsubseteq R(true))$ = [Refinement Equal Sides 1] true

 $\underline{For \ x = false:} \\
 (R (true) \sqsubseteq R(false)) \\
 = [Definitions of R1 B.19, R2 B.20 and R3 B.21] \\
 tr \leq tr' \land (II_{rea} \lhd wait \rhd true) (\langle \rangle, tr' - tr) \\
 \sqsubseteq tr \leq tr' \land (II_{rea} \lhd wait \rhd false) (\langle \rangle, tr' - tr) \\
 = [Ref. Conjunctive Monotonic B.13 and Ref. Healthiness Conditions B.1] \\
 true$

Lemma B.7. *Design of Assignment R2:* (*true* $\vdash x' = w_0 \land v' = v \land tr' = tr \land \neg wait')$ *is R2*

Proof

true $\vdash x' = w_0 \land v' = v \land tr' = tr \land \neg$ wait' = [Expression does not contain tr' neither tr] true $\vdash x' = w_0 \land v' = v \land tr' = tr \land \neg$ wait' [$\langle \rangle$, tr' - tr / tr, tr'] = [Predicate Calculus] true $\vdash x' = w_0 \land v' = v \land tr' = tr \land \neg wait' (\langle \rangle, tr' - tr)$ = [Definition of R2 B.20] R2 (true $\vdash x' = w_0 \land v' = v \land tr' = tr \land \neg wait')$

Lemma B.8. (*Lift* (*var* x ; $x := w_0$) ; A) \Rightarrow (*var* $x : T \bullet A$),

provided that

• $w_0 : T$

Proof

(Lift (var $x ; x := w_0$); A) = [Lift CSP4 **B.2.26**] (Lift (var $x ; x := w_0$); Skip; A) = [Definition of Lift **B.24**] $(R1 \circ R3 (true \vdash var x; x := w_0 \land tr' = tr \land \neg wait'); Skip; A)$ = [Design of Assignment R2 B.7] $(R1 \circ R3 \circ R2 (true \vdash var x; x := w_0 \land tr' = tr \land \neg wait'); Skip; A)$ = [R2 and R3 Composition Commutative B.2.49] $(R1 \circ R2 \circ R3 (true \vdash var x; x := w_0 \land tr' = tr \land \neg wait'); Skip; A)$ = [Definition of R **B**.22] $(R (true \vdash var x; x := w_0 \land tr' = tr \land \neg wait'); Skip; A)$ = [State Assignment **B.16**] (R (true \vdash var x; x' = w₀ \land v' = v \land tr' = tr $\land \neg$ wait'); Skip; A) = [UTP Variable Declaration **B.34**] (R (true $\vdash \exists x . x' = w_0 \land v' = v \land tr' = tr \land \neg wait'$); Skip; A) $= [Assumption w_0: T]$ (R (true $\vdash \exists x . x' = w_0 \land w_0 : T \land v' = v \land tr' = tr \land \neg wait'$); Skip; A) = [Predicate Calculus: $x' = w_0 \land w_0 : T \Rightarrow x : T$] $(R (true \vdash \exists x . x' = w_0 \land w_0 : T \land x : T \land v' = v \land tr' = tr \land \neg wait'); Skip; A)$ \Rightarrow [Predicate Calculus: $x' = w_0 \land w_0 : T \land x : T \Rightarrow \exists x, x' : T$] $(R (true \vdash \exists x, x' : T . x' = w_0 \land w_0 : T \land x : T \land v' = v \land tr' = tr \land \neg wait'); Skip; A)$ = [Predicate Calculus: x, x' and w_0 do not occur on R] $\exists x, x' \cdot x' = w_0 \land w_0 : T \land x : T \land (R (true \vdash v' = v \land tr' = tr \land \neg wait'); Skip; A)$ \Rightarrow [Predicate Calculus: removing $x' = w_0$, $w_0 : T$ and x : T weakens the expression] $\exists x, x': T. (R (true \vdash v' = v \land tr' = tr \land \neg wait'); Skip; A)$ = [Skip denotational definition A.3]

 $\exists x, x' : T. (Skip ; Skip ; A)$ = [Theorem B.2.2 twice] $\exists x, x' : T. A$ = [Variable Block Denotational Definition A.1]
(var $x : T \bullet A$)

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Lemma B.9.

 $(c_1 \models P_1 \ OP \ P_2) \rightsquigarrow (c_2 \models P_3 \ OP \ P_2) = c_1 \land c_2 \Rightarrow$ $(Lift (gA (P_1)) \land Lift (gA (P_2)); P_1 \ OP \ P_2$ $\sqsubseteq (Lift (gA (P_1)) \land Lift (gA (P_2)); P_3 \ OP \ P_2))$

provided that

Lift $(gA(P_1)) = Lift (gA(P_3))$ **Proof:** To reduce verbose, we create the abbreviation gA(s) such that gA(s) = getAssignments(s)

LHS

= $(c_{1} \models P_{1} \ OP \ P_{2}) \rightsquigarrow (c_{2} \models P_{3} \ OP \ P_{2})$ = [Definition of Syntactic Transition B.27] $\forall w. c_{1} \land c_{2} \Rightarrow$ $\begin{pmatrix} ((Lift (gA (P_{1} \ OP \ P_{2})); \ P_{1} \ OP \ P_{2} \sqsubseteq Lift (gA (P_{3} \ OP \ P_{2})); \ P_{3} \ OP \ P_{2})) \\ \land Lift (gA (P_{1} \ OP \ P_{2})) = Lift (gA (P_{3} \ OP \ P_{2})) \\ = [w \text{ is universally quantified, so we abstract it]}$

 $c_{1} \wedge c_{2} \Rightarrow$ $\begin{pmatrix} (Lift (gA (P_{1} OP P_{2})); P_{1} OP P_{2} \sqsubseteq Lift (gA (P_{3} OP P_{2})); P_{3} OP P_{2})) \\ \wedge Lift (gA (P_{1} OP P_{2})) = Lift (gA (P_{3} OP P_{2})) \end{pmatrix}$ = [Definition of getAssignments B.1 (4x) for binary Operator OP] $c_{1} \wedge c_{2} \Rightarrow$ $\begin{pmatrix} (Lift (gA (P_{1}) \wedge gA (P_{2})); P_{1} OP P_{2} \sqsubseteq Lift (gA (P_{3}) \wedge gA (P_{2})); P_{3} OP P_{2})) \\ \wedge Lift (gA (P_{1}) \wedge gA (P_{2})) = Lift (gA (P_{3}) \wedge gA (P_{2})) \end{pmatrix}$

```
= [Lift And B.2.48]
c_1 \wedge c_2 \Rightarrow
      ((Lift(gA(P_1) \land gA(P_2)); P_1 OP P_2 \sqsubseteq Lift(gA(P_3) \land gA(P_2)); P_3 OP P_2))
      \wedge \textit{Lift}(\textit{gA}(P_1)) \wedge \textit{Lift}(\textit{gA}(P_2)) = \textit{Lift}(\textit{gA}(P_3)) \wedge \textit{Lift}(\textit{gA}(P_2))
= [Assumption]
c_1 \wedge c_2 \Rightarrow
      ((Lift(gA(P_1) \land gA(P_2)); P_1 OP P_2 \sqsubseteq Lift(gA(P_3) \land gA(P_2)); P_3 OP P_2))
      \wedge Lift(gA(P_3)) \wedge Lift(gA(P_2)) = Lift(gA(P_3)) \wedge Lift(gA(P_2))
= [Predicate Calculus: (P = P) = true]
c_1 \wedge c_2 \Rightarrow
      ((Lift(gA(P_1) \land gA(P_2)); P_1 OP P_2 \sqsubseteq Lift(gA(P_3) \land gA(P_2)); P_3 OP P_2))
      \wedge true
= [Predicate Calculus]
c_1 \wedge c_2 \Rightarrow
      ((Lift(gA(P_1) \land gA(P_2)); P_1 OP P_2 \sqsubseteq Lift(gA(P_3) \land gA(P_2)); P_3 OP P_2))
= [Lift And B.2.48]
c_1 \wedge c_2 \Rightarrow
(Lift(gA(P_1)) \land Lift(gA(P_2)); P_1 OP P_2 \sqsubseteq (Lift(gA(P_3)) \land Lift(gA(P_2)); P_3 OP P_2))
= [Assumption]
c_1 \wedge c_2 \Rightarrow
(Lift(gA(P_1)) \land Lift(gA(P_2)); P_1 OP P_2 \sqsubseteq (Lift(gA(P_1)) \land Lift(gA(P_2)); P_3 OP P_2))
=
RHS
```

Lemma B.10.
$$(c_1 \models P_1 \ OP \ P_2) \rightsquigarrow (c_2 \models P_1 \ OP \ P_3) = c_1 \land c_2 \Rightarrow$$

 $\begin{pmatrix} (Lift(gA(P_1)) \land Lift(gA(P_2)); \ P_1 \ OP \ P_2 \sqsubseteq (Lift(gA(P_1)) \land Lift(gA(P_2)); \ P_1 \ OP \ P_3)) \end{pmatrix}$

provided that Lift $(gA(P_2)) = Lift (gA(P_3))$

Proof:

To reduce verbose, we create the abbreviation gA(s) such that gA(s) = getAssignments(s)

LHS

_ $(c_1 \models P_1 \ OP \ P_2) \rightsquigarrow (c_2 \models P_1 \ OP \ P_3)$ = [Definition of Syntactic Transition **B.27**] $\forall w.c_1 \land c_2 \Rightarrow$ $((Lift(gA(P_1 OP P_2)); P_1 OP P_2 \sqsubseteq Lift(gA(P_1 OP P_3)); P_1 OP P_3))$ $\wedge Lift(gA(P_1 OP P_2)) = Lift(gA(P_1 OP P_3))$ = [w is universally quantified, so we abstract it] $c_1 \wedge c_2 \Rightarrow$ $((Lift(gA(P_1 OP P_2)); P_1 OP P_2 \sqsubseteq Lift(gA(P_1 OP P_3)); P_1 OP P_3))$ $\wedge Lift(gA(P_1 OP P_2)) = Lift(gA(P_1 OP P_3))$ = [Definition of getAssignments **B.1**] $c_1 \wedge c_2 \Rightarrow$ $((Lift(gA(P_1) \land gA(P_2)); P_1 OP P_2 \sqsubseteq Lift(gA(P_1) \land gA(P_3)); P_1 OP P_3))$ $\wedge Lift(gA(P_1) \wedge gA(P_2)) = Lift(gA(P_1) \wedge gA(P_3))$ = [Lift And **B.2.48**] $c_1 \wedge c_2 \Rightarrow$ $((Lift(gA(P_1) \land gA(P_2)); P_1 OP P_2 \sqsubseteq Lift(gA(P_1) \land gA(P_3)); P_1 OP P_3))$ \wedge Lift $(gA(P_1)) \wedge$ Lift $(gA(P_2)) =$ Lift $(gA(P_1)) \wedge$ Lift $(gA(P_3))$ = [Assumption] $c_1 \wedge c_2 \Rightarrow$ $((Lift(gA(P_1) \land gA(P_2)); P_1 OP P_2 \sqsubseteq Lift(gA(P_1) \land gA(P_3)); P_1 OP P_3))$ $\wedge Lift(gA(P_1)) \wedge Lift(gA(P_3)) = Lift(gA(P_1)) \wedge Lift(gA(P_3))$ = [Predicate Calculus: (P = P) = true] $c_1 \wedge c_2 \Rightarrow$ $((Lift(gA(P_1) \land gA(P_2)); P_1 OP P_2 \sqsubseteq Lift(gA(P_1) \land gA(P_3)); P_1 OP P_3)$ \wedge true = [Predicate Calculus: $(P \land true) = P$] $c_1 \wedge c_2 \Rightarrow$ $((Lift(gA(P_1) \land gA(P_2)); P_1 OP P_2 \sqsubseteq Lift(gA(P_1) \land gA(P_3)); P_1 OP P_3))$ = [Lift And **B.2.48**] $c_1 \wedge c_2 \Rightarrow$ $(Lift(gA(P_1)) \land Lift(gA(P_2)); P_1 OP P_2 \sqsubseteq (Lift(gA(P_1)) \land Lift(gA(P_3)); P_1 OP P_2))$ = [Assumption] $c_1 \wedge c_2 \Rightarrow$

$$\begin{pmatrix} (Lift(gA(P_1)) \land Lift(gA(P_2)); P_1 OP P_2 \sqsubseteq (Lift(gA(P_1)) \land Lift(gA(P_2)); P_1 OP P_3)) \end{pmatrix} \\ = & RHS \end{pmatrix}$$

Lemma B.11. $true \sqsubseteq X$ **Proof** $true \sqsubseteq X$ $= [X \Rightarrow true]$ = [true] = true \Box

Lemma B.12. if $(pred_1) \rightarrow A_1 \parallel \dots \parallel (pred_n) \rightarrow A_n$ fi $\sqsubseteq A1$

provided that

• $pred_1$

Proof:

```
if (pred_1) \rightarrow A_1 \parallel \dots \parallel (pred_n) \rightarrow A_n fi \sqsubseteq A1
= [If-Guarded Command Denotational Definition A.5]
R (
(pred_1 \lor ... \lor pred_n)
\wedge (pred_1 \Rightarrow \neg A_1{}_f^f \land ... \land pred_n \Rightarrow \neg A_n{}_f^f) \vdash ((pred_1 \land A_1{}_f^t) \lor ... \lor (pred_n \land A_n{}_f^t)
)) \sqsubseteq A1
= [Assumption pred_1]
(R (
(true \lor ... \lor pred_n)
\wedge (true \Rightarrow \neg A_1_f^f \land ... \land pred_n \Rightarrow \neg A_n_f^f) \vdash ((true \land A_1_f^t) \lor ... \lor (pred_n \land A_n_f^t))
))) \sqsubseteq A1
= [Predicate Calculus]
(R (
true
\wedge (true \Rightarrow \neg A_1_f^f \land ... \land pred_n \Rightarrow \neg A_n_f^f) \vdash ((true \land A_1_f^t) \lor ... \lor (pred_n \land A_n_f^t))
))) \Box A1
= [Predicate Calculus]
```

$$\left[R \left((true \Rightarrow \neg A_{1} \frac{f}{f} \land ... \land pred_{n} \Rightarrow \neg A_{n} \frac{f}{f} \right) \vdash \left((true \land A_{1} \frac{f}{f}) \lor ... \lor (pred_{n} \land A_{n} \frac{f}{f}) \right) \\ \implies I = \left[Predicate Calculus \right] \\ \left(R \left(\neg A_{1} \frac{f}{f} \land ... \land pred_{n} \Rightarrow \neg A_{n} \frac{f}{f} \right) \vdash \left(A_{1} \frac{f}{f} \lor ... \lor (pred_{n} \land A_{n} \frac{f}{f}) \right) \\ \implies I = \left[Disjunction Reactive Designs B.36 \right] \\ \left(R \left(\neg A_{1} \frac{f}{f} \vdash A_{1} \frac{f}{f} \right) \lor R \left(\neg (pred_{2} \Rightarrow A_{2} \frac{f}{f}) \vdash (pred_{2} \land A_{2} \frac{f}{f}) \right) \\ (pred_{2} \land A_{2} \frac{f}{f}) \\ (pred_{2} \land A_{2} \frac{f}{f}) \\ (pred_{2} \land A_{2} \frac{f}{f}) \\ \vdash (pred_{2} \land A_{2} \frac{f}{f}) \\ (pred_{n} \land A_{n} \frac{f}{f}) \\ (R \left(\neg (pred_{n} \Rightarrow A_{n} \frac{f}{f}) \vdash (pred_{2} \land A_{2} \frac{f}{f}) \vdash (pred_{2} \land A_{2} \frac{f}{f}) \\ (vR \left(\neg (pred_{n} \Rightarrow A_{n} \frac{f}{f}) \vdash (pred_{n} \land A_{n} \frac{f}{f}) \\ (vR \left(\neg (pred_{n} \Rightarrow A_{n} \frac{f}{f}) \vdash (pred_{n} \land A_{n} \frac{f}{f}) \\ (vR \left(\neg (pred_{n} \Rightarrow A_{n} \frac{f}{f}) \vdash (pred_{n} \land A_{n} \frac{f}{f}) \\ (VR \left(\neg (pred_{n} \Rightarrow A_{n} \frac{f}{f}) \vdash (pred_{n} \land A_{n} \frac{f}{f}) \\ (VR \left(\neg (pred_{n} \Rightarrow A_{n} \frac{f}{f}) \vdash (pred_{n} \land A_{n} \frac{f}{f}) \\ (VR \left(\neg (pred_{n} \Rightarrow A_{n} \frac{f}{f}) \vdash (pred_{n} \land A_{n} \frac{f}{f}) \\ (R \left(\neg (pred_{n} \Rightarrow A_{n} \frac{f}{f}) \vdash (pred_{n} \land A_{n} \frac{f}{f}) \\ (R \left(\neg (pred_{n} \Rightarrow A_{n} \frac{f}{f}) \vdash (pred_{n} \land A_{n} \frac{f}{f}) \\ (R \left(\neg (pred_{n} \Rightarrow A_{n} \frac{f}{f}) \vdash (pred_{n} \land A_{n} \frac{f}{f}) \\ (R \left(\neg (pred_{n} \Rightarrow A_{n} \frac{f}{f}) \vdash (pred_{n} \land A_{n} \frac{f}{f}) \\ (R \left(\neg (pred_{n} \Rightarrow A_{n} \frac{f}{f}) \vdash (pred_{n} \land A_{n} \frac{f}{f}) \\ (R \left(\neg (pred_{n} \Rightarrow A_{n} \frac{f}{f}) \vdash (pred_{n} \land A_{n} \frac{f}{f}) \\ (R \left(\neg (pred_{n} \Rightarrow A_{n} \frac{f}{f}) \vdash (pred_{n} \land A_{n} \frac{f}{f}) \\ (R \left(\neg (pred_{n} \Rightarrow A_{n} \frac{f}{f}) \vdash (pred_{n} \land A_{n} \frac{f}{f}) \\ (R \left(\neg (pred_{n} \Rightarrow A_{n} \frac{f}{f}) \vdash (pred_{n} \land A_{n} \frac{f}{f}) \\ = \left[Predicate Calculus \right] \\ \begin{bmatrix} rue \lor \\ (R \left(\neg (pred_{n} \Rightarrow A_{n} \frac{f}{f}) \vdash (pred_{n} \land A_{n} \frac{f}{f}) \\ (R \left(\neg (pred_{n} \Rightarrow A_{n} \frac{f}{f}) \vdash (pred_{n} \land A_{n} \frac{f}{f}) \\ (R \left(\neg (pred_{n} \Rightarrow A_{n} \frac{f}{f}) \vdash (pred_{n} \land A_{n} \frac{f}{f}) \\ (R \left(\neg (pred_{n} \Rightarrow A_{n} \frac{f}{f}) \vdash (pred_{n} \land A_{n} \frac{f}{f}) \\ (R \left(\neg (pred_{n} \Rightarrow A_{n} \frac{f}{f}) \vdash (pred_{n} \land$$

true

Lemma B.13. *Refinement Conjunctive Monotonic* $(P \land F \sqsubseteq Q \land F)$

provided that ($P \sqsubseteq Q$)

Proof: <u>For F = true</u>: $(P \land true \sqsubseteq Q \land true)$ = [**Predicate Calculus**] $(P \sqsubseteq Q)$ = [**Assumption**] true</u>

For F = false: $(P \land false \sqsubseteq Q \land false)$ = [Predicate Calculus] $(false \sqsubseteq false)$ = [Refinement Definition B.14] $[(false \Rightarrow false)]$ = [Predicate Calculus]true

Lemma B.14. Design Trace R2 (true $\vdash s \land tr' = tr0 \land \neg wait'$) is R2 Proof: (true $\vdash s \land tr' = tr0 \land \neg wait'$) = [Sequence Property] (true $\vdash s \land tr' - tr0 = \langle \rangle \land \neg wait'$) = [Definition of R2 B.20] R2 (true $\vdash s \land tr' = tr0 \land \neg wait'$)

Lemma B.15. **Existential Quantifier Shifted Inside R:* $\exists x . R(P) = R(\exists x . P),$

provided that x is neither tr nor wait

This theorem lies on [7].

Lemma B.16. Existential Quantifier Distributed Throughout Design:

 $\exists x . (true \vdash Post) = (true \vdash (\exists x . Post)),$

provided that x is neither ok or ok'.

Proof:

```
\exists x . (true \vdash Post)
[Definition of Design B.23]
\exists x. ((true \land ok) \Rightarrow (Post \land ok'))
[Predicate Calculus]
\exists x . (ok \Rightarrow (Post \land ok'))
[Predicate Calculus]
\exists x . (\neg ok \lor (Post \land ok'))
[Predicate Calculus]
(\exists x. \neg ok) \lor (\exists x. Post \land ok')
[Predicate Calculus]
(\exists x . \neg (true \land ok)) \lor (\exists x . Post \land ok')
[Predicate Calculus]
(\neg \forall x. (true \land ok)) \lor (\exists x. Post \land ok')
[Predicate Calculus]
(\forall x. (true \land ok)) \Rightarrow (\exists x. Post \land ok')
[Predicate Calculus]
(\forall x. (true \land ok)) \Rightarrow (\exists x. Post \land ok')
[Predicate Calculus]
((true \land \forall x . ok)) \Rightarrow (\exists x . Post \land ok')
[Assumption]
((true \land ok)) \Rightarrow (\exists x . Post \land ok')
[Assumption]
((true \land ok)) \Rightarrow ((\exists x . Post) \land ok')
[Definition of Design B.23]
true \vdash (\exists x . Post)
```

Lemma B.17. *Labelled Transition Implication* $(c_1 \mid s_1 \models A_1) \xrightarrow{d^*w_1} (c_3 \mid s_3 \models A_3)$ = \forall w. (*Lift* (s₁); A₁) $\sqsubseteq \forall$ w. (*Lift* (s₃); d^{*}w₁ \rightarrow A₃)

Proof:

 $(c_{1} | s_{1} \models A_{1}) \xrightarrow{d^{*}w_{1}} (c_{3} | s_{3} \models A_{3})$ = [Definition of Labelled Transition B.26] $\forall w. c_{1} \land c_{3} \Rightarrow (Lift (s_{1}); A_{1}) \sqsubseteq (Lift (s_{3}); d^{*}w_{1} \rightarrow A_{3}) \Box (Lift (s_{1}); A_{1})$ = [External Choice Refinement Implication 15] $\forall w. c_{1} \land c_{3} \Rightarrow (Lift (s_{1}); A_{1}) \sqsubseteq (Lift (s_{3}); d^{*}w_{1} \rightarrow A_{3})$

B.2.3 Auxiliary Theorems

Theorem 1. *Refinement Equal Sides:* $A \sqsubseteq A$

Proof

```
A \sqsubseteq A
= [Definition of Refinement]
[A \Rightarrow A]
= [Predicate Calculus]
[\neg A \lor A]
= [Predicate Calculus]
[true]
= [Predicate Calculus]
true
```

Theorem 2.

Silent Transition between equivalent nodes: $(c \mid s \models A) \xrightarrow{\tau} (c \mid s \models A)$

Proof

 $(c | s \models A) \xrightarrow{\tau} (c | s \models A)$ = [Definition of Silent Transition, B.25] $\forall w . c \land c \Rightarrow ((Lift (s) ; A \sqsubseteq Lift (s) ; A))$ = [Refinement Equal Sides 1] $\forall w. c \land c \Rightarrow true$
```
= [(P ⇒ true) = true]
∀ w. true
=
true
```

Theorem 3.

```
Sigma Equal:
(c \models P) \rightsquigarrow (c \models P)
```

```
Proof (c \models P) \rightsquigarrow (c \models P)

= [Definition of Sigma Transition]

\forall w.c \land c \Rightarrow

\begin{pmatrix} (Lift(getAssignments(P)); P \sqsubseteq Lift(getAssignments(P)); P) \\ \land Lift(getAssignments(P)) = Lift(getAssignments(P)) \end{pmatrix}

= [Refinement Equal Sides (2x) 1]

\forall w. c \land c \Rightarrow (true \land true)

= [Predicate Calculus]

\forall w. c \land c \Rightarrow true

= [Predicate Calculus]
```

true

Theorem 4. Sigma Equal Basic Process: $(c \models P) \rightsquigarrow (c \mid s \models B)$

provided that P = B

Proof

 $(c \models P) \rightsquigarrow (c \mid s \models B)$ = [Definition of Syntactic Transition B.27] $\forall w.c \land c \Rightarrow$ $\begin{pmatrix} (Lift(getAssignments(P)); P \sqsubseteq Lift(s); B) \\ \land Lift(getAssignments(P)) = Lift(s) \end{pmatrix}$ = [Assumption P = B] $\forall w.c \land c \Rightarrow$ $\begin{pmatrix} (Lift(getAssignments(B)); B \sqsubseteq Lift(s); B) \\ \land Lift(getAssignments(B)) = Lift(s) \end{pmatrix}$ = [Definition of getAssignments B.1]

```
\forall w.c \land c \Rightarrow 
 \begin{pmatrix} (Lift(s); B \sqsubseteq Lift(s); B) \\ \land Lift(s) = Lift(s) \end{pmatrix} 
= [Predicate Calculus] 
 \forall w.c \land c \Rightarrow 
 \begin{pmatrix} (Lift(s); B \sqsubseteq Lift(s); B) \\ \land true \end{pmatrix} \\ = [Refinement Equal Sides 1] 
 \forall w.c \land c \Rightarrow 
 \begin{pmatrix} true \\ \land true \end{pmatrix} \\ = [Predicate Calculus] true
```

Theorem 5.

*S Sequence False: s ; false = false

This theorem is quoted on [4].

Theorem 6.

**Monotonicity of Action Refinement:* A_1 ; $A_2 \sqsubseteq B_1$; B_2 provided $A_1 \sqsubseteq B_1$ and $A_2 \sqsubseteq B_2$

Proof The proof lies on the document [7]. □

Theorem 7. Lift Shift: $l \rightarrow Lift(s); A = Lift(s); l \rightarrow A$

provided that

• ok = ok'

Where FV (l) are the free variables of l, and LHS (s) returns the left variables of the sequence s of assignments. We use Theorem 11 to assume that all Lifted assignments (e.g. Lift (s)) are Circus actions.

Proof

$l \rightarrow Lift\left(s\right); A$

= [Prefixing Sequence B.2.5, having, from theorem 11, that Lift (s) is a *Circus* action] 1 → Skip ; Lift (s) ; A

= [Definition of Lift (B.24)]

 $l \rightarrow Skip$; (R1 \circ R3 (true \vdash s \wedge tr' = tr $\wedge \neg$ wait')); A

= [Sequence Denotational Definition **B.33** and Prefixing Denotational Definition **A.2** (where v0 is a set that contains all observational variables in an intermediate state (ok0, wait0, ref0, tr0 and so on))]

$$\exists v 0. \begin{pmatrix} R(true \vdash doC(l, C) \land vars0 = vars) \\ \land (R1 \circ R3(true \vdash s(\alpha 0, \alpha') \land tr' = tr0 \land \neg wait')) \end{pmatrix}; A$$
= [Definition of doC B.32]
$$\exists v 0. \begin{pmatrix} R \begin{pmatrix} true \vdash \begin{pmatrix} tr0 = tr \land (l, C) \notin ref0 \\ \lhd wait0 \rhd \\ tr0 = tr \land ((l, C)) \end{pmatrix} \land vars0 = vars \\ tr0 = tr \land ((l, C)) \end{pmatrix} \land vars0 = vars \end{pmatrix} \end{pmatrix}; A$$
= [Design Trace R2 B.14]
$$\exists v 0. \begin{pmatrix} R \begin{pmatrix} true \vdash \begin{pmatrix} tr0 = tr \land (l, C) \notin ref0 \\ \lhd wait0 \rhd \\ tr0 = tr \land ((l, C)) \end{pmatrix} \land vars0 = vars \\ tr0 = tr \land ((l, C)) \end{pmatrix} \land vars0 = vars \end{pmatrix} \end{pmatrix}; A$$
= [State Assignment B.16]
$$\exists v 0. \begin{pmatrix} R \begin{pmatrix} true \vdash \begin{pmatrix} tr0 = tr \land (l, C) \notin ref0 \\ \lhd wait0 \rhd \\ tr0 = tr \land ((l, C)) \end{pmatrix} \land vars0 = vars \\ tr0 = tr \land ((l, C)) \end{pmatrix} \land vars0 = vars \end{pmatrix} \end{pmatrix}; A$$
= [State Assignment B.16]
$$\exists v 0. \begin{pmatrix} R \begin{pmatrix} true \vdash \begin{pmatrix} tr0 = tr \land (l, C) \notin ref0 \\ \lhd wait0 \rhd \\ tr0 = tr \land ((l, C)) \end{pmatrix} \land vars0 = vars \\ tr0 = tr \land ((l, C)) \end{pmatrix} \land vars0 = vars \end{pmatrix} \end{pmatrix}; A$$
= [Closure Conjunctive R B.2.42]

$$\exists v_{0}. \begin{cases} \left(\left(true \vdash \left(tr0 = tr \land (l, C) \notin ref0 \\ \exists wait0 \triangleright \\ rt0 = tr \urcorner \langle (l, C) \rangle \right) \land vars0 = vars \\ rt0 = tr \urcorner \langle (l, C) \rangle \\ \land vars0 = vars \\ rt0 = tr \land \langle ($$

$$R \left(rue \vdash \exists v0. \begin{pmatrix} f(\alpha 0, \alpha') \land \\ (r0 = tr \land (l, C) \notin ref0 \\ (\forall wait0 \triangleright \\ rt0 = tr \land (l, C) \end{pmatrix} \land vars0 = vars \\ rt0 = tr \land (l, C) \land \\ \land wait0 \models \\ rt0 = tr \land (l, C) \land \\ \land (wait' = wait0) \land \neg wait0 \\ \land (ref' = ref0) \land (nalocalvars' = nalocalvars0) \\ \land (t' = tr0) \land (tr' = tr0) \\ \land (t' = tr0) \land (tr' = tr0) \\ \land (t' = tr0) \land (tr' = tr0) \\ \land (t' = tr0) \land (tr' = tr0) \\ \land (wait0 \models \\ tr0 = tr \land (l, C) \notin ref0 \\ (\forall wait0 \models \\ tr0 = tr \land (l, C) \land wait0 \\ \land (ref' = ref0) \land (nalocalvars' = nalocalvars0) \\ \land (tr' = tr0) \land (tr' = tr0) \\ \land (tr' = tr0) \land (tr' = tr0) \\ \land (tr' = tr0) \land (tr' = tr0) \\ \land (tr' = tr0) \land (tr' = tr0) \\ \land (tr' = tr0) \land (tr' = tr0) \\ \land (tr' = tr0) \land (tr' = tr0) \\ \land (tr' = tr0) \land (tr' = tr0) \\ \land (tr' = tr0) \land (tr' = tr0) \\ \land (tr' = tr0) \land (tr' = tr0) \\ \land (tr' = tr0) \land (tr' = tr0) \\ \land (tr' = tr0) \land (tr' = tr0) \\ \land (tr' = tr0) \land (tr' = tr0) \\ \land (tr' = tr0) \land (tr' = tr0) \\ \land (tr' = tr0) \land (tr' = tr0) \\ \land (tr' = tr0) \land (tr' = tr0) \\ \land (tr' = tr0) \land (tr' = tr0) \\ \land (tr' = tr) \land (t, C) \notin ref0 \\ (\forall wait0 \models tr) \land (tr' = tr0) \\ \land (tr' = tr0) \land (tr' = tr0) \\ \land (tr' = tr0) \land (tr' = tr0) \\ \land (tr' = tr0) \land (tr' = tr0) \\ \land (tr' = tr0) \land (tr' = tr0) \\ \land (tr' = tr) \land (t, C) \notin ref0 \\ (\forall wait0 \models tr) (tr) \land tr0 = tr0) \\ (tr0 = tr \land (t, C) \notin ref0 \\ (\forall wait0 \models tr) (tr) \land tr0 = tr0) \\ \land (tr' = tr0) \land (tr' = tr0) \\ \land (tr' =$$

$$R\left(true \vdash \exists v0. \begin{pmatrix} f(\alpha 0, \alpha') \land wait = wait 0 \land \\ ((tr0 = tr \land (l, C) \notin ref 0 \lhd wait' \triangleright tr0 = tr^{\frown} \langle (l, C) \rangle \rangle \land vars0 = vars) \\ \land (ref' = ref 0) \land (nalocalvars' = nalocalvars0) \\ \land (re' = tr0) \land (tr' = tr0) \\ \land ok' = ok0 \land \neg wait0 \\ = [Predicate Calculus: One-point-rule (inserting ref = ref 0)] \\ R\left(true \vdash \exists v0. \begin{pmatrix} f(\alpha 0, \alpha') \land wait = wait0 \land ref = ref 0 \land \\ ((tr0 = tr \land (l, C) \notin ref 0 \lhd wait' \triangleright tr0 = tr^{\frown} \langle (l, C) \rangle \rangle \land vars0 = vars) \\ \land (nalocalvars' = nalocalvars0) \\ \land (rr' = tr0) \land (tr' = tr0) \\ \land ok' = ok0 \land \neg wait0 \\ = (redicate Calculus: One-point-rule (replacing \notin ref 0 by \notin ref')] \\ R\left(true \vdash \exists v0. \begin{pmatrix} f(\alpha 0, \alpha') \land wait = wait0 \land ref = ref 0 \land \\ ((tr0 = tr \land (l, C) \notin ref' \lhd wait' \triangleright tr0 = tr^{\frown} \langle (l, C) \rangle) \land vars0 = vars) \\ \land (nalocalvars' = nalocalvars0) \\ \land (tr' = tr0) \land (tr' = tr0) \\ \land (nalocalvars' = nalocalvars0) \\ \land (tr' = tr0) \land (tr' = tr0) \\ \land (nalocalvars' = nalocalvars0) \\ \land (tr' = tr0) \land (tr' = tr0) \\ \land (tr0 = tr \land (l, C) \notin ref' \lhd wait' \triangleright tr0 = tr^{\frown} \langle (l, C) \rangle) \land vars0 = vars) \\ \land (tr' = tr0) \land (tr' = tr0) \\ \land (tr' = tr0) \land (tr' = tr0) = tr^{\frown} \langle (l, C) \rangle \land vars0 = vars) \\ \land (tr' = tr0) \land (tr' = tr0) = tr^{\frown} \langle (l, C) \rangle \land vars0 = vars) \\ \land (tr' = tr0) \\ \land (tr' = tr0) \\ \land (tr' = tr0) \\ \land (tr0 = tr \land (l, C) \notin ref' \lhd wait' \triangleright tr0 = tr^{\frown} \langle (l, C) \rangle \land vars0 = vars) \\ \land (tr' = tr0) \\ \land (tr' = tr0) \\ \land (tr' = tr0) \\ \land (tr0 = tr \land (l, C) \notin ref' \lhd wait' \triangleright tr0 = tr^{\frown} \langle (l, C) \rangle \land vars0 = vars) \\ \land (tr' = tr0) \\ \land (tr0 = tr \land (l, C) \notin ref' \lhd wait' \triangleright tr0 = tr^{\frown} \langle (l, C) \rangle \land vars0 = vars) \\ \land (tr' = tr0) \\ (nalocalvars' = nalocalvars0) \\ \land (tr' = tr0) \\ (nalocalvars' = nalocalvars0) \\ \land (tr' = tr0) \\ (nalocalvars' = nalocalvars0) \\ \land (tr' = tr0) \\ (nalocalvars' = nalocalvars0) \\ \land (tr' = tr0) \\ (true \vdash \exists v0. \begin{pmatrix} f(\alpha, \alpha') \land wait = wait \land ref = ref 0 \land tr = tr0 \land \\ (true \vdash \exists v0. \begin{pmatrix} f(\alpha, \alpha') \land wait = wait \land ref = ref 0 \land tr = tr0 \land \\ (true \vdash \exists v0. \begin{pmatrix} f(\alpha, \alpha') \land wait = wait \land ref = ref 0 \land tr = tr0 \land \\ (true \vdash \exists v0. \begin{pmatrix} f(\alpha, \alpha') \land wait = wait \land ref = ref 0 \land tr = tr0 \land \\ (true \vdash i \land (l, C) \land wait = wa$$

Thus, vars0 = vars can be rewritten as $f(\alpha, \alpha 0) \land$ nalocalvars0 = nalocalvars, such

that f (α , α 0) does not change its values]

$$R\left(\begin{array}{c} true \vdash \exists v0. \left(\begin{array}{c} f(\alpha 0, \alpha') \land wait = wait0 \land ref = ref0 \land tr = tr0 \land \\ \left(tr' = tr \land (l, C) \notin ref' \lhd wait' \rhd tr' = tr \land \langle (l, C) \rangle \right) \\ \land f(\alpha, \alpha 0) \land nalocalvars0 = nalocalvars \end{array}\right) \\ \land (nalocalvars' = nalocalvars0) \\ \land ok' = ok0 \land \neg wait0 \end{array}\right) ; A$$

$$= [\operatorname{Predicate Calculus:} f(\alpha 0, \alpha') \operatorname{and} f(\alpha, \alpha 0) \operatorname{side by side}]$$

$$R\left(\begin{array}{c} true \vdash \exists v0. \left(\begin{array}{c} f(\alpha 0, \alpha') \land f(\alpha, \alpha 0) \land wait = wait0 \land ref = ref0 \land tr = tr0 \land \\ \left(tr' = tr \land (l, C) \notin ref' \lhd wait' \rhd tr' = tr \land \langle (l, C) \rangle \right) \\ \land nalocalvars0 = nalocalvars \end{array}\right) \\ \land (nalocalvars' = nalocalvars0) \\ \land ok' = ok0 \land \neg wait0 \end{array}\right) ; A$$

= [Predicate Calculus: switching the positions of *nalocalvars0* = *nalocalvars* and *nalo-calvars'* = *nalocalvars0*]

$$R\left(true \vdash \exists v0. \begin{pmatrix} f(\alpha 0, \alpha') \land f(\alpha, \alpha 0) \land wait = wait0 \land ref = ref0 \land tr = tr0 \land \\ (tr' = tr \land (l, C) \notin ref' \lhd wait' \rhd tr' = tr \land \langle (l, C) \rangle) \\ \land (nalocalvars' = nalocalvars0) \end{pmatrix} \right); A$$

$$= [Assumption: ok = ok']$$

$$R\left(true \vdash \exists v0. \begin{pmatrix} f(\alpha 0, \alpha') \land f(\alpha, \alpha 0) \land wait = wait0 \land ref = ref0 \land tr = tr0 \land \\ (tr' = tr \land (l, C) \notin ref' \lhd wait' \rhd tr' = tr \land \langle (l, C) \rangle) \\ \land (nalocalvars' = nalocalvars0) \end{pmatrix} \right); A$$

$$= [Predicate Calculus: placing nalocalvars0 = nalocalvars \land ok = ok0 \land \neg wait0$$

$$R\left(\begin{array}{c} true \vdash \exists v0. \left(\begin{array}{c} nalocalvars0 = nalocalvars \land ok = ok0 \land \neg wait0 \land \\ f(\alpha 0, \alpha') \land f(\alpha, \alpha 0) \land wait = wait0 \land ref = ref0 \land tr = tr0 \land \\ \left(\begin{array}{c} (tr' = tr \land (l, C) \notin ref' \lhd wait' \rhd tr' = tr \frown \langle (l, C) \rangle) \\ \land (nalocalvars' = nalocalvars0) \end{array}\right) \end{array}\right); A$$

$$= [\operatorname{Predicate Calculus: rearranging some factors]} \left(\begin{array}{c} f(\alpha, \alpha 0) \\ \land ok = ok0 \land wait = wait0 \land ref = ref0 \\ \land nalocalvars0 = nalocalvars \land tr0 = tr \land \neg wait0 \\ \land f(\alpha 0, \alpha') \land \\ \left(\begin{array}{c} (tr' = tr \land (l, C) \notin ref' \lhd wait' \rhd tr' = tr \frown \langle (l, C) \rangle) \\ \land (nalocalvars' = nalocalvars0) \end{array}\right) \right) \right); A$$

$$= [Existential Quantifier Distributed Throughout Design B.16] f(\alpha, \alpha0) \land ok = ok0 \land wait = wait0 \land ref = ref0 \land nalocatvars0 = nalocalvars \land tr0 = tr \land wait0 \land f(\alpha0, \alpha') \land (tr' = tr \land (l, C) \notin ref' \lhd wait' \rhd tr' = tr \land ((l, C))) \land (nalocatvars' = nalocalvars0) = = [Existential Quantifier Shifted Inside R (reverse) B.15] f(\alpha, \alpha0) \land ok = ok0 \land wait = wait0 \land ref = ref0 \land nalocatvars0 = nalocalvars \land tr0 = tr \land wait0 \land f(\alpha0, \alpha') \land (tr' = tr \land (l, C) \notin ref' \lhd wait' \rhd tr' = tr \land ((l, C)))))) ; A = [Designs And True B.2.46] f(\alpha, \alpha0) \land true \vdash (f(\alpha, \alpha0) \land ok = ok0 \land wait = wait0 \land ref = ref0 \land nalocatvars0 = nalocalvars0) = = [Designs And True B.2.46] f(\alpha, \alpha0) \land true \vdash (f(\alpha, \alpha0) \land ok = ok0 \land wait = wait0 \land ref = ref0 \land nalocatvars0 = nalocalvars0) = = [State Assignment B.16] \exists v0.R \land true \vdash (s(\alpha, \alpha0) \land tr = tr0 \land \neg wait0) \exists v0.R (tr' = tr \land (l, C) \notin ref' \lhd wait' \rhd tr' = tr \land ((l, C)))))) ; A (nalocatvars' = nalocatvars0) = = [Closure Conjunctive R B.2.42] = [Closure Conjunctive R B.2.42] R (true \vdash (s(\alpha, \alpha0) \land tr = tr0 \land \neg wait0)) \exists v0. (R (true \vdash (s(\alpha, \alpha0) \land tr = tr0 \land \neg wait0))) \exists v0. (R (true \vdash (s(\alpha, \alpha0) \land tr = tr0 \land \neg wait0))) \exists v0. (R (true \vdash (s(\alpha, \alpha0) \land tr = tr0 \land \neg wait0))) \exists v0. (R (true \vdash (s(\alpha, \alpha0) \land tr = tr0 \land \neg wait0))))))) ; A = [Predicate Calculus: repositioning nalocalvars0 = nalocalvars0 = = [Predicate Calculus: repositioning nalocalvars0 = nalocalvars0] \exists v0. (R (true \vdash (s(\alpha, \alpha0) \land tr = tr0 \land \neg wait0))) \exists v0. (R (true \vdash (s(\alpha, \alpha0) \land tr = tr0 \land \neg wait0))) \exists v0. (R (true \vdash (s(\alpha, \alpha0) \land tr = tr0 \land \neg wait0))) \exists v0. (R (true \vdash (s(\alpha, \alpha0) \land tr = tr0 \land \neg wait0))) \exists v0. (R (true \vdash (s(\alpha, \alpha0) \land tr = tr0 \land \neg wait0))) \exists v0. (R (true \vdash (s(\alpha, \alpha0) \land tr = tr0 \land \neg wait0))))) ; A = [On the denotational definition of Prefixing A.2, f (c0, c') \land nalocalvars' = na$$

vars0 is vars' = vars0]

$$\exists v 0. \begin{pmatrix} R \left(true \vdash \left(s(\alpha, \alpha 0) \land tr = tr 0 \land \neg wait 0 \right) \right) \\ \land R \left(true \vdash \left((tr' = tr \land (l, C) \notin ref' \lhd wait' \rhd tr' = tr \land \langle (l, C) \rangle \right) \\ \land vars' = vars 0 \end{pmatrix} \end{pmatrix} \end{pmatrix}; A$$

$$= [Definition of Lift B.24]$$

$$\exists v 0. \begin{pmatrix} Lift(s)(\alpha, \alpha 0) \\ \land R \left(true \vdash \left((tr' = tr \land (l, C) \notin ref' \lhd wait' \rhd tr' = tr \land \langle (l, C) \rangle \right) \\ \land vars' = vars 0 \end{pmatrix} \end{pmatrix}) \end{pmatrix}; A$$

$$= [Definition of doC B.32]$$

$$\exists v 0. \begin{pmatrix} (Lift(s))(\alpha, \alpha 0) \\ \land (l \rightarrow Skip)(\alpha 0, \alpha') \end{pmatrix}; A$$

$$= [Sequence Denotational Definition B.33]$$
Lift (s); $l \rightarrow Skip$

Theorem 8. Parallel Prefixed Loc:

```
(loc \ s1 \bullet A1) \ [x1 \mid CS \mid x2] \ (loc \ s2 \bullet A2)\sqsubseteql \to ((loc \ s3 \bullet A3) \ [x1 \mid CS \mid x2] \ (loc \ s2 \bullet A2))
```

provided that

Lift (*s1*) ; *A1* \sqsubseteq *Lift* (*s3*) ; *l* \rightarrow *A3* \square *Lift* (*s1*) ; *A1* [*Assumption 1*] (assumption 1 is the right side of the denotational definition of labelled transition (*c1* | *s1* \models *A1*) $\stackrel{l}{\rightarrow}$ (*c3* | *s3* \models *A3*))

```
initials (Lift (s2); A2) \subseteq CS [Assumption 2]
(assumption 2 indicates that we require that the initial events being offered by Lift (s2);
A2 lie on channel set CS)
```

 $CS \cap usedC$ (Lift (s3); A3) = \emptyset [Assumption 3] (assumption 3 demands that no channel used on Lift (s3); A3 can lie on channel set CS)

wrtV (Lift (s3); A3) \cap usedV (Lift (s2); A2) = \emptyset [Assumption 4]

(assumption 4 demands that no variables that are used by action Lift (s2); A2 can be written)

Lift (*s*2) ; *A*2 *is divergence free* [*Assumption 5*] (*assumption 5 is self-explanatory*)

ok = ok' [Assumption 6]

```
(assumption 6 demands that either (1) if the program has started than it has finished, or (2) if the program did not start then it did not finish)
```

Proof

Before starting to prove, we will derive a new assumption from the provided assumption: [Assumption 1] Lift (s1); A1 \sqsubseteq Lift (s3); 1 \rightarrow A3 \square Lift (s1); A1

 \Rightarrow [External Choice Refinement Implication 15]

[Assumption ppl] Lift (s1); A1 \sqsubseteq Lift (s3); $1 \rightarrow A3$

We also assume Theorem 11 on the proof to assure that Lift (s1), Lift (s2) and Lift (s3) are *Circus* actions. We will add an explanation of each tactic and sub-goal, envisaging explaining this proof. Now we will start proving:

 $((\log s1 \bullet A1) || x1 | CS | x2 || (\log s2 \bullet A2))$

= [Definition of loc **B.29**]

(We will apply the definitions of loc in order to convert them to Lift expressions. Lift expressions allow the application of the lemmas and theorems used throughtout the proof) ((Lift (s1); A1) $\| x1 | CS | x2 \|$ (Lift (s2); A2))

[Assumption ppl with Parallelism Refinement Monotonic B.2.21]

(application of assumption ppl and Monotonicity of Refinement for Parallelism allow refining the expression to an expression that has $l \rightarrow A3$, linking the left expression to the right expression)

 $((Lift (s3); 1 \rightarrow A3) || x1 | CS | x2 || (Lift (s2); A2))$

= [Lift Shift (having Assumption 6) 7]

(Lift Shift has an important role on this proof, as it allows swapping the positions from Lift (s3) and l on the prefixing (\rightarrow) operator. This is important because the right expression of the refinement we want to prove has l before expression loc s3 • A3)

 $((l \rightarrow Lift (s3); A3) [[x1 | CS | x2]] (Lift (s2); A2))$

= [Prefixing Sequence theorem: **B.2.5**]

(now we transform $l \rightarrow Lift$ (s3) into $l \rightarrow Skip$; Lift (s3), in order to allow the application of Parallel Composition Sequence Step)

 $((l \rightarrow Skip; Lift(s3); A3) || x1 | CS | x2 || (Lift(s2); A2))$

= [Parallel Composition Sequence Step (having assumptions 2 to 5) B.2.3]

(the role of this step is to take l outside the left branch, making it a prefix not only from the left branch of the parallel composition, but also from the whole parallel composition)

 $l \rightarrow ((Lift (s3); A3) \ [\![x1 \mid CS \mid x2 \,]\!] (Lift (s2); A2))$

= [Definition of loc **B.29**]

(now we apply again the definition of loc in order to reach the right expression of the refinement)

 $l \rightarrow ((loc \ s3 \bullet A3) \ [\![\ x1 \ | \ CS \ | \ x2 \]\!] \ (loc \ s2 \bullet A2))$

Theorem 9. Parallel Independent Refinement:

 $(loc \ s1 \bullet A1) \parallel x1 \mid CS \mid x2 \parallel (loc \ s2 \bullet A2) \sqsubseteq (loc \ s3 \bullet A3) \parallel x1 \mid CS \mid x2 \parallel (loc \ s2 \bullet A2)$

provided that

• *Lift* (s1); $A1 \sqsubseteq Lift (s3)$; A3

In order to prove, we use Theorem 11 to assume that all Lift (s_i) are *Circus* actions. **Proof**

```
\begin{pmatrix} (locs1 \bullet A1) ||x1| CS| x2|| (locs2 \bullet A2) \\ \subseteq (locs3 \bullet A3) ||x1| CS| x2|| (locs2 \bullet A2) \end{pmatrix}
= [Definition of loc B.29]
\begin{pmatrix} (Lift(s1); A1) ||x1| CS| x2|| (Lift(s2); A2) \\ \subseteq (Lift(s3); A3) ||x1| CS| x2|| (Lift(s2); A2) \end{pmatrix}
= [Assumption, Ref. Eq. Sides 1 and Refinement Monotonic 6]
true
```

Theorem 10. Lifted Assignment is a Circus Assignment Command: Lift (x := c) = (x := c)

Proof

```
Lift (x := c)

= [Definition of Lift B.24]

R1 \circ R3 (true \vdash x := c \wedge tr' = tr \wedge \neg wait')

= [Replacing tr' = tr by tr' - tr = \langle \rangle]

R1 \circ R3 (true \vdash x := c \wedge tr' - tr = \langle \rangle \wedge \neg wait')

= [The expression is also R2. If it is R1 and R3, it is R]

R (true \vdash x := c \wedge tr' - tr = \langle \rangle \wedge \neg wait')

= [State Assignment B.16]

R (true \vdash x' = c \wedge u' = u \wedge tr' - tr = \langle \rangle \wedge \neg wait')

= [Assignment Denotational Definition A.4]

x := c
```

Theorem 11. *Lifted Sequence of Assignments is a Circus Assignment Command: Lift (s) = s*

provided that

• s is a sequence of state assignments (B.16) of the type $(x_1 := c_1; ...; x_n := c_n)$;

Proof

Lift (s) = [Assumption] Lift $(x_1 := c_1; ...; x_n := c_n)$ = [Lift Composition B.2.27] Lift $(x_1 := c_1); ...;$ Lift $(x_n := c_n)$ = [Lifted Assignment is a Circus Assignment Command 10 (n times)] $x_1 := c_1; ...; x_n := c_n$ = [Assumption] s

Theorem 12. **CSP* process as a Self-Reactive Design: $A = R((\neg A_f^f) \vdash (A_f^t)), \text{ provided that } A \text{ is a CSP process (CSP1, CSP2 and CSP3-healthy)}$

This theorem lies on [6].

Theorem 13. **Circus Action CSP1-CSP2-CSP3-Healthy:* Every Circus action is CSP1 B.38, CSP2 B.39 and CSP3 B.40 Healthy.

This theorem lies on [6].

Theorem 14.

**Monotonicity of Refinement on External Choice:* $A_1 \Box A_2 \sqsubseteq B_1 \Box B_2$ provided $A_1 \sqsubseteq B_1$ and $A_2 \sqsubseteq B_2$

Proof The proof lies on the document [7]. \Box

Theorem 15.

External Choice Refinement Implication $((Lift (s1); A1) \sqsubseteq (Lift (s2); l \rightarrow A2) \Box (Lift (s1); A1))$ \Rightarrow $((Lift (s1); A1) \sqsubseteq (Lift (s2); l \rightarrow A2))$ provided that $A1 = l \rightarrow A2$

Proof

 $\begin{array}{l} ((\text{Lift} (s1); A1) \sqsubseteq (\text{Lift} (s2); 1 \rightarrow A2) \Box (\text{Lift} (s1); A1)) \\ \textbf{[Assumption]} \\ ((\text{Lift} (s1); A1) \sqsubseteq (\text{Lift} (s2); A1) \Box (\text{Lift} (s1); A1)) \\ \Rightarrow \textbf{[Refinement Implication For Subst.Equiv. B.4 (having Lift Subst. Equiv. B.5 both for Lift (s1) and Lift (s2)) + Monotonicity of Refinement for Ext.Choice 14)]} \\ ((\text{Lift} (s1); A1) \sqsubseteq (\text{Lift} (s2); A1) \\ = \textbf{[Assumption]} \\ ((\text{Lift} (s1); A1) \sqsubseteq (\text{Lift} (s2); 1 \rightarrow A2) \\ \Box \end{array}$

Theorem 16. *Hidden Event Sequenced by Skip:* $((l \rightarrow Skip) \setminus \{l\}) = Skip$

Proof

The proof lies on [6].

B.2.4 Auxiliary Laws

On this appendix, we will list all denotational laws that were used throughtout this document (all refinement laws that were used from the Denotational Semantics of *Circus* [6] (refinement laws), laws concerning the denotational theory of the CML Operational Semantics we have lifted, based on [3], and laws that we created and proved correct).

Refinement Laws

Law B.2.1. (*) *Skip* = *V* : [g, true]

The above law is shown on [6].

Law B.2.2. (*) *Skip* ; A = A

Proof The proof lies on the document [6]. □

Law B.2.3. *Parallel Composition Sequence Step:

 $(A1; A2) \parallel ns1 \parallel cs \parallel ns2 \parallel A3 = A1; (A2 \parallel ns1 \parallel cs \parallel ns2 \parallel A3)$

provided that

- *initials* $(A3) \subseteq cs$
- $cs \cap usedC(A1) = \emptyset$
- $wrtV(A1) \cap usedV(A3) = \emptyset$
- A3 is divergence-free

Function usedV (Act) is defined at [6] and returns the set of variables that are used by action Act. Function usedC is defined on B.12. Function wrtV (Act) is defined at [6] and returns the set of variables that are written by action Act.

Proof The proof lies on the document [6].

Law B.2.4. **True Guard*: true & A = A

Proof The proof lies on the document [6] \Box

Law B.2.5. **Prefixing Sequence:* $a \rightarrow B = a \rightarrow Skip$; *B*

The proof lies on the document [6]

Law B.2.6.

*Compound Actions Commutative (Except for Sequence): A1 BOP A2 = A2 BOP A1 provided that BOP $\in \{ \| \{ | cs | \} \|, \| |, \Box, \Box, \}$

For Parallel Compositions with name-sets, the name-sets are also commuted: A1 $[[ns1 \{ | cs | \} ns2]]$ A2 = A2 $[[ns2 \{ | cs | \} ns1]]$ A1

Proof There is a version of this law for each compound operator that is commutative, all of which are referenced on document [6].

Law B.2.7.

*Communication Parallelism Distribution:

 $c \rightarrow (A1 \parallel \{ | CS | \} \parallel A2) = ((c \rightarrow A1) \parallel \{ | CS | \} \parallel (c \rightarrow A2))$ provided that $\{ c \} \in CS$

Proof The law is referenced on document [6].

Law B.2.8. *Hiding Identity: $A \setminus CS = A$ provided $CS \cap UsedC(A) = \emptyset$ **Proof** The law is referenced on document [6]. Law B.2.9. *Hiding Monotonic: $P_1 \setminus S \sqsubseteq P_2 \setminus S$ provided $P_1 \sqsubset P_2$ **Proof** The law is referenced on document [6]. Law B.2.10. *Hiding External Choice Distributive: $(A_1 \Box A_2) \setminus cs = (A_1 \setminus cs) \Box (A_2 \setminus cs)$ *provided* (*initials* (A1) \cup *initials* (A2)) \cap cs = \emptyset **Proof** The law is referenced on document [6]. Law B.2.11. *External Choice Sequence Distributive: $((A_1; B) \Box (A_2; B)) = ((A_1 \Box A_2); B))$ **Proof** The law is referenced on document [6]. Law B.2.12. *Hiding Sequence Distributive: $(A_1; A_2) \setminus cs = (A_1 \setminus cs); (A_2 \setminus cs)$ **Proof** The law is referenced on document [6]. Law B.2.13. *Variable Block Extension:

 $A_1 ; (\mathbf{var} \ x : T \bullet A_2) ; A_3 = (\mathbf{var} \ x : T \bullet A_1 ; A_2 ; A_3)$ provided $x \notin FV(A_1) \cup FV(A_3)$

| Proof The law is referenced on document [6]. | |
|---|--|
| Law B.2.14. *Variable Block Extension (A): | |
| A_1 ; (var $x : T \bullet A_2$) = (var $x : T \bullet A_1$; A_2) | |
| <i>provided</i> $x \notin FV(A_1)$ | |
| Proof The law is referenced on document [6]. | |
| Law B.2.15. * Circus Basic Process to Circus action: | |
| begin state [decl pred] PPars • A end $\hat{=}$ var decl • A | |
| Proof The law is referenced on document [6]. | |
| Lemma B.18. (*) STOP $\Box A = A$ | |
| Proof The proof lies on [6]. | |
| Law B.2.16. *Sequence, External and Internal Choice Process to Basic Process: | |
| For $op \in \{ \ ; \ , \ \Box, \ \Box \ \}$ | |
| $P \ op \ Q = $ begin state $State \ \widehat{=}$ | |
| $P.State \land Q.State$ | |
| <i>P.PPar</i> $\wedge_{\Xi} Q.State$ | |
| $Q.PPar \wedge_{\Xi} P.State$ | |
| • P.Act op Q.Act | |
| end | |
| Proof The law is referenced on document [6]. | |

Law B.2.17. *Parallel and Interleave Processes to Basic Process:

For op = ||CS|| $P ||Cs||Q = begin state State \cong$ $P.State \land Q.State$ $P.PPar \land_{\Xi} Q.State$ $Q.PPar \land_{\Xi} P.State$ • $P.Act ||\alpha(P.State) | cs | \alpha(Q.State) || Q.Act$ end

Proof The law is referenced on document [6].

Law B.2.18. **Rename Basic Process to Basic Process with Rename Main Action:* (begin *PARS* • *A* end) [*a1*, ... *an* := *b1*, ..., *bn*] = (begin *PARS* • *A* [*a1*, ... *an* := *b1*, ..., *bn*] end)

Proof The proof lies on [6]

Law B.2.19. (*) begin *PPars* • A end $\setminus CS$ = begin *PPars* • (A $\setminus CS$) end

The law is referenced on document [6].

Law B.2.20.

*Internal Choice Refinement Monotonic: $A_1 \sqcap A_2 \sqsubseteq B_1 \sqcap B_2$ provided $A_1 \sqsubseteq B_1$ and $A_2 \sqsubseteq B_2$

Proof Proof lies on document [6].

Law B.2.21.

**Parallelism Refinement Monotonic*: $A_1 \parallel CS \parallel A_2 \sqsubseteq B_1 \parallel CS \parallel B_2 \text{ provided } A_1 \sqsubseteq B_1 \text{ and } A_2 \sqsubseteq B_2$

Proof Proof lies on document [6].

Law B.2.22.

**External Choice Refinement Monotonic*: $A_1 \Box A_2 \sqsubseteq B_1 \Box B_2$ provided $A_1 \sqsubseteq B_1$ and $A_2 \sqsubseteq B_2$

Proof Proof lies on document [6].

Law B.2.23. *R2 Conjunction Not Mentioning Trace* $p \land R2$ (P) = R2 ($p \land P$), provided that p does not mention tr and tr'

The proof lies on the documents [6].

Cavalcanti and Woodcock's Laws

Law B.2.24. **External Choice Idempotence:* $(P \Box P) = P$

Proof The proof lies on the document [3]

Law B.2.25. **Refinement of Non-Determinism:* $A \sqcap B \sqsubseteq A$

Proof The proof lies on document [3]

Law B.2.26. **Lift is CSP4*: *Lift* (v := e); *Skip* = *Lift* (v := e)

Proof The proof lies on the document [3]. All definitions, lemmas, theorems, laws and rules from CML can be used for *Circus* [5]. □

Law B.2.27. *Lift Composition: Lift $(s ; v := w_1) = Lift (s)$; Lift $(v := w_1)$

Proof The proof lies on the document [3] \Box

Law B.2.28. *Lift External Choice: Lift(s); $(P \Box Q) = (Lift(s); P) \Box (Lift(s); Q)$

Proof The proof lies on the document [3] \Box

Law B.2.29.

*Lift Left Unit: Lift (s); Lift (t) = Lift (t)

Proof The proof lies on the document [3] \Box

Law B.2.30. *Lift Leading Substitution: Lift (s) ; P = Lift(s) ; $P [e / w_1]$, provided that (s ; $(w_1 = e))$

Proof The proof lies on the document [3] \Box

Law B.2.31. (*) *Lift* (*s*) ; *Lift* (v := e) = *Lift* (*s*) ; $v :=_{RD} e$

Proof The proof lies on the document [3] \Box

Law B.2.32.

*Substitution: Lift (v := w) [e / w] = Lift (v := e) **Proof** The proof lies on the document [3]

Law B.2.33. (*) *Lift* (*var* $x := w_1$) = *var* x; *Lift* ($x := w_1$)

Proof The proof lies on document [3]

Law B.2.34. **Reactive Design Assignment Declaration:* $var x ; x :=_{RD} w = var x :=_{RD} w$

Proof The proof lies on document [3]

Law B.2.35. (*) $var_{RD} x :=_{RD} w$; $P = P(w \lor x)$

Proof The proof lies on document [3]

Law B.2.36. **Input Absorption:* Lift(s); $d?x: T \rightarrow A = (Lift(s); d.w \rightarrow A [w / x]) \Box (Lift(s); d?x: T \rightarrow A)$

Proof The proof lies on document [3] □

Law B.2.37. *Parallel Distributivity: Lift (s); $(P |[x_1 | cs | x_2]] Q) = (Lift(s); P) |[x_1 | cs | x_2]] (Lift(s); Q)$

Proof The proof lies on document [3] □

Law B.2.38. **Lift Semi-Idempotence:* $s ; (s | x_1)_{+x_2} = s$

Proof The proof lies on document [3] □

Law B.2.39. *Lift Merge: Lift $(s_1) || x_1 | c_5 | x_2 ||$ Lift $(s_2) = Lift ((s_1 | x_1) \land (s_2 | x_2))$ **Proof** The law is referenced on document [3]

Law B.2.40. **Closure Conjunctive R1* R1 ($P \land Q$) = $P \land Q$, provided that P and Q are R1

Law B.2.41. **Closure Conjunctive R3* R3 ($P \land Q$) = $P \land Q$, provided that P and Q are R3

This law was proved on [2].

Law B.2.42. **Closure Conjunctive R* $R(P \land Q) = P \land Q$, provided that P and Q are R

This law was proved on [2].

Law B.2.43. **Closure Disjunctive R2* $R2(P \lor Q) = P \lor Q$, provided that P and Q are R2

This law was proved on [2].

Other Laws

On this sub-section we show laws that we created and proved correct.

Law B.2.44. Parallel Composition Prefixing Step: $(a \rightarrow A2) \parallel ns1 \parallel cs \parallel ns2 \parallel A3 = a \rightarrow (A2 \parallel ns1 \parallel cs \parallel ns2 \parallel A3)$

provided that

initials (A3) \subseteq cs cs \cap {a} = \emptyset wrtV ({a}) \cap usedV (A3) = \emptyset A3 is divergence-free

Proof

(a → A2) |[ns1 {| cs |} ns2]| A3 = [Prefixing Sequence theorem: B.2.5] ((a → Skip) ; A2) |[ns1 {| cs |} ns2]| A3 = [Parallel Composition Sequence Step B.2.3 and Assumptions] true

Law B.2.45. Lifted Assignment Sequenced by end x

Lift (s; end x) = Lift (s); Lift (end x)

Proof

```
Lift (s; end x)
= [Definition of Lift B.24]
R1 \circ R3 (true \vdash s; end x \wedge tr' = tr \wedge \neg wait')
= [Definition of Sequence B.33]
R1 \circ R3 (true \vdash (\exists v0 . s (\alpha, \alpha 0) \land end x (\alpha 0, \alpha ')) \land tr' = tr \land \neg wait')
= [Predicate Calculus: all variables on v0 are free on R1 and R3]
\exists v0. R1 \circ R3 (true \vdash (s (\alpha, \alpha 0) \land end x (\alpha 0, \alpha')) \land tr' = tr \land \neg wait')
= [Predicate Calculus]
\exists v0. R1 \circ R3 (true \vdash s (\alpha, \alpha 0) \wedge tr' = tr \wedge \neg wait' \wedge end x (\alpha 0, \alpha') \wedge tr' = tr \wedge \neg wait')
= [Designs And True B.2.46]
\exists v0.
R1 \circ R3 (true \vdash s (\alpha, \alpha0) \wedge tr' = tr \wedge \neg wait')
\wedge R1 \circ R3 (true \vdash end x (\alpha0, \alpha') \wedge tr' = tr \wedge \neg wait')
= [Definition of Lift B.24]
\exists v0. Lift (s) \land Lift (end x)
= [Definition of Sequence B.33, having, from theorem 11 that Lift (s) is a Circus
action]
Lift (s); Lift (end x)
Law B.2.46. Designs And True:
```

 $(true \vdash Q_1 \land Q_2) = (true \vdash Q_1) \land (true \vdash Q_2)$

```
Proof true \vdash Q1 \land Q2

= [Predicate Calculus]

true \land ok \Rightarrow (Q1 \land Q2 \land ok')

= [Predicate Calculus]

ok \Rightarrow (Q1 \land Q2 \land ok')

= [Predicate Calculus]

(\neg ok) \lor (Q1 \land Q2 \land ok')

= [Predicate Calculus]

(\neg ok \lor Q1) \land (\neg ok \lor Q2) \land (\neg ok \lor ok')

= [Predicate Calculus]

((\neg ok \lor Q1) \land (\neg ok \lor ok')) \land ((\neg ok \lor Q2) \land (\neg ok \lor ok'))
```

```
= [Predicate Calculus]

(\neg ok \lor (Q1 \land ok')) \land (\neg ok \lor (Q2 \land ok'))

= [Predicate Calculus]

(ok \Rightarrow Q1 \land ok') \land (ok \Rightarrow Q2 \land ok')

= [Predicate Calculus]

(true \land ok \Rightarrow Q1 \land ok') \land (true \land ok \Rightarrow Q2 \land ok')

= [Predicate Calculus]

(true \vdash Q1) \land (true \vdash Q2)
```

```
Law B.2.47. P \lhd b \rhd (Q \land R) = (P \lhd b \rhd Q) \land (P \lhd b \rhd R)
```

```
Proof P \triangleleft b \triangleright (Q \land R)

= [Definition of Conditional]

(b \land P) \lor (\neg b \land Q \land R)

= [Predicate Calculus]

((b \land P) \lor (\neg b \land Q \land \neg b \land R))

= [Predicate Calculus]

((b \land P) \lor (\neg b \land Q)) \land ((b \land P) \lor (\neg b \land R))

= [Definition of Conditional]

(P \lhd b \rhd Q) \land (P \lhd b \rhd R)

\Box
```

Law B.2.48. *Lift And: Lift* $(S \land P) = Lift (S) \land Lift (P)$

```
Proof LHS

= Lift (S \land P)

= [Definition of Lift (B.24)]

R1 (R3 (true \vdash S \land P \land tr' = tr \land \neg wait'))

= [Predicate Calculus]

R1 (R3 (true \vdash S \land tr' = tr \land \neg wait' \land P \land tr' = tr \land \neg wait'))

= [Predicate Calculus]

R1 (R3 (true \vdash (S \land tr' = tr \land \neg wait') \land (P \land tr' = tr \land \neg wait')))

= [Designs And True B.2.46]

R1 \circ R3 ((true \vdash (S \land tr' = tr \land \neg wait')) \land (true \vdash (P \land tr' = tr \land \neg wait')))

= [Closure Conjunctive R1 (B.2.40) and Closure Conjunctive R3 (B.2.41)]

R1 \circ R3 (true \vdash (S \land tr' = tr \land \neg wait')) \land R1 \circ R3 (true \vdash (P \land tr' = tr \land \neg wait'))
```

```
= [Definition of Lift (B.24)]
```

```
Lift (S) \land Lift (P)
= RHS
```

Law B.2.49. *R2 and R3 Composition Commutative:* $R2 \circ R3 (P) = R3 \circ R2 (P)$

Proof

```
\begin{array}{l} \texttt{R2} \circ \texttt{R3} (\texttt{P}) \\ = [\texttt{Definition of } \texttt{R3 B.21}] \\ \texttt{R2} (\texttt{II}_{rea} \lhd \texttt{wait} \vartriangleright \texttt{P}) \\ = [\texttt{Definition of Conditional B.18}] \\ \texttt{R2} ((\texttt{wait} \land \texttt{II}_{rea}) \lor ((\neg \texttt{wait}) \land \texttt{P})) \\ = [\texttt{Disjunctive Closure } \texttt{R2 B.2.43}] \\ \texttt{R2} (\texttt{wait} \land \texttt{II}_{rea}) \lor \texttt{R2} ((\neg \texttt{wait}) \land \texttt{P}) \\ = [\texttt{R2 Conjunctive Not Mentioning Trace B.2.23} (\texttt{having that wait and } \neg \texttt{wait do not mention tr and tr'})] \\ (\texttt{wait} \land \texttt{R2} (\texttt{II}_{rea})) \lor ((\neg \texttt{wait}) \land \texttt{R2} (\texttt{P})) \\ = [\texttt{Definition of Conditional B.18}] \\ (\texttt{R2} (\texttt{II}_{rea})) \lhd \texttt{wait} \rhd (\texttt{R2} (\texttt{P})) \\ = [\texttt{Definition of R3 B.21}] \\ \texttt{R3} \circ \texttt{R2} (\texttt{P}) \\ \Box \end{array}
```

B.3 Proof of Soundness for rules

B.3.1 Assignment

Attached Rule 1.

Assignment:

 $\frac{c \quad (s ; (w0 = e))}{(c \mid s \models v := e) \xrightarrow{\tau} (c \land (s ; (w0 = e)) \mid s ; v := w0 \models Skip)}$

The proof, on document [3], consists on proving that the LHS of the refinement expression equals the RHS.

Proof

```
RHS

=

Lift (s ; v := w0) ; Skip

= [Law LiftCSP4 B.2.26]

Lift (s ; v := w0)

= [Law Lift Composition B.2.27]

Lift (s) ; Lift (v := w0)

= [Law Lift Leading Substitution B.2.30]

Lift (s) ; Lift (v := w0) [e/w0]

= [Law Substitution B.2.32]

Lift (s) ; Lift (v := e)

= [Reactive Design Assignment B.17]

Lift (s) ; v :=<sub>RD</sub> e

=

LHS
```

B.3.2 Prefixing*

Attached Rule 2.

Input*:

 $\frac{c \quad T \neq \emptyset \quad x \notin \alpha(s)}{(c \mid s \models d?x:T \to A) \xrightarrow{d.w_0} (c \land w_0 \in T \mid s; \mathbf{var} \ x := w_0 \models \mathbf{let} \ x \bullet A)}$

Proof

 $(c \mid s \models d?x:T \rightarrow A) \xrightarrow{d.w_0} (c \land w_0 \in T \mid s; var x := w_0 \models let x \bullet A)$ = [Definition **B.26**] \forall w. c \land w₀ : T \Rightarrow $(Lift(s); d?x: T \rightarrow A \sqsubseteq (Lift(s; var x := w_0); d_{\cdot 1} \rightarrow let x \bullet A) \Box (Lift(s); d?x: T \rightarrow A))$

On Deliverable [3], the proof consists on proving that the RHS (Right-Hand Side) equals the LHS (Left-Hand Side):

RHS

= (Lift(s; var x := w_0); d.1 \rightarrow let x \bullet A) \Box (Lift(s); d?x: T \rightarrow A) = [Lemma **B.28**] (Lift (s; var x := w_0); d. $w_0 \rightarrow A$) \Box (Lift(s); d?x : T $\rightarrow A$) = [Law Lift Composition **B.2.27**] (Lift(s); Lift(var x := w_0); d. $w_0 \rightarrow A$) \Box (Lift(s); d?x : T $\rightarrow A$) = [Law Lift Var B.2.33] $\left((Lift(s); \mathbf{var}x; Lift(x := w_0); d.w_0 \to A) \Box (Lift(s); d?x : T \to A) \right)$ = [Reactive Design Assignment **B.17**] (Lift(s); var x; x :=_{RD} w_0 ; d.w₀ \rightarrow A) \Box (Lift(s); d?x : T \rightarrow A) = [Reactive Design Declaration **B.2.34**] (Lift(s); var $x :=_{RD} w_0$; d.w₀ \rightarrow A) \Box (Lift(s); d?x : T \rightarrow A) = [Reactive Design Declaration Elimination B.2.35] (Lift(s); (d.w₀ \rightarrow A) (w_0 /x)) \Box (Lift(s); d?x : T \rightarrow A) = [Substitution **B.2.32**] $(Lift(s); d.w_0 \rightarrow A(w_0/x)) \Box (Lift(s); d?x : T \rightarrow A)$ = [Input Absorption **B.2.36**] $(Lift(s); d?x : T \rightarrow A)$

= LHS

Attached Rule 3.

Output*:

 $\frac{c \quad s ; (w_0 = e)}{(c \mid s \models d! e \to A) \xrightarrow{d.w_0} (c \land s ; (w_0 = e) \mid s \models A)}$

Proof

 $(c \mid s \models d!e \rightarrow A) \xrightarrow{d.w_0} (c \land s ; (w_0 = e) \mid s \models A)$ = [Definition **B.26**] \forall w. c \land (c \land s; (w₀ = e)) \Rightarrow $(\text{Lift (s)}; d.e \rightarrow A \Box (\text{Lift (s)}; d.w_0 \rightarrow A) \Box (\text{Lift (s)}; d.e \rightarrow A))$ = [Lift Leading Substitution B.2.30] and assumption (s; $(w_0 = e)$) \forall w. c \land (c \land s; (w₀ = e)) \Rightarrow (Lift (s); d.e \rightarrow A \sqsubseteq (Lift (s); (d.w₀ \rightarrow A) [e / w₀]) \Box (Lift (s); d.e \rightarrow A)) = [Substitution **B.2.32**] and assumption (s ; $(w_0 = e)$) \forall w. c \land (c \land s; (w₀ = e)) \Rightarrow $(\text{Lift (s)}; d.e \rightarrow A \sqsubseteq (\text{Lift (s)}; d.e \rightarrow A [e / w_0]) \Box (\text{Lift (s)}; d.e \rightarrow A))$ = [Substitution B.2.32] and w₀ does not occur in A \forall w. c \land (c \land s; (w₀ = e)) \Rightarrow $(\text{Lift (s) ; d.e} \rightarrow A \sqsubseteq (\text{Lift (s) ; d.e} \rightarrow A) \Box (\text{Lift (s) ; d.e} \rightarrow A))$ = [External Choice Idempotence B.2.24] \forall w. c \land (c \land s; (w₀ = e)) \Rightarrow (Lift (s); d.e \rightarrow A \sqsubseteq Lift (s); d.e \rightarrow A) = [Refinement Equal Sides 1] \forall w. c \land (c \land s; (w₀ = e)) \Rightarrow true = [Predicate Calculus] \forall w . true

= true

B.3.3 Variable Block

All laws for Variable Block (Variable Block Begin, Variable Block Visible and Variable Block End) were proved by Barrocas, on this Thesis.

Attached Rule 4.

Variable Block Begin:

 $(c \mid s \models var x : T \bullet A) \xrightarrow{\tau} (c \land w_0 \in T \mid s; var x := w_0 \models let x \bullet A)$

Proof

```
(c \mid s \models var x : T \bullet A) \xrightarrow{\tau} (c \land w_0 \in T \mid s; var x := w_0 \models let x \bullet A)
= [Definition of Silent Transition B.25]
\forall w . (c \land c \land w_0 : T) \Rightarrow (Lift (s); var x : T \bullet A) \sqsubseteq (Lift (s; var x := w_0); let x \bullet A)
= [w is universally quantified, so we abstract it]
(c \land c \land w_0 : T) \Rightarrow (Lift (s); var x : T \bullet A) \sqsubset (Lift (s; var x := w_0); let x \bullet A)
= [Lift Composition B.2.27]
(c \land c \land w_0 : T) \Rightarrow (Lift (s); var x : T \bullet A) \sqsubseteq (Lift (s); Lift (var x := w_0); let x \bullet A)
= [Lift Left Unit B.2.29]
(c \land c \land w_0 : T) \Rightarrow (var x : T \bullet A) \sqsubseteq (Lift (var x := w_0); let x \bullet A)
= [(x := e) = (var x ; x := e)]
(c \land c \land w_0 : T) \Rightarrow (var x : T \bullet A) \sqsubseteq (Lift (var x; x := w_0); let x \bullet A)
= [Let definition B.28]
(c \land c \land w_0 : T) \Rightarrow (var x : T \bullet A) \sqsubseteq (Lift (var x; x := w_0); A)
= [Refinement Definition B.14]
(c \land c \land w_0 : T) \Rightarrow [(Lift (var x; x := w_0); A) \Rightarrow (var x : T \bullet A)]
= [Lemma B.8 and assms (\mathbf{w}_0 : \mathbf{T})]
(c \land c \land w_0 : T) \Rightarrow [true]
= [Predicate Calculus]
(c \land c \land w_0 : T) \Rightarrow true
= [Predicate Calculus]
true
Attached Rule 5.
```

Variable Block Visible: $\frac{(c_1 | s_1 \models A_1) \xrightarrow{l} (c_2 | s_2 \models A_2)}{(c_1 | s_1 \models let \ x \bullet A_1) \xrightarrow{l} (c_2 | s_2 \models let \ x \bullet A_2)}$

Proof

 $(c_{1} | s_{1} \models \text{let } x \bullet A_{1}) \xrightarrow{l} (c_{2} | s_{2} \models \text{let } x \bullet A_{2})$ = [Definition of let B.28] $(c_{1} | s_{1} \models A_{1}) \xrightarrow{l} (c_{2} | s_{2} \models \text{let } x \bullet A_{2})$ = [Definition of let B.28] $(c_{1} | s_{1} \models A_{1}) \xrightarrow{l} (c_{2} | s_{2} \models A_{2})$ = [Assumption (c_{1} | s_{1} \models A_{1}) \xrightarrow{l} (c_{2} | s_{2} \models A_{2})] true

Attached Rule 6.

Variable Block End:

 $\frac{c}{(c \mid s \models \textit{let } x \bullet \textit{Skip}) \xrightarrow{l} (c \mid s ; \textit{end } x \models \textit{Skip})}$

Proof

 $\forall w. (c \land c) \Rightarrow (Lift(s); letx \bullet Skip) \sqsubseteq (Lift(s; endx); Skip) \\ = [w is universally quantified, so we abstract it] \\ (c \land c) \Rightarrow (Lift(s); letx \bullet Skip) \sqsubseteq (Lift(s; endx); Skip) \\ = [Assumption c] \\ (Lift(s); letx \bullet Skip) \sqsubseteq (Lift(s; endx); Skip) \\ = [Definition of let [B.28]] \\ (Lift(s); Skip) \sqsubseteq (Lift(s; endx); Skip) \\ = [Lifted Assignment Sequenced by end x B.2.45] \\ (Lift(s); Skip) \sqsubseteq (Lift(s); Lift(endx); Skip) \\ \end{cases}$

As Sequence is monotonic with respect to refinement and Lift (s) is refined by itself, if we prove that Skip \sqsubseteq (Lift (end x) ; Skip), we also prove the above expression: $Skip \sqsubseteq (Lift (end x); Skip)$ = [Sequence Denotational Definition B.33] $Skip \sqsubseteq \exists v0.(Lift (end x) [v, v0] \land Skip [v0, v'])$ = [end x definition] $Skip \sqsubseteq \exists v0.(Lift (true \land \exists x') [v, v0] \land Skip [v0, v'])$ = [Lift Definition B.24 and true $\land \exists x'$ is R2] $Skip \sqsubseteq \exists v0.(R(true \vdash true \land \exists x0.tr0 = tr \land \neg wait0) \land Skip [v0, v'])$

= [Skip Denotational Definition]

$$Skip \sqsubseteq$$

$$\exists v0. \begin{pmatrix} R(true \vdash true \land \exists x0.tr0 = tr \land \neg wait0) \\ \land (R(true \vdash tr' = tr0 \land \neg wait' \land v' = v0)) \end{pmatrix}$$
= [Predicate Calculus]
$$Skip \sqsubseteq$$

$$\exists v0. \begin{pmatrix} R(true \vdash true \land tr0 = tr \land \neg wait0) \\ \land (R(true \vdash tr' = tr0 \land \neg wait' \land v' = v0)) \end{pmatrix}$$
= [Skip definition]
$$R(true \vdash tr' = tr \land \neg wait' \land v' = v) \sqsubseteq$$

$$\exists v0. \begin{pmatrix} R(true \vdash true \land tr0 = tr \land \neg wait0) \\ \land (R(true \vdash tr' = tr0 \land \neg wait' \land v' = v0)) \end{pmatrix}$$
= [Designs And True B.2.46 and Predicate Calculus]
$$R(true \vdash tr' = tr \land \neg wait' \land v' = v) \sqsubseteq$$

$$\exists v0. \begin{pmatrix} R(true \vdash tr' = tr \land \neg wait' \land v' = v) \sqsubseteq$$

$$\exists v0. \begin{pmatrix} R(true \vdash tr' = tr \land \neg wait' \land v' = v) \sqsubseteq$$

$$\exists v0. \begin{pmatrix} R(true \vdash tr' = tr \land \neg wait' \land v' = v) \sqsubseteq$$

$$\exists v0. \begin{pmatrix} R(true \vdash tr' = tr \land \neg wait' \land v' = v) \sqsubseteq$$

$$\exists v0. \begin{pmatrix} R(true \vdash tr' = tr \land \neg wait' \land v' = v) \end{bmatrix}$$
= [Predicate Calculus]
$$R(true \vdash tr' = tr \land \neg wait' \land v' = v) \sqsubseteq$$

$$\exists v. \begin{pmatrix} R(true \vdash tr' = tr \land \neg wait' \land v' = v) \end{bmatrix}$$
= [Factor ¬ wait0 makes the right side stronger than the left side, thus it is a refinement]
= true

B.3.4 Sequence

Attached Rule 7.

Sequence Progress: $\frac{(c_1 \mid s_1 \models A_1) \stackrel{l}{\rightarrow} (c_2 \mid s_2 \models A_2)}{(c_1 \mid s_1 \models A_1 ; B) \stackrel{l}{\rightarrow} (c_2 \mid s_2 \models A_2 ; B)}$

Proof

We will divide the proof in two cases, both of which have c_1 and c_2 being true. In the case that some of them is false, the antecedent of the implication is false, what makes the expression directly true.

Case 1 : $l = \tau$ and c_1 and c_2 are true

The assumption

 $(c_1 | s_1 \models A_1) \xrightarrow{l} (c_2 | s_2 \models A_2)$

equals (by the definition of Silent Transition B.25)

 $\forall \ w \ . \ c_1 \land c_2 \Rightarrow Lift \left(s_1 \right) \text{; } A_1 \sqsubseteq Lift \left(s_2 \right) \text{; } A_2$

Abstracting w, as it is universally quantified, we have

 $c_{1} \wedge c_{2} \Rightarrow Lift\left(s_{1}\right); A_{1} \sqsubseteq Lift\left(s_{2}\right); A_{2}$

Having c_1 and c_2 being true, by predicate calculus, we have:

[Derived Assumption]: Lift (s_1) ; A₁ \sqsubseteq Lift (s_2) ; A₂

Now we start proving:

 $(c_1 | s_1 \models A_1; B) \xrightarrow{\tau} (c_2 | s_2 \models A_2; B)$ = [Definition B.25, of τ transition] $\forall w . c_1 \land c_2 \Rightarrow \text{Lift} (s_1); A_1; B \sqsubseteq \text{Lift} (s_2); A_2; B$ = [w is universally quantified, so we abstract it]
c₁ ∧ c₂ ⇒ Lift (s₁) ; A₁ ; B ⊑ Lift (s₂) ; A₂ ; B
= [Derived Assumption with Monotonicity of Refinement (6) lead us to: Lift (s₁) ; A₁
; B ⊑ Lift (s₂) ; A₂ ; B]
= true

Case 2 : 1 is not silent ($\neq \tau$) and c1 and c2 are true The assumption

 $(c_1 | s_1 \models A_1) \xrightarrow{l} (c_2 | s_2 \models A_2)$

equals (by the definition of Labelled Transition B.26)

 $\begin{array}{l} \forall \ w \ . \ c_1 \land c_2 \Rightarrow \text{Lift} \ (s_1) \ ; \ A_1 \sqsubseteq (\text{Lift} \ (s_2) \ ; \ c.w1 \rightarrow A_2) \square (\text{Lift} \ (s_1) \ ; \ A_1) \\ = [w \ is \ universally \ quantified, \ so \ we \ abstract \ it] \\ c_1 \land c_2 \Rightarrow \text{Lift} \ (s_1) \ ; \ A_1 \sqsubseteq (\text{Lift} \ (s_2) \ ; \ c.w1 \rightarrow A_2) \square (\text{Lift} \ (s_1) \ ; \ A_1) \end{array}$

Having c_1 and c_2 being true, by predicate calculus, we have:

 \forall w . Lift (s₁) ; A₁ \sqsubseteq (Lift (s₂) ; c.w1 \rightarrow A₂) \Box (Lift (s₁) ; A₁)

and this lead us to

[Derived Assumption 2]:

Lift (s_1) ; $A_1 \sqsubseteq (Lift (s_2); c.w1 \rightarrow A_2) \Box (Lift (s_1); A_1)$

Expression to prove: $(c_{1} | s_{1} \models A_{1}; B) \xrightarrow{l} (c_{2} | s_{2} \models A_{2}; B) =$ $\forall w. c_{1} \land c_{2} \Rightarrow (Lift (s_{1}); A_{1}; B) \sqsubseteq (Lift (s_{2}); c.w1 \rightarrow A_{2}; B) \Box (Lift (s_{1}); A_{1}; B)$ = [w is universally quantified, so we abstract it] $c_{1} \land c_{2} \Rightarrow (Lift (s_{1}); A_{1}; B) \sqsubseteq (Lift (s_{2}); c.w1 \rightarrow A_{2}; B) \Box (Lift (s_{1}); A_{1}; B)$ = [External Choice/Sequence Distributive B.2.11] $c_{1} \land c_{2} \Rightarrow (Lift (s_{1}); A_{1}; B) \sqsubseteq ((Lift (s_{2}); c.w1 \rightarrow A_{2}) \Box (Lift (s_{1}); A_{1}); B)$ $= [Derived Assumption 2 with Monotonicity of Refinement (6) lead us to: (Lift (s_{1}); A_{1}; B) \sqsubseteq (Lift (s_{2}); c.w1 \rightarrow A_{2}; B) \Box (Lift (s_{1}); A_{1}; B)$ $= [(P \Rightarrow true) = true]$ = true

Attached Rule 8.

Sequence End:

 $\frac{c}{(c \mid s \models Skip ; A) \xrightarrow{\tau} (c \mid s \models A)}$ Proof $(c \mid s \models Skip ; A) \xrightarrow{\tau} (c \mid s \models A)$ = [Theorem B.2.2] $(c \mid s \models A) \xrightarrow{\tau} (c \mid s \models A)$ = [Theorem 2] true

B.3.5 Internal Choice*

Attached Rule 9.

Internal Choice Left*: $(c \mid s \models A_1 \sqcap A_2) \xrightarrow{\tau} (c \mid s \models A_1)$

Proof

 $(c \mid s \models A_1 \sqcap A_2) \xrightarrow{\tau} (c \mid s \models A_1)$ = [Definition of Silent Transition B.25] $\forall w . c \land c \Rightarrow Lift(s); (A_1 \sqcap A_2) \sqsubseteq Lift(s); A_1$ = [w is universally quantified, so we abstract it] $c \land c \Rightarrow Lift(s); (A_1 \sqcap A_2) \sqsubseteq Lift(s); A_1$ = [Refinement of Non-Determinism B.2.25] $c \land c \Rightarrow Lift(s); A_1 \sqsubseteq Lift(s); A_1$ = [Refinement Equal sides 1] $c \land c \Rightarrow true$ = [Predicate Calculus] = true

Attached Rule 10.

Internal Choice Right: $(c \mid s \models A_1 \sqcap A_2) \xrightarrow{\tau} (c \mid s \models A_2)$

Proof

 $(c \mid s \models A_1 \sqcap A_2) \xrightarrow{\tau} (c \mid s \models A_2)$ = Definition of Silent Transition B.25 $\forall w . c \land c \Rightarrow Lift (s) ; (A_1 \sqcap A_2) \sqsubseteq Lift (s) ; A_2$ = [w is universally quantified, so we abstract it] $c \land c \Rightarrow Lift (s) ; (A_1 \sqcap A_2) \sqsubseteq Lift (s) ; A_2$ = [Refinement Non-Determinism B.2.25] $c \land c \Rightarrow Lift (s) ; A_1 \sqsubseteq Lift (s) ; A_2$ = [Refinement Equal sides 1] $c \land c \Rightarrow true$ = [Predicate Calculus] = true

B.3.6 Guard

Attached Rule 11.

Guard:

```
\frac{c \quad (s ; g)}{(c \mid s \models g \& A) \xrightarrow{\tau} (c \land (s ; g) \mid s \models A)}
Proof
[Case 1: g is true]
(c \mid s \models g \& A) \xrightarrow{\tau} (c \land (s; g) \mid s \models A)
= [Definition of Silent Transition B.25]
\forall w . c \land c \land s ; g \Rightarrow (Lift (s) ; g & A) \sqsubseteq (Lift (s) ; A)
= [w is universally quantified, so we abstract it]
c \land c \land s; g \Rightarrow (Lift (s); g & A) \sqsubseteq (Lift (s); A)
= [Assumptions c and s ; g]
(true \land true \land true) \Rightarrow (Lift (s) ; g \& A) \sqsubseteq (Lift (s) ; A)
= [Predicate Calculus]
(Lift (s); g \& A) \sqsubseteq (Lift (s); A)
[True guard B.2.4]
(Lift (s); A) \sqsubseteq (Lift (s); A)
= [Refinement Equal Sides 1]
true
[Case 2: g is false]
(c \mid s \models g \& A) \xrightarrow{\tau} (c \land (s; g) \mid s \models A)
= [Definition of Silent Transition B.25]
\forall w. c \land c \land s; g \Rightarrow (Lift (s); g & A) \sqsubseteq (Lift (s); A)
= [w is universally quantified, so we abstract it]
c \land c \land s; g \Rightarrow (Lift (s); g \& A) \sqsubseteq (Lift (s); A)
= [Case 2: g is false (replacing g by false)]
c \land c \land s; false \Rightarrow (Lift (s); false & A) \sqsubseteq (Lift (s); A)
= [S Sequence False Equals False 5]
c \land c \land false \Rightarrow (Lift (s); false \& A) \sqsubseteq (Lift (s); A)
= [Predicate Calculus]
false \Rightarrow (Lift (s); false & A) \sqsubseteq (Lift (s); A)
= [Predicate Calculus]
true
```

B.3.7 External Choice*

Attached Rule 12.

External Choice Begin:* $(c \mid s \models A_1 \Box A_2) \xrightarrow{\tau} (c \mid s \models (loc \ s \bullet A_1) \boxplus (loc \ s \bullet A_2))$

Proof

```
\forall w . c \land c \Rightarrow (Lift (s); A_1 \Box A_2 \sqsubseteq (loc s \bullet A_1) \boxplus (loc s \bullet A_2))
= [Definition of Extra Choice B.30]
\forall w . c \land c \Rightarrow (Lift (s); A_1 \Box A_2 \sqsubseteq (loc s \bullet A_1) \Box (loc s \bullet A_2))
= [w is universally quantified, so we abstract it]
c \land c \Rightarrow (Lift (s); A_1 \Box A_2 \sqsubseteq (loc s \bullet A_1) \Box (loc s \bullet A_2))
= [Definition of loc B.29]
c \land c \Rightarrow (Lift (s); A_1 \Box A_2 \sqsubseteq (Lift (s); A_1) \Box (Lift (s); A_2))
= [Lift External Choice B.2.28]
c \land c \Rightarrow (Lift (s); A_1 \Box A_2 \sqsubseteq (Lift (s); Lift (s); A_1 \Box A_2))
= [Lift Left Unit B.2.29]
c \land c \Rightarrow (Lift (s) ; A_1 \Box A_2 \sqsubseteq (Lift (s) ; (A_1 \Box A_2)))
= [Parenthesis]
c \land c \Rightarrow (Lift (s); (A_1 \Box A_2) \sqsubseteq (Lift (s); (A_1 \Box A_2)))
= [Refinement Equal Sides 1]
c \land c \Rightarrow true
= [(\mathbf{P} \Rightarrow \mathbf{true}) = \mathbf{true}]
true
```

Attached Rule 13.

External Choice Skip:* $(c \mid s \models loc s_1 \bullet Skip \boxplus loc s_2 \bullet A) \xrightarrow{\tau} (c \mid s \models Skip)$

Proof $(c | s \models loc s_1 \bullet Skip \boxplus loc s_2 \bullet A) \xrightarrow{\tau} (c | s_1 \models Skip)$ = [Definition of Silent Transition B.25] $\forall w . c \Rightarrow Lift (s_1); (loc s_1 \bullet Skip \boxplus loc s_2 \bullet A) \sqsubseteq Lift (s_1); Skip$ = [w is universally quantified, so we abstract it] $c \Rightarrow Lift (s_1); (loc s_1 \bullet Skip \boxplus loc s_2 \bullet A) \sqsubseteq Lift (s_1); Skip$ = [Definition of Loc B.29]

```
c \Rightarrow \text{Lift } (s_1) ; (\text{Lift } (s_1) ; \text{Skip } \boxplus \text{Lift } (s_2) ; \text{A}) \sqsubseteq \text{Lift } (s_1) ; \text{Skip}
= [\text{Lift is CSP4 B.2.26}]
c \Rightarrow \text{Lift } (s_1) ; (\text{Lift } (s_1) \boxplus \text{Lift } (s_2) ; \text{A}) \sqsubseteq \text{Lift } (s_1) ; \text{Skip}
= [\text{Extra Choice Definition B.30}]
c \Rightarrow \text{Lift } (s_1) ; (\text{Lift } (s_1) \square \text{Lift } (s_2) ; \text{A}) \sqsubseteq \text{Lift } (s_1) ; \text{Skip}
= [\text{External Choice Assignment }]
c \Rightarrow \text{Lift } (s_1) ; \text{Lift } (s_1) \sqsubseteq \text{Lift } (s_1) ; \text{Skip}
= [\text{Lift is CSP4 B.2.26}]
c \Rightarrow \text{Lift } (s_1) ; \text{Lift } (s_1) \sqsubseteq \text{Lift } (s_1)
= [\text{Lift Left Unit B.2.29}]
c \Rightarrow \text{Lift } (s_1) \sqsubseteq \text{Lift } (s_1)
= [\text{Refinement Equal Sides 1}]
c \Rightarrow \text{true}
= [\text{Predicate Calculus}]
```

Attached Rule 14.

External Choice End*: $\frac{(c_1 | s_1 \models A_1) \xrightarrow{l} (c_3 | s_3 \models A_3)}{(c | s \models loc s_1 \bullet A_1 \boxplus loc s_2 \bullet A_2) \xrightarrow{l} (c_3 | s_3 \models A_3)}$

Proof

```
(c | s \models loc s_1 \bullet A_1 \boxplus loc s_2 \bullet A_2) \xrightarrow{l} (c_3 | s_3 \models A_3)

= [Definition of labelled transition B.26]

\forall w . c \land c_3 \Rightarrow Lift (s) ; ((loc s_1 \bullet A_1) \boxplus (loc s_2 \bullet A_2)) \sqsubseteq (Lift (s_3) ; 1 \rightarrow A_3) \square (Lift (s) ; ((loc s_1 \bullet A_1) \boxplus (loc s_2 \bullet A_2)))

= [w is universally quantified, so we abstract it]

c \land c_3 \Rightarrow Lift (s) ; ((loc s_1 \bullet A_1) \boxplus (loc s_2 \bullet A_2)) \sqsubseteq (Lift (s_3) ; 1 \rightarrow A_3) \square (Lift (s) ; ((loc s_1 \bullet A_1) \boxplus (loc s_2 \bullet A_2)))

= [Definition of Extra Choice B.30]

c \land c_3 \Rightarrow Lift (s) ; ((loc s_1 \bullet A_1) \square (loc s_2 \bullet A_2)) \sqsubseteq (Lift (s_3) ; 1 \rightarrow A_3) \square (Lift (s) ; ((loc s_1 \bullet A_1) \square (loc s_2 \bullet A_2)))

= [Definition of Loc B.29]

c \land c_3 \Rightarrow Lift (s) ; ((loc s_1 \bullet A_1) \square (loc s_2 \bullet A_2)) \sqsubseteq (Lift (s_3) ; 1 \rightarrow A_3) \square (Lift (s) ; ((Lift (s_1) ; A_1) \square (Lift (s) ; ((Lift (s_1) ; A_1) \square (Lift (s_2) ; A_2))))
```
```
= [Lift External Choice B.2.28]
c \land c_3 \Rightarrow \text{Lift}(s); ((loc s_1 \bullet A_1) \Box (loc s_2 \bullet A_2)) \sqsubseteq (Lift (s_3); l \rightarrow A_3) \Box (Lift (s); Lift
(s_1); A_1) \Box (Lift (s); Lift (s_2); A_2)))
= [Lift Left Unit B.2.29]
c \wedge c_3 \Rightarrow \text{Lift}(s); ((\text{loc } s_1 \bullet A_1) \Box (\text{loc } s_2 \bullet A_2)) \sqsubseteq (\text{Lift}(s_3); l \rightarrow A_3) \Box (\text{Lift}(s_1); A_1)
\Box (Lift (s<sub>2</sub>) ; A<sub>2</sub>)))
= [Assumption]
c \land c_3 \Rightarrow \text{Lift}(s); ((\text{loc } s_1 \bullet A_1) \Box ((\text{loc } s_2 \bullet A_2)) \sqsubseteq (\text{Lift}(s_1); A_1) \Box ((\text{Lift}(s_2); A_2)))
= [Lift Left Unit B.2.29]
c \wedge c_3 \Rightarrow \text{Lift}(s); ((loc s_1 \bullet A_1) \Box (loc s_2 \bullet A_2)) \sqsubseteq (Lift (s); Lift (s_1); A_1) \Box (Lift (s);
Lift (s_2); A<sub>2</sub>)))
= [Lift External Choice B.2.28]
c \land c_3 \Rightarrow Lift(s); ((loc s_1 \bullet A_1) \Box (loc s_2 \bullet A_2)) \sqsubseteq (Lift(s); (Lift(s_1); A_1) \Box Lift(s_2);
A<sub>2</sub>)
= [Definition of Loc B.29]
c \land c_3 \Rightarrow \text{Lift}(s); ((\text{loc } s_1 \bullet A_1) \Box (\text{loc } s_2 \bullet A_2)) \sqsubseteq (\text{Lift}(s); (\text{loc } s_1 \bullet A_1) \Box (\text{loc } s_2 \bullet A_2))
= [Definition of Extra Choice B.30]
c \land c_3 \Rightarrow \text{Lift}(s); ((\text{loc } s_1 \bullet A_1) \Box (\text{loc } s_2 \bullet A_2)) \sqsubseteq (\text{Lift}(s); (\text{loc } s_1 \bullet A_1) \boxplus \text{loc } s_2 \bullet A_2)
= [Refinement Equal Sides 1]
c \wedge c_3 \Rightarrow true
= [Predicate Calculus]
= true
Attached Rule 15.
```

External Choice Silent Left:

$$\frac{(c_1 \mid s_1 \models A_1) \xrightarrow{\tau} (c_3 \mid s_3 \models A_3)}{(c \mid s \models loc \ s_1 \bullet A_1 \boxplus loc \ s_2 \bullet A_2) \xrightarrow{\tau} (c \mid s \models loc \ s_3 \bullet A_3 \boxplus loc \ s_2 \bullet A_2)}$$

 $(c1 | s \models (loc s1 \bullet A1) \boxplus (loc s2 \bullet A2))$ $\xrightarrow{\tau}$ $(c2 | s \models (loc s3 \bullet A3) \boxplus (loc s2 \bullet A2))$ = [loc definition B.29] $(c1 | s \models (Lift (s1); A1) \boxplus (Lift (s2); A2))$ $\xrightarrow{\tau}$ $(c2 | s \models (Lift (s3); A3) \boxplus (Lift (s2); A2))$

```
= [Extra choice definition B.30]

(c1 | s \models (Lift (s1); A1 ) \Box (Lift (s2); A2 ))

\xrightarrow{\tau}

(c2 | s \models (Lift (s3); A3 ) \Box (Lift (s2); A2 ))

= [Definition of Silent Transition B.25]

\forall w . c1 \land c2 \Rightarrow (Lift (s1); A1) \Box (Lift (s2); A2 )) \sqsubseteq (Lift (s3); A3) \Box (Lift (s2); A2)

= [w is universally quantified, so we abstract it]

c1 \land c2 \Rightarrow (Lift (s1); A1) \Box (Lift (s2); A2 )) \sqsubseteq (Lift (s3); A3) \Box (Lift (s2); A2)

[Assumpt. (Lift (s1); A1) \Box (Lift (s3); A3) + Ref.Eq.Sides (1)]

c1 \land c2 \Rightarrow true

= [Predicate Calculus]

true
```

Attached Rule 16.

```
External Choice Silent Right:
```

```
\frac{(c_2 \mid s_2 \models A_2) \xrightarrow{\tau} (c_3 \mid s_3 \models A_3)}{(c \mid s \models loc \ s_1 \bullet A_1 \boxplus loc \ s_2 \bullet A_2) \xrightarrow{\tau} (c \mid s \models loc \ s_1 \bullet A_1 \boxplus loc \ s_3 \bullet A_3)}
```

```
(c1 | s \models (loc s1 \bullet A1) \boxplus (loc s2 \bullet A2))
\xrightarrow{\tau}
(c2 | s \models (loc s1 \bullet A1) \boxplus (loc s3 \bullet A3))
= [loc definition B.29]
(c1 | s \models (Lift (s1); A1) \boxplus (Lift (s2); A2))
\xrightarrow{\tau}
(c2 | s \models (Lift (s1); A1) \boxplus (Lift (s3); A3))
= [Extra choice definition B.30]
(c1 | s \models (Lift (s1); A1) \Box (Lift (s2); A2))
\xrightarrow{\tau}
(c2 | s \models (Lift (s1); A1) \square (Lift (s3); A3))
= [Definition of Silent Transition B.25]
\forallw. c2 \land c2 \Rightarrow (Lift (s1); A1 ) \Box (Lift (s2); A2 )) \sqsubseteq (Lift (s1); A1 ) \Box (Lift (s3); A3 )
= [w is universally quantified, so we abstract it]
c2 \land c2 \Rightarrow (Lift (s1); A1) \Box (Lift (s2); A2)) \sqsubseteq (Lift (s1); A1) \Box (Lift (s3); A3)
= [Lift (s2); A2 \square Lift (s3); A3 (this is the assumption) + Refinement Equal Sides 1]
c1 \wedge c2 \Rightarrow true
```

= [Predicate Calculus] true

B.3.8 Parallelism*

Attached Rule 17.

Parallel Begin*:

 $(c \mid s \models A_1 \parallel s_1 \mid cs \mid s_2 \parallel A_2)$ $\stackrel{\tau}{\rightarrow}$ $(c \mid s \models (loc (s \mid x_1)_{+x2} \bullet A_1) \parallel x_1 \mid cs \mid x_2 \parallel (loc (s \mid x_2)_{+x1} \bullet A_2))$

Proof

```
\begin{array}{l} (c \mid s \models A_1 \parallel s_1 \mid cs \mid s_2 \parallel A_2) \\ \stackrel{\tau}{\rightarrow} \\ (c \mid s \models (\operatorname{loc} (s \mid x_1)_{+x2} \bullet A_1) \parallel x_1 \mid cs \mid x_2 \parallel (\operatorname{loc} (s \mid x_2)_{+x1} \bullet A_2)) \end{array}
```

= [Definition of Silent Transition **B.25**]

 $\begin{array}{l} \forall \ w \ . \ c \Rightarrow Lift \ (s) \ ; \ A_1 \ \| \ s_1 \ | \ cs \ | \ s_2 \ \| \ A_2 \sqsubseteq Lift \ (s) \ ; \ (loc \ (s \ | \ x_1)_{+x2} \bullet A_1) \ \| \ x_1 \ | \ cs \ | \ x_2 \ \| \\ (loc \ (s \ | \ x_2)_{+x1} \bullet A_2 \end{array}$

The proof from now on will consist on proving that the RHS of the refinement is equal to the LHS.

RHS =

Lift (s) ; (loc (s | x_1)_{+ x_2} • A₁) $[[x_1 | cs | x_2]]$ (loc (s | x_2)_{+ x_1} • A₂ = [Definition of Loc B.29] Lift (s) ; (Lift (s | x_1)_{+ x_2} ; A₁) $[[x_1 | cs | x_2]]$ (Lift (s | x_2)_{+ x_1} ; A₂ = [Parallel Distributivity B.2.37] Lift (s) ; (Lift (s | x_1)_{+ x_2} ; A₁) $[[x_1 | cs | x_2]]$ Lift (s) ; (Lift (s | x_2)_{+ x_1} ; A₂ = [Lift Composition (twice)B.2.27] Lift (s; (s | x_1)_{+ x_2} ; A₁) $[[x_1 | cs | x_2]]$ Lift (s ; (s | x_2)_{+ x_1} ; A₂ = [Lift Semi Idempotence B.2.38] Lift (s) ; A₁) $[[x_1 | cs | x_2]]$ Lift (s₂) ; A₂ = [Lift Parallel Distributivity B.2.37] Lift (s) ; A₁ $[[x_1 | cs | x_2]]$ A₂

= LHS

Attached Rule 18.

Parallel End*:

 $(c \mid s \models (loc \ s_1 \bullet Skip) \| [x_1 \mid cs \mid x_2] \| (loc \ s_2 \bullet Skip)) \xrightarrow{\tau} (c \mid (s_1 \mid x_1) \land (s_2 \mid x_2) \models Skip)$

Proof

 $(c \mid s \models (loc \ s_1 \bullet Skip) \parallel x_1 \mid cs \mid x_2 \parallel (loc \ s_2 \bullet Skip)) \xrightarrow{\tau} (c \mid (s_1 \mid x_1) \land (s_2 \mid x_2) \models Skip)$

= [Definition of Silent Transiton **B.25**] $\forall \mathbf{w} \cdot \mathbf{c} \Rightarrow \begin{pmatrix} Lift(s); \ loc s_1 \bullet Skip \parallel cs \parallel loc s_2 \bullet Skip \\ \sqsubseteq Lift(s); \ (loc(s \mid x_1)_{+x2} \bullet Skip) \parallel x_1 \mid cs \mid x_2 \parallel (loc(s \mid x_2)_{+x1} \bullet Skip) \end{pmatrix}$ The proof from now on will consist on proving that the RHS of the refinement is equal to the LHS. LHS = Lift (s); (loc s₁ \bullet Skip) $\| \mathbf{x}_1 \| cs \| \mathbf{x}_2 \|$ (loc s₂ \bullet Skip) = [Definition of Loc **B.29**] Lift (s); (Lift (s₁); Skip) $||x_1| cs |x_2||$ (Lift (s₂); Skip) = [Parallel Distributivity **B.2.37**] (Lift (s); Lift(s₁); Skip) $||x_1| cs |x_2||$ (Lift (s); Lift(s₂); Skip) = [Lift Left Unit **B.2.29** twice] $(Lift (s_1); Skip) || x_1 | cs | x_2 || (Lift (s_2); Skip)$ = [Lift CSP4 B.2.26 twice] Lift $(s_1) || x_1 | c_2 || x_2 ||$ Lift (s_2) = [Lift Merge **B.2.39**] Lift $(s_1 | x_1 \land s_2 | x_2)$; Skip = RHS

Attached Rule 19.

Parallel Independent Left:

 $\frac{(c_1 \mid s_1 \models A_1) \stackrel{l}{\rightarrow} (c_3 \mid s_3 \models A_3) \quad ((l = \tau) \lor chan(l) \notin cs)}{(c \mid s \models loc \ s_1 \bullet A_1 \mid [x_1 \mid CS \mid x_2 \mid] \ loc \ s_2 \bullet A_2)}$ $\stackrel{l}{\rightarrow} (c \mid s \models loc \ s_3 \bullet A_3 \mid [x_1 \mid CS \mid x_2 \mid] \ loc \ s_2 \bullet A_2)$

Recapitulating the assumptions given on rule 19, they are:

- $(c_1 | s_1 \models A_1) \xrightarrow{l} (c_3 | s_3 \models A_3)$
- $((l = \tau) \lor chan(l) \notin cs)$

Beyond the previous two assumptions, we also provide the following assumptions (in order to apply Parallel Prefixed Loc 8 rule):

- Lift (s1) ; A1 \sqsubseteq Lift (s3) ; 1 \rightarrow A3 \Box Lift (s1) ; A1 [Assumption 3]
- initials (Lift (s2); A2) \subseteq CS [Assumption 4]
- $CS \cap usedC$ (Lift (s3); A3) = \emptyset [Assumption 5]
- wrtV (Lift (s3); A3) \cap usedV (Lift (s2); A2) = \emptyset [Assumption 6]

- Lift (s2); A2 is divergence free [Assumption 7]
- ok = ok' [Assumption 8]

From assumptions (c | s1 |= A1) \xrightarrow{l} (c3 | s3 |= A3) and (l $\neq \tau$)

we apply Labelled Transition Definition and find

 \forall w . c \land c3 \Rightarrow Lift (s1) ; A1 \sqsubseteq Lift (s3) ; A3

Then we consider both c and c3 being true and we find

 \forall w . true \land true \Rightarrow Lift (s1) ; A1 \sqsubseteq Lift (s3) ; A3

then we apply Predicate Calculus twice and find

Lift (s1); A1 \sqsubseteq Lift (s3); A3

For the case where c or c3 is false, we have a false assumption and then it makes the expression directly true ((false \Rightarrow Rule) = true).

Proof

As there is an \lor operator between factor $l = \tau$ and factor chan (l) \notin CS, the proof must be done to both cases:

For $l = \tau$:

 $\begin{array}{l} (c \mid s \models \log s_1 \bullet A_1 \mid [x_1 \mid CS \mid x_2 \mid] \log s_2 \bullet A_2) \\ \stackrel{l}{\rightarrow} (c3 \mid s \models \log s_3 \bullet A_3 \mid [x_1 \mid CS \mid x_2 \mid] \log s_2 \bullet A_2) \\ = [Definition of Silent Transition B.25 (as l = <math>\tau$, the transition is silent)] $\forall w . c \land c3 \Rightarrow \\ \text{Lift } (s) ; (\log s1 \bullet A1) \mid [x1 \{ \mid CS \mid \} x2 \mid] (\log s2 \bullet A2) \\ \sqsubseteq \text{Lift } (s) ; (\log s3 \bullet A3) \mid [x1 \mid CS \mid x2 \mid] (\log s2 \bullet A2) \\ = [w \text{ is universally quantified, so we abstract it throughout the proof]} \\ c \land c3 \Rightarrow \\ \text{Lift } (s) ; (\log s1 \bullet A1) \mid [x1 \{ \mid CS \mid \} x2 \mid] (\log s2 \bullet A2) \\ \sqsubseteq \text{Lift } (s) ; (\log s1 \bullet A1) \mid [x1 \{ \mid CS \mid \} x2 \mid] (\log s2 \bullet A2) \\ \sqsubseteq \text{Lift } (s) ; (\log s3 \bullet A3) \mid [x1 \mid CS \mid x2 \mid] (\log s2 \bullet A2) \\ \sqsubseteq \text{Lift } (s) ; (\log s3 \bullet A3) \mid [x1 \mid CS \mid x2 \mid] (\log s2 \bullet A2) \\ \blacksquare \text{Lift } (s) ; (\log s3 \bullet A3) \mid [x1 \mid CS \mid x2 \mid] (\log s2 \bullet A2) \\ \blacksquare \text{Lift } (s) ; (\log s3 \bullet A3) \mid [x1 \mid CS \mid x2 \mid] (\log s2 \bullet A2) \\ \blacksquare \text{Lift } (s) ; (\log s3 \bullet A3) \mid [x1 \mid CS \mid x2 \mid] (\log s2 \bullet A2) \\ \blacksquare \text{Lift } (s) ; (\log s3 \bullet A3) \mid [x1 \mid CS \mid x2 \mid] (\log s2 \bullet A2) \\ \blacksquare \text{Lift } (s) ; (\log s3 \bullet A3) \mid [x1 \mid CS \mid x2 \mid] (\log s2 \bullet A2) \\ \blacksquare \text{Lift } (s) ; (\log s3 \bullet A3) \mid [x1 \mid CS \mid x2 \mid] (\log s2 \bullet A2) \\ \blacksquare \text{Lift } (s) ; (\log s3 \bullet A3) \mid [x1 \mid CS \mid x2 \mid] (\log s2 \bullet A2) \\ \blacksquare \text{Lift } (s) ; (\log s3 \bullet A3) \mid [x1 \mid CS \mid x2 \mid] (\log s2 \bullet A2) \\ \blacksquare \text{Lift } (s) ; (\log s3 \bullet A3) \mid [x1 \mid CS \mid x2 \mid] (\log s2 \bullet A2) \\ \blacksquare \text{Lift } (s) ; (\log s3 \bullet A3) \mid [x1 \mid CS \mid x2 \mid] (\log s2 \bullet A2) \\ \blacksquare \text{Lift } (s) ; (\log s3 \bullet A3) \mid [x1 \mid CS \mid x2 \mid] (\log s2 \bullet A2) \\ \blacksquare \text{Lift } (s) ; (\log s3 \bullet A3) \mid [x1 \mid CS \mid x2 \mid] (\log s2 \bullet A2) \\ \blacksquare \text{Lift } (s) ; (\log s3 \bullet A3) \mid [x1 \mid CS \mid x2 \mid] (\log s2 \bullet A2) \\ \blacksquare \text{Lift } (s) ; (\log s3 \bullet A3) \mid [x1 \mid CS \mid x2 \mid] (\log s2 \bullet A2) \\ \blacksquare \text{Lift } (s) ; (\log s3 \bullet A3) \mid [x1 \mid CS \mid x2 \mid] (\log s2 \bullet A2) \\ \blacksquare \text{Lift } (s) ; (\log s3 \bullet A3) \mid [x1 \mid CS \mid x2 \mid] (\log s2 \bullet A2) \\ \blacksquare \text{Lift } (s) ; (\log s3 \bullet A3) \mid [x1 \mid CS \mid x2 \mid] (\log s2 \bullet A2) \\ \blacksquare \text{Lift } (s) ; (\log s3 \bullet A3) \mid [x1 \mid CS \mid x2 \mid] (\log s3 \bullet A3) \\ \blacksquare (s) : (\log$ = [Par.Ind.Ref.9 (providing Assumpt.1 from the rule)+Ref.Eq.Sides 1+Ref.Mon.6] true

 $\label{eq:constraint} \frac{\text{For chan (l)} \notin CS \text{ , } l \neq \tau \text{ and } c \text{ and } c3 \text{ are true}}{(\text{when at least some of them is false the whole expression is true}):}$

$$\begin{aligned} (c \mid s \models \log s_1 \bullet A_1 || x_1 \mid CS \mid x_2 || \log s_2 \bullet A_2) \\ \xrightarrow{l} (c3 \mid s \models \log s_3 \bullet A_3 || x_1 \mid CS \mid x_2 || \log s_2 \bullet A_2) \\ = [Definition of Labelled Transition B.26 (as $l \neq \tau$, the transition is labelled)]
 $\forall w. c \wedge c3 \Rightarrow$

$$\begin{cases} Lift(s); locs_1 \bullet A_1 || x_1 \mid CS \mid x_2 || locs_2 \bullet A_2 \\ & \Box \\ (Lift(s); locs_1 \bullet A_1 || x_1 \mid CS \mid x_2 || locs_2 \bullet A_2 \\ & \Box \\ (Lift(s); locs_1 \bullet A_1 || x_1 \mid CS \mid x_2 || locs_2 \bullet A_2 \\ & \Box \\ (Lift(s); locs_1 \bullet A_1 || x_1 \mid CS \mid x_2 || locs_2 \bullet A_2 \\ & \Box \\ (Lift(s); locs_1 \bullet A_1 || x_1 \mid CS \mid x_2 || locs_2 \bullet A_2 \\ & \Box \\ (Lift(s); locs_1 \bullet A_1 || x_1 \mid CS \mid x_2 || locs_2 \bullet A_2 \\ & \Box \\ (Lift(s); locs_1 \bullet A_1 || x_1 \mid CS \mid x_2 || locs_2 \bullet A_2 \\ & \Box \\ (Lift(s); locs_1 \bullet A_1 || x_1 \mid CS \mid x_2 || locs_2 \bullet A_2 \\ & \Box \\ (Lift(s); locs_1 \bullet A_1 || x_1 \mid CS \mid x_2 || locs_2 \bullet A_2 \\ & \Box \\ (Lift(s); locs_1 \bullet A_1 || x_1 \mid CS \mid x_2 || locs_2 \bullet A_2 \\ & \Box \\ (Lift(s); locs_1 \bullet A_1 || x_1 \mid CS \mid x_2 || locs_2 \bullet A_2 \\ & \Box \\ (Lift(s); locs_1 \bullet A_1 || x_1 \mid CS \mid x_2 || locs_2 \bullet A_2 \\ & \Box \\ (Lift(s); locs_1 \bullet A_1 || x_1 \mid CS \mid x_2 || locs_2 \bullet A_2 \\ & \Box \\ (Lift(s); locs_1 \bullet A_1 || x_1 \mid CS \mid x_2 || locs_2 \bullet A_2 \\ & \Box \\ (Lift(s); locs_1 \bullet A_1 || x_1 \mid CS \mid x_2 || locs_2 \bullet A_2 \\ & \Box \\ (Lift(s); locs_1 \bullet A_1 || x_1 \mid CS \mid x_2 || locs_2 \bullet A_2 \\ & \Box \\ (Lift(s); locs_1 \bullet A_1 || x_1 \mid CS \mid x_2 || locs_2 \bullet A_2 \\ & \Box \\ (Lift(s); locs_1 \bullet A_1 || x_1 \mid CS \mid x_2 || locs_2 \bullet A_2 \\ & \Box \\ (Lift(s); locs_1 \bullet A_1 || x_1 \mid CS \mid x_2 || locs_2 \bullet A_2 \\ & \Box \\ (Lift(s); locs_1 \bullet A_1 || x_1 \mid CS \mid x_2 || locs_2 \bullet A_2 \\ & \Box \\ (Lift(s); locs_1 \bullet A_1 || x_1 \mid CS \mid x_2 || locs_2 \bullet A_2 \\ & \Box \\ (Lift(s); locs_1 \bullet A_1 || x_1 \mid CS \mid x_2 || locs_2 \bullet A_2 \\ & \Box \\ (Lift(s); locs_1 \bullet A_1 || x_1 \mid CS \mid x_2 || locs_2 \bullet A_2 \\ & \Box \\ (Lift(s); locs_1 \bullet A_1 || x_1 \mid CS \mid x_2 || locs_2 \bullet A_2 \\ & \Box \\ (Lift(s); l \to locs_3 \bullet A_3 || x_1 \mid CS \mid x_2 || locs_2 \bullet A_2 \\ & \Box \\ (Lift(s); l \to locs_3 \bullet A_3 || x_1 \mid CS \mid x_2 || locs_2 \bullet A_2 \\ & \Box \\ (Lift(s); l \to locs_3 \bullet A_3 || x_1 \mid CS \mid x_2 || locs_2 \bullet A_2 \\ & \Box \\ (Lift(s); l \to locs_3 \bullet A_3 || x_1 \mid CS \mid x_2 ||$$$$

true □

Attached Rule 20.

Parallel Independent Right:

 $\frac{(c_2 \mid s_2 \models A_2) \xrightarrow{l} (c_3 \mid s_3 \models A_3) ((l = \tau) \lor chan(l) \notin cs)}{(c \mid s \models loc s_1 \bullet A_1 || x_1 \mid CS \mid x_2 || loc s_2 \bullet A_2)}$ $\xrightarrow{l} (c \mid s \models loc s_1 \bullet A_1 || x_1 \mid CS \mid x_2 || loc s_3 \bullet A_3)$

Recapitulating the previous assumptions:

- $(c_2 | s_2 \models A_2) \xrightarrow{l} (c_3 | s_3 \models A_3)$ [Assumption 1]
- $(l = \tau) \lor chan(l) \notin cs$ [Assumption 2]

Beyond the previous two assumptions, we also provide the following assumptions (in order to apply Parallel Prefixed Loc 8 rule):

- Lift (s2) ; A2 \sqsubseteq Lift (s3) ; 1 \rightarrow A3 \square Lift (s2) ; A2 [Assumption 3]
- initials (Lift (s1); A1) \subseteq CS [Assumption 4]
- CS \cap usedC (Lift (s3); A3) = \emptyset [Assumption 5]
- wrtV (Lift (s3); A3) \cap usedV (Lift (s1); A1) = \emptyset [Assumption 6]
- Lift (s1); A1 is divergence free [Assumption 7]
- ok = ok' [Assumption 8]

Proof

```
(c \mid s \models loc s_1 \bullet A_1 || x_1 \mid CS \mid x_2 || loc s_2 \bullet A_2)
\stackrel{l}{\rightarrow} (c \mid s \models loc s_1 \bullet A_1 || x_1 \mid CS \mid x_2 || loc s_3 \bullet A_3)
= [Compound Actions Commutative B.2.6]
(c \mid s \models loc s_2 \bullet A_2 || x_2 \mid CS \mid x_1 || loc s_1 \bullet A_1)
\stackrel{l}{\rightarrow} (c \mid s \models loc s_1 \bullet A_1 || x_1 \mid CS \mid x_2 || loc s_3 \bullet A_3)
= [Compound Actions Commutative B.2.6]
(c \mid s \models loc s_2 \bullet A_2 || x_2 \mid CS \mid x_1 || loc s_1 \bullet A_1)
\stackrel{l}{\rightarrow} (c \mid s \models loc s_3 \bullet A_3 || x_3 \mid CS \mid x_1 || loc s_1 \bullet A_1)
\stackrel{l}{\rightarrow} (c \mid s \models loc s_3 \bullet A_3 || x_3 \mid CS \mid x_1 || loc s_1 \bullet A_1)
= [Parallel Independent Left 19 (having assumptions 2-12)]
true
```

Attached Rule 21.

Parallel Synchronised:

 $d \in cs c_1 c_2 c_3 c_4 (w_1 = w_2)$ $(^*,\diamond) \in (?, !), (!, ?), (!, !), (., .), (?, ?)$ $(c_1 \mid s_1 \models A_1) \xrightarrow{d^* w_1} (c_3 \mid s_3 \models A_3)$ $\frac{(c_2 \mid s_2 \models A_2) \xrightarrow{d \diamond w_2} (c_4 \mid s_4 \models A_4)}{(c_1 \land c_2 \mid s \models (c_1 \mid loc \ s_1 \bullet A_1) \parallel [x_1 \mid cs \mid x_2 \parallel (c_2 \mid loc \ s_2 \bullet A_2))}$ $d|w_2 \rightarrow$ $\left(\begin{array}{c}c_{3}\wedge c_{4}\wedge w_{1}=w_{2}\mid s\models\\ \left(\begin{array}{c}c_{3}\wedge (w_{1}=w_{2})\mid locs_{3}\bullet A_{3})\\ |[x_{1}\mid cs\mid x_{2}]|\\ (c_{4}\wedge (w_{1}=w_{2})\mid locs_{4}\bullet A_{4})\end{array}\right)\end{array}\right)$

Recapitulating the previous assumptions:

- $d \in cs, c_1, c_2, c_3, c_4$ [Assumptions 1, 2, 3, 4 and 5]
- $w_1 = w_2$ [Assumption 6]
- (*,◊) ∈ (?, !), (!, ?), (!, !), (., .), (?, ?) [Assumption 7]
- $(c_1 | s_1 \models A_1) \xrightarrow{d^*w_1} (c_3 | s_3 \models A_3)$ [Assumption 8] $(c_2 | s_2 \models A_2) \xrightarrow{d \diamond w_2} (c_4 | s_4 \models A_4)$ [Assumption 9]

We also provide the following assumption in order to allow the proof using Lift Shift 7:

• 3.ok = 3.ok' and 4.ok = 4.ok' [Assumption 10] (3 and 4 are labels for some branches of the parallelism, such that i is the label for branch Lift (s_i) ; $d \rightarrow A_i$);

And now we derive other assumptions from Assumption 8 and Assumption 9, called compldw1 and compldw2:

[Assumption 8]

= [Labelled Transition Implication B.17]

 \forall w. c₁ \land c₃ \Rightarrow (Lift (s₁); A₁) \sqsubseteq (Lift (s₃); d*w₁ \rightarrow A₃) [Assumption compldw1]

= w is unviversally quantified, so we abstract it]

 $c_1 \land c_3 \Rightarrow (\text{Lift}(s_1); A_1) \sqsubseteq (\text{Lift}(s_3); d^*w_1 \rightarrow A_3)$ [Assumption compldw1] [Assumption 9]

= [Labelled Transition Implication B.17]

 $c_1 \wedge c_3 \Rightarrow$ (Lift (s₁); A₁) \sqsubset (Lift (s₃); d*w₁ \rightarrow A₃) [Assumption compldw2] Now we will start proving.

Proof

$$\begin{aligned} & (c_1 \land c_2 \mid s \models (c_1 \mid loc s_1 \bullet A_1) \mid [x_1 \mid cs \mid x_2 \mid] (c_2 \mid loc s_2 \bullet A_2)) \\ & \xrightarrow{d|w_2} \\ & (c_3 \land c_4 \land w_1 = w_2 \mid s \models ((loc s_3 \bullet A_3) \mid [x_1 \mid cs \mid x_2 \mid] (loc s_4 \bullet A_4))) \\ &= [Definition of Labelled Transition] \\ & \forall w \cdot c_1 \land c_2 \land c_3 \land c_4 \land w_1 = w_2 \Rightarrow \\ & \left(\begin{array}{c} (Lift(s); (locs_1 \bullet A_1) \mid [x_1 \mid cs \mid x_2 \mid] (c_2 \mid locs_2 \bullet A_2)) \\ & \Box \\ & (Lift(s); (locs_1 \bullet A_1) \mid [x_1 \mid cs \mid x_2 \mid] (c_2 \mid locs_4 \bullet A_4))) \\ & \Box \\ & (Lift(s); (locs_1 \bullet A_1) \mid [x_1 \mid cs \mid x_2 \mid] (c_2 \mid locs_2 \bullet A_2)) \\ & = [w \text{ is universally quantified, so we abstract it]} \\ & c_1 \land c_2 \land c_3 \land c_4 \land w_1 = w_2 \Rightarrow \\ & \left(\begin{array}{c} (Lift(s); (locs_1 \bullet A_1) \mid [x_1 \mid cs \mid x_2 \mid] (c_2 \mid locs_2 \bullet A_2)) \\ & \Box \\ & (Lift(s); (locs_1 \bullet A_1) \mid [x_1 \mid cs \mid x_2 \mid] (c_2 \mid locs_4 \bullet A_4))) \\ & \Box \\ & (Lift(s); (locs_1 \bullet A_1) \mid [x_1 \mid cs \mid x_2 \mid] (c_2 \mid locs_2 \bullet A_2)) \\ & \Box \\ & (Lift(s); (locs_1 \bullet A_1) \mid [x_1 \mid cs \mid x_2 \mid] (c_2 \mid locs_2 \bullet A_2)) \\ & = [Communication Parallelism Distribution B.2.7 (having that {d} \in CS, as it is Par. \\ & Synchronised)] \\ & c_1 \land c_2 \land c_3 \land c_4 \land w_1 = w_2 \Rightarrow \\ & \left((Lift(s); (locs_1 \bullet A_1) \mid [x_1 \mid cs \mid x_2 \mid] (c_2 \mid locs_2 \bullet A_2)) \\ & \Box \\ & \left((Lift(s); (locs_1 \bullet A_1) \mid [x_1 \mid cs \mid x_2 \mid] (c_2 \mid locs_2 \bullet A_2)) \\ & \Box \\ & \left((Lift(s); (locs_1 \bullet A_1) \mid [x_1 \mid cs \mid x_2 \mid] (c_2 \mid locs_2 \bullet A_2)) \\ & \Box \\ & \end{array} \right) \end{aligned}$$

$$\begin{bmatrix} \Box \\ (Lift(s); (d \mid w_2 \rightarrow (locs_3 \bullet A_3) \parallel [x_1 \mid cs \mid x_2] \mid d \mid w_2 \rightarrow (locs_4 \bullet A_4))) \\ \Box \\ (Lift(s); (locs_1 \bullet A_1) \parallel [x_1 \mid cs \mid x_2] \mid (c_2 \mid locs_2 \bullet A_2)) \end{bmatrix} =$$
[Definition of Loc B.29 6x]

$$c_{1} \wedge c_{2} \wedge c_{3} \wedge c_{4} \wedge w_{1} = w_{2} \Rightarrow \begin{pmatrix} (Lift(s); (Lift(s_{1}); A_{1}) ||x_{1}| cs | x_{2}]| (c_{2} | Lift(s_{2}); A_{2})) \\ \Box \\ (Lift(s); (d | w_{2} \rightarrow (Lift(s_{3}); A_{3}) ||x_{1}| cs | x_{2}]| d | w_{2} \rightarrow (Lift(s_{4}); A_{4}))) \\ \Box \\ (Lift(s); (Lift(s_{1}); A_{1}) ||x_{1}| cs | x_{2}]| (c_{2} | Lift(s_{2}); A_{2})) \\ = [Lift Shift 7 (having assumption 10)] \end{cases}$$

 $c_1 \wedge c_2 \wedge c_3 \wedge c_4 \wedge w_1 = w_2 \Rightarrow$

$$\begin{pmatrix} (Lift(s); (Lift(s_1); A_1) ||x_1 | cs | x_2]| (c_2 | Lift(s_2); A_2)) \\ & \sqsubseteq \\ \begin{pmatrix} (Lift(s); ((Lift(s_3); d | w_2 \to A_3) ||x_1 | cs | x_2]| (Lift(s_4); d | w_2 \to A_4))) \\ & \square \\ (Lift(s); (Lift(s_1); A_1) ||x_1 | cs | x_2]| (c_2 | Lift(s_2); A_2)) \end{pmatrix} \end{pmatrix}$$

= [If $w_1 \neq w_2$, the antecedent is false, thus the whole expression is true. If $w_1 = w_2$ is true, w_2 can be replaced by w_1]

$$c_{1} \wedge c_{2} \wedge c_{3} \wedge c_{4} \wedge w_{1} = w_{2} \Rightarrow$$

$$\begin{pmatrix} (Lift(s); (Lift(s_{1}); A_{1}) ||x_{1}| cs | x_{2}]| (c_{2} | Lift(s_{2}); A_{2})) \\ \Box \\ (Lift(s); ((Lift(s_{3}); d | w_{1} \rightarrow A_{3}) ||x_{1}| cs | x_{2}]| (Lift(s_{4}); d | w_{2} \rightarrow A_{4}))) \\ \Box \\ (Lift(s); (Lift(s_{1}); A_{1}) ||x_{1}| cs | x_{2}]| (c_{2} | Lift(s_{2}); A_{2})) \end{pmatrix} \end{pmatrix}$$

$$= [External Choice Refinement Implication 15]$$

$$\begin{array}{l} \mathbf{c}_{1} \wedge \mathbf{c}_{2} \wedge \mathbf{c}_{3} \wedge \mathbf{c}_{4} \wedge \mathbf{w}_{1} = \mathbf{w}_{2} \Rightarrow \\ \left(\begin{array}{c} (Lift(s); \ (Lift(s_{1}); A_{1}) \| [x_{1} \mid cs \mid x_{2}] \| (c_{2} \mid Lift(s_{2}); A_{2})) \\ \Box \\ \left((Lift(s); \ ((Lift(s_{3}); d \mid w_{1} \rightarrow A_{3}) \| [x_{1} \mid cs \mid x_{2}] | (Lift(s_{4}); d \mid w_{2} \rightarrow A_{4}))) \end{array}\right) \\ \end{array} \right) \\ = [Assumptions \ \mathbf{complw1} \ \mathbf{and} \ \mathbf{complw2} \ \mathbf{with} \ \mathbf{Monotonicity} \ \mathbf{of} \ \mathbf{Refinement} \ \mathbf{for} \ \mathbf{Paral-} \end{array}$$

lelism B.2.21]

$$\begin{split} & c_1 \wedge c_2 \wedge c_3 \wedge c_4 \wedge w_1 = w_2 \Rightarrow true \\ & = [\text{Predicate Calculus}] \\ & true \end{split}$$

B.3.9 Hiding

Attached Rule 22.

Hiding Internal: $\frac{(c1 | s1 \models A) \xrightarrow{l} (c2 | s2 \models B) \quad l \in S}{(c1 | s1 \models A \setminus S) \xrightarrow{\tau} (c2 | s2 \models B \setminus S)}$

For proving the above rule, we will also assume that $(A \setminus S)$ and $(B \setminus S)$ are divergence-free (ok and ok'), and we will call this assumption as **[Assumption Div]**.

On the rule, as it has a labelled transition from program text A to program text B, then $A = 1 \rightarrow B$ [We will call it Assumption 3].

```
[Assumption 1]
(c1 | s1 \models A) \xrightarrow{l} (c2 | s2 \models B)
= [Definition of Labelled Transition B.26]
\forallw. c1 \land c2 \Rightarrow Lift (s1) ; A \sqsubseteq (Lift (s2) ; 1 \rightarrow B) \Box Lift (s1) ; A
= [w is universally quantified, so we abstract it]
c1 \land c2 \Rightarrow Lift(s1); A \sqsubseteq (Lift(s2); 1 \rightarrow B) \Box Lift(s1); A
= [External Choice Refinement Implication 15]
c1 \land c2 \Rightarrow Lift(s1); A \sqsubseteq (Lift(s2); 1 \rightarrow B)
= [For c1 and c2 being true, we have as follows (if either c1 or c2 is false, the an-
tecedent is false, thus the whole expression is true)]
true \Rightarrow Lift (s1); A \square (Lift (s2); l \rightarrow B)
= [Predicate Calculus]
Lift (s1); A \sqsubset (Lift (s2); l \rightarrow B)
= [Assumption 3]
Lift (s1); l \rightarrow B \sqsubset (Lift (s2); l \rightarrow B)
\Rightarrow [Hiding Monotonic B.2.9]
(\text{Lift } (s1); l \rightarrow B) \setminus S \sqsubseteq (\text{Lift } (s2); l \rightarrow B) \setminus S
= [Sequence Skip B.2.2]
(Lift (s1); l \rightarrow Skip; B) \ S \sqsubseteq (Lift (s2); l \rightarrow Skip; B) \ S
= [Hidden Event Sequenced By Skip 16 (having ok and ok' from Assumption Div)]
(Lift (s1); Skip; B) \setminus S \sqsubset (Lift (s2); Skip; B) \setminus S
= [Sequence Skip B.2.2]
```

 $(Lift (s1); B) \setminus S \sqsubseteq (Lift (s2); B) \setminus S [Assumption 4]$

Expression to be proved:

 $\forall w . c1 \land c2 \Rightarrow Lift (s1) ; A \setminus S \sqsubseteq Lift (s2) ; B \setminus S$

Proof

```
(c1 | s1 \models A \setminus S) \xrightarrow{\tau} (c2 | s2 \models B \setminus S)
= [Definition of Silent Transition B.25]
\forallw. c1 \land c2 \Rightarrow Lift (s1) ; A \setminus S \sqsubseteq Lift (s2) ; B \setminus S
= [w is universally quantified, so we abstract it]
c1 \wedge c2 \Rightarrow Lift(s1); A \setminus S \Box Lift(s2); B \setminus S
= [By Assumption 3]
c1 \wedge c2 \Rightarrow (Lift (s1); (1 \rightarrow B)) \setminus S \sqsubseteq (Lift (s2); B) \setminus S
= [Hiding Sequence Distributive B.2.12]
c1 \land c2 \Rightarrow (Lift (s1) ; (l \rightarrow B)) \setminus S \sqsubseteq (Lift (s2) ; B) \setminus S
= [Skip A Equals A B.2.2]
c1 \land c2 \Rightarrow (Lift (s1); (l \rightarrow Skip; B)) \setminus S \sqsubseteq (Lift (s2); B) \setminus S
= [Hiding Sequence Distributive B.2.12]
c1 \land c2 \Rightarrow (Lift (s1); ((l \rightarrow Skip) \setminus S; B \setminus S)) \Box (Lift (s2); B) \setminus S
= [Hidden Event Sequenced by Skip 16]
c1 \land c2 \Rightarrow (Lift (s1); (Skip; B \setminus S)) \sqsubseteq (Lift (s2); B) \setminus S
= [Skip A Equals A B.2.2]
c1 \land c2 \Rightarrow (Lift (s1); (B \setminus S)) \sqsubseteq (Lift (s2); B) \setminus S
= [Hiding Identity B.2.8 (as Lift (s1) is a sequence of assignments, it does not contain
any channel)]
c1 \land c2 \Rightarrow (Lift (s1) \setminus S; (B \setminus S)) \sqsubseteq (Lift (s2); B) \setminus S
= [Assume c1 \wedge c2 from now on (when c1 \wedge c2 is false, then the whole expression is
true)]
(\text{Lift } (s1) \setminus S ; (B \setminus S)) \sqsubseteq (\text{Lift } (s2) ; B) \setminus S
= [Hiding Sequence Distributive B.2.12]
```

```
(\text{Lift}(s1); B) \setminus S \sqsubseteq (\text{Lift}(s2); B) \setminus S
```

```
= [Assumption 4]
```

true

Attached Rule 23.

Hiding Visible:

$$\frac{(c1 \mid s1 \models A) \stackrel{l}{\rightarrow} (c2 \mid s2 \models B) \qquad l \notin S}{(c1 \mid s1 \models A \setminus S) \stackrel{l}{\rightarrow} (c2 \mid s2 \models B \setminus S)}$$

Expression to be proved:

```
\forall w. c1 \land c2 \Rightarrow Lift (s1); A \land S \sqsubseteq (Lift (s2); c.w1 \rightarrow B \land S) \Box Lift (s1); A \land S
Proof
\forall w . c1 \land c2 \Rightarrow
Lift (s1); A \setminus S \sqsubseteq (Lift (s2); c.w1 \rightarrow B \setminus S) \Box Lift (s1); A \setminus S
= [w is universally quantified, so we abstract it]
c1 \wedge c2 \Rightarrow
Lift (s1); A \setminus S \sqsubseteq (Lift (s2); c.w1 \rightarrow B \setminus S) \Box Lift (s1); A \setminus S
= [No channels are used on Lift (s), so Lift (s) = Lift (s) \setminus S]
c1 \wedge c2 \Rightarrow
Lift (s1) \setminus S ; A \setminus S \sqsubseteq (Lift (s2) \setminus S ; c.w1 \rightarrow B \setminus S) \Box Lift (s1) \setminus S ; A \setminus S
= [Hiding Sequence Distributive B.2.12]
c1 \wedge c2 \Rightarrow
(Lift (s1); A) \setminus S \sqsubset ((Lift (s2); c.w1 \rightarrow B) \setminus S) \Box (Lift (s1); A) \setminus S
= [Hiding External Choice Distributive B.2.10]
c1 \wedge c2 \Rightarrow
(Lift (s1); A) \setminus S \sqsubseteq ((Lift (s2); c.w1 \rightarrow B) \Box (Lift (s1); A)) \setminus S
= [Assumption and Hiding Monotonic B.2.9]
c1 \wedge c2 \Rightarrow true
= [Predicate Calculus]
true
```

Attached Rule 24.

Hiding Skip: $(c \mid s \models Skip \setminus S) \xrightarrow{\tau} (c \mid s \models Skip)$

Proof We start this proof by infering an assumption from function UsedC (B.12): (UsedC (Skip) = { }) \Rightarrow (New Assumption) (S \cap UsedC (Skip) = { }) Now we will continue the proof: (c | s \models Skip \setminus S) $\xrightarrow{\tau}$ (c | s \models Skip) = [From New Assumption and Law B.2.8]

 $(c | s \models Skip) \xrightarrow{\tau} (c | s \models Skip)$ = [Silent Transition between Equivalent nodes 2] true

B.3.10 Recursion

Attached Rule 25.

Recursion: $\frac{(c \mid s \models A) \xrightarrow{\tau} (c \mid s \models B) N = A}{(c \mid s \models N) \xrightarrow{\tau} (c \mid s \models B)}$

Proof The proof for Recursion is straightforward. We only apply the assumption N = A and then the other assumption to prove:

 $(c | s \models N) \xrightarrow{\tau} (c | s \models B)$ = [Assumption N = A] $(c | s \models A) \xrightarrow{\tau} (c | s \models B)$ = [Assumption (c | s ⊨ A) $\xrightarrow{\tau} (c | s \models B)$] true

B.3.11 Call

Attached Rule 26.

Call:

 $\frac{CALL = Content (CALL)}{(c \mid s \models CALL) \xrightarrow{\tau} (c \mid s \models Content (CALL))}$

Proof $(c | s \models CALL) \xrightarrow{\tau} (c | s \models Content (CALL))$ = [Assumption CALL = Content (CALL)] $(c | s \models Content (CALL)) \xrightarrow{\tau} (c | s \models Content (CALL))$ = [Silent Transition Between Equivalent Nodes 2] true

B.3.12 Iterated Actions

Attached Rule 27.

Iterated Actions:

 $(c \mid s \models OP \ Decl \bullet A) \xrightarrow{\tau} (c \mid s \models Iterated Expansion (A, Decl, ITOPFLAG))$ Iterated Expansion is defined on B.3. ITOPFLAG, as indicated on B.3, is a flag that indicates the operator that is being iterated.

Proof. $(c | s \models OP Decl \bullet A) \xrightarrow{\tau} (c | s \models IteratedExpansion (A, Decl, ITOPFLAG))$ = [Definition of Iterated Operator **B.3**] $(c \mid s \models IteratedExpansion (A, Decl, ITOPFLAG)) \xrightarrow{\tau} (c \mid s \models IteratedExpansion (A, Decl, ITOPFLAG))$ ITOPFLAG)) = [Silent Transition Equal Sides 2] true

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B.3.13 If-Guarded Command

Attached Rule 28.

If-Guarded Command: Be

 $IGC \cong \mathbf{if} (pred_1) \to A_1 \parallel (pred_2) \to A_2 \parallel \dots \parallel (pred_n) \to A_n \mathbf{fi}$, then

 $(c \mid s \models IGC) \xrightarrow{\tau} (c \land pred_1 \mid s \models A_1) T_1$ $(c \mid s \models IGC) \xrightarrow{\tau} (c \land pred_2 \mid s \models A_2) T_2$... $(c \mid s \models IGC) \xrightarrow{\tau} (c \land pred_n \mid s \models A_n) T_n$ $(c \mid s \models IGC) \xrightarrow{\tau}$ $(c \land (\neg pred_1) \land (\neg pred_2) \land ... \land (\neg pred_{n-1}) \land (\neg pred_n) \mid s \models Chaos) T_{Chaos}$

Proof

Proof of T_1

Among rules T_i , we will prove only law T_1 . The other laws can be proved using similar reasoning.

 $(c | s \models IGC) \xrightarrow{\tau} (c \land pred_1 | s \models A_1)$ = [Definition of Silent Transition B.25] $\forall w . c \land c \land pred_1 \Rightarrow (Lift (s) ; IGC \sqsubseteq Lift (s) ; A_1)$ = [w is universally quantified, so we abstract it] $c \land c \land pred_1 \Rightarrow (Lift (s) ; IGC \sqsubseteq Lift (s) ; A_1)$ = [Monotonicity of Refinement 6: if Lift (s) \sqsubseteq Lift (s) and IGC $\sqsubseteq A_1$ (by B.12 and (assms) pred₁ (pred₁ is true because it appears on the left side of the implication))] $c \land c \land pred_1 \Rightarrow$ true = [Predicate Calculus] true

Now we will prove T_{Chaos} rule.

Proof of <T*_{Chaos}> rule:*

```
(c | s \models IGC) \xrightarrow{\tau} (c \land (\neg \text{ pred}_1) \land ... \land (\neg \text{ pred}_n) | s \models \text{Chaos})
=
\forall w . (c \land c \land (\neg \text{ pred}_1) \land ... \land (\neg \text{ pred}_n)) \Rightarrow (\text{Lift } (s) ; \text{IGC} \sqsubseteq \text{Lift } (s) ; \text{Chaos})
= [w \text{ is universally quantified, so we abstract it]}
(c \land c \land (\neg \text{ pred}_1) \land ... \land (\neg \text{ pred}_n)) \Rightarrow (\text{Lift } (s) ; \text{IGC} \sqsubseteq \text{Lift } (s) ; \text{Chaos})
= [c \text{ is true}]
((\neg \text{ pred}_1) \land ... \land (\neg \text{ pred}_n)) \Rightarrow (\text{Lift } (s) ; \text{IGC} \sqsubseteq \text{Lift } (s) ; \text{Chaos})
= [(\neg \text{ pred}_1) \land ... \land (\neg \text{ pred}_n)) \Rightarrow (\text{Lift } (s) ; \text{Chaos})]
((\neg \text{ pred}_1) \land ... \land (\neg \text{ pred}_n)) \Rightarrow (\text{Lift } (s) ; \text{Chaos} \sqsubseteq \text{Lift } (s) ; \text{Chaos})
= [E \sqsubseteq E]
((\neg \text{ pred}_1) \land ... \land (\neg \text{ pred}_n)) \Rightarrow \text{true}
=
\text{true}
\Box
```

B.3.14 Z Schema

Attached Rule 29.

Z Schema:

 $\frac{c \land (s ; pre \ Op)}{(c \mid s \models Op) \xrightarrow{\tau} (c \land (s ; Op \ [w0/v']) \mid s; v := w0 \models Skip)}$

The **pre** operator is defined on **B**.2.

Proof

 \forall w . c \land c \land (s ; Op [w0/v']) \Rightarrow ((Lift (s) ; Op) \sqsubseteq (Lift (s; v := w0) ; Skip))

The proof is divided in two steps: we firstly prove the expression for Op = true, and then prove it for Op = false

 $\begin{array}{l} \hline For \ Op = true: \\ \hline \forall \ w \ . \ c \ \land \ c \ \land \ (s \ ; \ true \ [w0/v']) \Rightarrow ((Lift \ (s) \ ; \ true) \sqsubseteq (Lift \ (s; \ v := w0) \ ; \ Skip)) \\ = [w \ is universally quantified, so we abstract it] \\ c \ \land \ c \ \land \ (s \ ; \ true \ [w0/v']) \Rightarrow ((Lift \ (s) \ ; \ true) \sqsubseteq (Lift \ (s; \ v := w0) \ ; \ Skip)) \\ = [Lift \ Composition \ B.2.27] \\ c \ \land \ c \ \land \ (s \ ; \ true \ [w0/v']) \Rightarrow ((Lift \ (s) \ ; \ true) \sqsubseteq (Lift \ (s); \ Lift \ (v := w0) \ ; \ Skip)) \end{array}$

```
= [By lemma B.11, (true \sqsubseteq Lift (v := w0) ; Skip). By Ref.Eq.Sides 1, (Lift (s) \sqsubseteq Lift (s)). By both B.11 and 1 and by Monotonicity of refinement, the refinement expression on the right side of the implication is true]
```

 $c \land c \land (s ; true [w0/v']) \Rightarrow true$ = [Predicate Calculus]

true

```
For Op = false:
```

```
\forall w . c \land c \land (s ; false [w0/v']) \Rightarrow ((Lift (s) ; false) \sqsubseteq (Lift (s; v := w0) ; Skip))
= [w is universally quantified, so we abstract it]

c \land c \land (s ; false [w0/v']) \Rightarrow ((Lift (s) ; false) \sqsubseteq (Lift (s; v := w0) ; Skip))

= [false [w/x] = false]

c \land c \land (s ; false) \Rightarrow ((Lift (s) ; false) \sqsubseteq (Lift (s; v := w0) ; Skip))

= [S Sequence False 5]

c \land c \land false \Rightarrow ((Lift (s) ; false) \sqsubseteq (Lift (s; v := w0) ; Skip))

= [Predicate Calculus]

false \Rightarrow ((Lift (s) ; false) \sqsubseteq (Lift (s; v := w0) ; Skip))

= [Predicate Calculus]

true
```

B.3.15 Specification Statements

```
Attached Rule 30.
```

Specification Statements (Rule 1): $(c \mid s \models V : [Pre, Post]) \xrightarrow{\tau} (c \land Pre \mid s \models V [:] [Pre, Post])$

The Extra Statement ([:]) operator B.31 has the role of representing the Specification Statement in an intermediate state where its pre-condition is holded but its post-condition was not processed yet. The role of the Extra-statement operator is the same as the **let** B.28 operator on the rules of Variable Block.

Proof

 $(c \mid s \models V : [Pre, Post]) \xrightarrow{\tau} (c \land Pre \mid s \models V [:] [Pre, Post])$ = [Extra statement (definition B.31)] $(c \mid s \models V : [Pre, Post]) \xrightarrow{\tau} (c \land Pre \mid s \models V : [Pre, Post])$ = [Silent Transition Equal Sides (lemma 2)] true

Attached Rule 31.

Specification Statements (Rule 2): $(c \mid s \models V : [Pre, Post]) \xrightarrow{\tau} (c \land (\neg Pre) \mid s \models Skip)$

Proof

 $\begin{aligned} (c \mid s \models V : [Pre, Post]) \xrightarrow{\tau} (c \land (\neg Pre) \mid s \models Skip) \\ = [Skip V G True B.2.1] \\ \forall w . c \land c \land (\neg Pre) \Rightarrow Lift (s) ; V : [Pre, Post] \sqsubseteq Lift (s) ; V : [true, true] \end{aligned}$

From now on, the proof will be made for all 4 different situations of Pre and Post:

<u>Pre = Post = true</u>:

 $\forall w . c \land c \land (\neg true) \Rightarrow Lift (s) ; V : [true, true] \sqsubseteq Lift (s) ; V : [true, true]$ = [w is universally quantified, so we abstract it] $c \land c \land (\neg true) \Rightarrow Lift (s) ; V : [true, true] \sqsubseteq Lift (s) ; V : [true, true]$ = [Predicate Calculus] $false \Rightarrow true$ = [Predicate Calculus] true

Pre = true, Post = false:

 $\forall w . c \land c \land (\neg true) \Rightarrow Lift (s) ; V : [true, false] \sqsubseteq Lift (s) ; V : [true, true]$ = [w is universally quantified, so we abstract it] $c \land c \land (\neg true) \Rightarrow (Lift (s) ; V : [true, false] \sqsubseteq Lift (s) ; V : [true, true])$ $= false \Rightarrow (Lift (s) ; V : [true, false] \sqsubseteq Lift (s) ; V : [true, true])$ = true

 $\underline{Pre = false, Post = true:}$

 $(c | s \models V : [false, true]) \xrightarrow{\tau} (c \land (\neg false) | s \models Skip)$ = [Definition of Silent Transition B.25]

```
\forall w. c \land c \land (\neg false) \Rightarrow Lift (s) ; V : [false, true] \sqsubseteq Lift (s) ; V : [true, true]
= [w is universally quantified, so we abstract it]
c \land c \land (\neg false) \Rightarrow Lift (s); V : [false, true] \sqsubseteq Lift (s); V : [true, true]
= [Assume c = true]
Lift (s); V : [false, true] \sqsubseteq Lift (s); V : [true, true]
= [As Lift (s) is refined by itself, so, from Monotonicity of Refinement, the proof from
now on will consist only on proving that V : [false, true] \Box V : [true, true]]
V : [false, true] \Box V : [true, true]
= [Specification Statement Denotational Definition A.6]
R (false \vdash true \land \neg wait' \land tr' = tr \land u' = u) \Box R(true \vdash true \land \neg wait' \land tr' = tr \land u' = u)
= [Predicate Calculus]
R ((false \wedge ok)
\Rightarrow
((true \land \neg wait' \land tr' = tr \land u' = u) \land ok') \sqsubseteq R((true \land ok) \Rightarrow (true \land \neg wait' \land tr' = tr \land u' = u) \land ok')
u' = u \wedge ok')
= [Predicate Calculus]
R (true)
\Box R((true \land ok) \Rightarrow (true \land \neg wait' \land tr' = tr \land u' = u \land ok'))
= [Predicate Calculus]
R (true)
\Box R((\neg true \lor \neg ok) \lor (true \land \neg wait' \land tr' = tr \land u' = u \land ok'))
= [Predicate Calculus]
R (true)
\sqsubseteq R((\neg ok) \lor (\neg wait' \land tr' = tr \land u' = u \land ok'))
= [Be x = (\neg ok) \lor (\neg wait' \land tr' = tr \land u' = u \land ok')]
R (true) \sqsubseteq R(x)
= [Healthy True Refinement B.6]
true
Pre = Post = false:
(c \mid s \models V : [Pre,Post]) \xrightarrow{\tau} (c \land (\neg Pre) \mid s \models Skip)
= [Definition of Silent Transition B.25]
\forall w. c \land c \land (\neg false) \Rightarrow Lift (s); V : [false, false] \Box Lift (s); V : [true, true]
= [w is universally quantified, so we abstract it]
c \wedge c \wedge (\neg \text{ false}) \Rightarrow \text{Lift } (s) ; V : [\text{false, false}] \sqsubseteq \text{Lift } (s) ; V : [\text{true, true}]
```

```
= [Predicate Calculus]
```

Lift (s); V : [false, false] \sqsubseteq Lift (s); V : [true, true] = [Monotonicity of Refinement 6] V : [false, false] \sqsubseteq V : [true, true] = [Predicate Calculus] R (false \vdash false $\land \neg$ wait' \land tr' = tr \land u' = u) $\sqsubseteq R(true \vdash true \land \neg wait' \land tr' = tr \land u' = u)$ = [Predicate Calculus] R (false \vdash false) \Box R(true $\vdash \neg$ wait' \land tr' = tr \land u' = u) = [Predicate Calculus] R (false \land ok \Rightarrow false \land ok') \Box R(true $\vdash \neg$ wait' \land tr' = tr \land u' = u) = [Predicate Calculus] R (false \Rightarrow false) \sqsubseteq R(true $\vdash \neg$ wait' \land tr' = tr \land u' = u) = [Predicate Calculus] R (true) \sqsubseteq R(true $\vdash \neg$ wait' \land tr' = tr \land u' = u) = [Healthy True Refinement **B.6**] true

Attached Rule 32.

Specification Statements (Rule 3): $(c \land Pre \mid s \models V [:] [Pre, Post])$ $\stackrel{\tau}{\rightarrow}$ $(c \land Pre \land Post \land (\alpha(P) - V)' = (\alpha(P) - V)) \mid s \models Skip)$

Proof

 $\begin{array}{l} (c \land Pre \mid s \models V \; [:] \; [Pre, Post]) \\ \xrightarrow{\tau} \\ (c \land Pre \land (Post \land (\alpha(P) - V)' = (\alpha(P) - V)) \mid s \models Skip) \\ = [Definition \; of \; Silent \; Transition \; B.25] \\ \forall \; w \; . \; (c \land Pre \land c \land Pre \land Post \land (\alpha(P) - V)' = (\alpha(P) - V)) \\ \Rightarrow \; Lift \; (s) \; ; \; V \; [:] \; [Pre, Post] \sqsubseteq Lift \; (s) \; ; \; Skip \end{array}$

We will prove the above expression checking the following complementary situations: (Pre = false \lor Post = false) and (Pre = true \land Post = true)

 $\underline{Pre = false \lor Post = false}$

In this case, the antecedent of the implication is false:

```
 \begin{array}{l} \forall \ w \ . \ (c \ \land \ false \ \land \ c \ \land \ Pre \ \land \ Post \ \land \ (\alpha(P) - V)' = (\alpha(P) - V)) \\ \Rightarrow \ Lift \ (s) \ ; \ V \ [:] \ [Pre, \ Post] \ \sqsubseteq \ Lift \ (s) \ ; \ Skip \\ = \left[ w \ is \ universally \ quantified, \ so \ we \ abstract \ it \right] \\ (c \ \land \ false \ \land \ c \ \land \ Pre \ \land \ Post \ \land \ (\alpha(P) - V)' = (\alpha(P) - V)) \\ \Rightarrow \ Lift \ (s) \ ; \ V \ [:] \ [Pre, \ Post] \ \sqsubseteq \ Lift \ (s) \ ; \ Skip \\ = \left[ Predicate \ Calculus \right] \\ (false \ \Rightarrow \ Lift \ (s) \ ; \ V \ [:] \ [Pre, \ Post] \ \sqsubseteq \ Lift \ (s) \ ; \ Skip \\ = \left[ Predicate \ Calculus \right] \\ true \end{array}
```

```
\underline{Pre} = true \land Post = true
```

```
\forall \ w \ . \ (c \land true \land c \land true \land true \land (\alpha(P) - V)' = (\alpha(P) - V))
```

- \Rightarrow Lift (s) ; V [:] [true, true] \sqsubseteq Lift (s) ; Skip
- = [w is universally quantified, so we abstract it]
- $(c \land true \land c \land true \land true \land (\alpha(P) V)' = (\alpha(P) V))$
- \Rightarrow Lift (s) ; V [:] [true, true] \sqsubseteq Lift (s) ; Skip

```
= [Predicate Calculus]
```

- $(c \land true \land c \land true \land true \land (\alpha(P) V)' = (\alpha(P) V))$
- \Rightarrow Lift (s); V [:] [true, true] \sqsubseteq Lift (s); V : [true, true]
- = [Predicate Calculus]
- $(c \land true \land c \land true \land true \land (\alpha(P) V)' = (\alpha(P) V))$
- \Rightarrow Lift (s); V : [true, true] \sqsubseteq Lift (s); V : [true, true]
- = [Refinement Equal Sides 1]
- $(c \land true \land c \land true \land true \land (\alpha(P) V)' = (\alpha(P) V))$
- \Rightarrow true
- = [Predicate Calculus]
- = true

B.3.16 Basic Process

Attached Rule 33.

Basic Process Begin: $\frac{(c1 \mid s1 \models A1) \xrightarrow{lp} (c2 \mid s2 \models A2)}{(c1 \mid s1 \mid begin \ state \ [Vars-decl \mid inv] \bullet A1 \ end)}$ $\xrightarrow{lp} (c2 \mid s2 \mid begin \ state \ [Vars-decl \mid inv] \bullet A2 \ end)$

Assumption: $(c1 | s1 \models A1) \xrightarrow{lp} (c2 | s2 \models A2)$ = [Definition of Labelled Transition B.26] $\forall w . c1 \land c2 \Rightarrow$ $\begin{pmatrix} Lift(s1); A1 \\ \Box Lift(s2); lp \to A1 \Box Lift(s1); A1 \end{pmatrix}$ = [Labelled Transition Implication B.17] $\forall w . (Lift(c1); A1) \Box \forall w . (Lift(c2); lp \to A2) [Assumption for a field of the second second$

 $\forall \; w$. (Lift (s1); A1) $\sqsubseteq \; \forall \; w$. (Lift (s3); lp \rightarrow A3) [Assumption 2]

Proof

(c1 | s1 | begin state [Vars-decl | inv] • A1 end) $\xrightarrow{lp} (c2 | s2 | begin state [Vars-decl | inv] • A2 end)$ = [Definition of Labelled Transition B.26] $\forall w.c1 \land c2 \Rightarrow$ Lift(s1); (begin state[Vars - decl | inv] • A1 end) \subseteq $\begin{pmatrix} Lift(s2); lp \rightarrow begin state[Vars - decl | inv] • A1 end \\ \Box Lift(s1); begin state[Vars - decl | inv] • A1 end$ = [Basic Process Denotational Meaning B.2.15] $\forall w.c1 \land c2 \Rightarrow$ Lift(s1); Vars - Decl • A1 \subseteq $\begin{pmatrix} Lift(s2); lp \rightarrow Vars - Decl • A1 \\ \Box Lift(s1); Vars - Decl • A1 \end{pmatrix}$ = [W is universally quantified, so we abstract it] $c1 \land c2 \Rightarrow$ Lift(s1); Vars - Decl • A1 \subseteq

B.3. PROOF OF SOUNDNESS FOR RULES

```
\begin{pmatrix} Lift(s2); lp \rightarrow Vars - Decl \bullet A1 \\ \Box Lift(s1); Vars - Decl \bullet A1 \end{pmatrix}
= [External Choice Idempotence B.2.24]

c1 \wedge c2 \Rightarrow

(Lift(s1); Vars - Decl \bullet A1) \Box (Lift(s1); Vars - Decl \bullet A1)

\Box

\begin{bmatrix} Lift(s2); lp \rightarrow Vars - Decl \bullet A1 \\ \Box Lift(s1); Vars - Decl \bullet A1 \end{bmatrix}

= [Assumption 2 + External Choice Monotonic 14]

c1 \wedge c2 \Rightarrow true

= [Predicate Calculus]

true
```

Attached Rule 34.

Basic Process Reduction:

Based on B.2.16 and B.2.17 from the refinement calculus of Circus:

 $\frac{c \quad \alpha(STA) \cap \alpha(STB) = \emptyset}{(c \models (\text{begin state } STA \ PARS-A \bullet A \ \text{end}) \ OP \ (\text{begin state } STB \ PARS-B \bullet B \ \text{end}))}$ $\sim \rightarrow (c \mid s \models \text{begin state } (STA \land STB) \ (PARS-A \land_{\Xi} STB) \ (PARS-B \land_{\Xi} STA) \bullet A \ OP \ B \ \text{end})$

Where $OP \in \{ \sqcap, \square, ;, |||, || CS ||, || \alpha(A) | CS | \alpha(B) || \}$

As Basic Process Reduction is an abstract rule applied for a set of binary operators that appear as processes and as actions (Internal Choice, External Choice, Parallelism, Sequence, Interleaving), the proof involves the application of different refinement laws, depending on the operator. But the sequence of proof sub-goals is the same. As the proof is based on the application of rules B.2.16 and B.2.17. Be

```
B = (begin state STA PARS - A \bullet A end) OP (begin state STB PARS - B \bullet B end), and
```

 $P = begin state (STA \land STB) (PARS - A \land_{\Xi} STB) (PARS - B \land_{\Xi} STA) \bullet A OP B end)$

= [Sigma Equal Basic Process (having, from def.B.2.16 and B.2.17, that B=P] true
□

B.3.17 Compound Process

Attached Rule 35.

Compound Process Left:

 $\frac{(c_1 \models P_1) \rightsquigarrow (c_2 \models P_3)}{(c_1 \models P_1 \ OP \ P_2) \rightsquigarrow (c_2 \models P_3 \ OP \ P_2)}$

Where $OP \in \{ \sqcap, \square, ;, |||, || CS || \}$

The proof will be divided on the following steps:

- Derivation of the assumption on other minor assumptions;
- Creation of a Lemma to synthesize the proof (the lemmas are referenced on the tactics and have their proofs made on appendix B.2.2);
- Division of the rule on a Sub-rule for each operator OP (OP ∈ { □,□,;,|||,|[CS]] }), and proof for each Sub-rule;

To reduce verbose, we create the abbreviation gA(s) such that gA(s) = getAssignments(s)

Assumptions B.19. .

[Assumption 1] $(c_1 \models P_1) \rightsquigarrow (c_2 \models P_3) =$ [Definition of Syntactic Transition having w universally quantified B.27] $c_1 \land c_2 \Rightarrow$ $((Lift (gA (P_1)) ; P_1 \sqsubseteq Lift (gA (P_3)) ; P_3)) \land Lift (gA (P_1)) = Lift (gA (P_3))$ $((Lift (gA (P_1)) ; P_1 \sqsubseteq Lift (gA (P_3)) ; P_3)) \land Lift (gA (P_1)) = Lift (gA (P_3)) \Rightarrow$ [Assumption 2] Lift (gA (P_1)) = Lift (gA (P_3)) $((Lift (gA (P_1)) ; P_1 \sqsubseteq Lift (gA (P_3)) ; P_3)) \land Lift (gA (P_1)) = Lift (gA (P_3)) \Rightarrow$ [Assumption 3] Lift (gA (P_1)) ; P_1 \sqsubseteq Lift (gA (P_3)) ; P_3)

As [Assumption 2] and [Assumption 3]

then

[Assumption 4] Lift $(gA(P_3))$; $P_1 \sqsubseteq Lift (gA(P_3))$; P_3 As [Assumption 2] and [Assumption 4] [Assumption 5] $P_1 \sqsubseteq P_3$

Sub-Rule 1.

Internal Choice Compound Process Left:

 $\frac{(c_1 \models P_1) \rightsquigarrow (c_2 \models P_3) \quad OP = \sqcap}{(c_1 \models P_1 \ OP \ P_2) \rightsquigarrow (c_2 \models P_3 \ OP \ P_2)}$

Proof

```
(c_1 \models P_1 \text{ OP } P_2) \rightsquigarrow (c_2 \models P_3 \text{ OP } P_2)
= [Lemma Compound Process B.9]
c_1 \wedge c_2 \Rightarrow
(\text{Lift}(\text{gA}(\text{P}_1)) \land \text{Lift}(\text{gA}(\text{P}_2)); \text{P}_1 \text{ OP } \text{P}_2 \sqsubseteq (\text{Lift}(\text{gA}(\text{P}_1)) \land \text{Lift}(\text{gA}(\text{P}_2)); \text{P}_3 \text{ OP } \text{P}_2))
= [Be L = (Lift (gA (P<sub>1</sub>)) \land Lift (gA (P<sub>2</sub>))]
c_1 \wedge c_2 \Rightarrow
L; P_1 OP P_2 \sqsubseteq L; P_3 OP P_2
= [Assumption OP = \Box]
c_1 \wedge c_2 \Rightarrow
L; P_1 \sqcap P_2 \sqsubseteq (L; P_3 \sqcap P_2)
= [\mathbf{P}_1 \sqsubseteq \mathbf{P}_3 \text{ (Assumption 5)} \land \mathbf{P}_2 \sqsubseteq \mathbf{P}_2, \text{ so } \mathbf{P}_1 \sqcap \mathbf{P}_2 \sqsubseteq \mathbf{P}_3 \sqcap \mathbf{P}_2 \text{ (B.2.20)}, \mathbf{L} \sqsubseteq \mathbf{L} \land \mathbf{P}_1 \sqcap
P_2 \sqsubseteq P_3 \sqcap P_2, then (Monotonicity of Refinement 6) L; P_1 \sqcap P_2 \sqsubseteq L; P_3 \sqcap P_2]
c_1 \wedge c_2 \Rightarrow true
= [Predicate Calculus: (P \Rightarrow true) = true]
true
= true
```

Sub-Rule 2.

External Choice Compound Process Left: $\frac{(c_1 \models P_1) \rightsquigarrow (c_2 \models P_3) \quad OP = \Box}{(c_1 \models P_1 \ OP \ P_2) \rightsquigarrow (c_2 \models P_3 \ OP \ P_2)}$

Proof

 $\begin{array}{l} (\mathbf{c}_1 \models \mathbf{P}_1 \ \mathrm{OP} \ \mathbf{P}_2) \rightsquigarrow (\mathbf{c}_2 \models \mathbf{P}_3 \ \mathrm{OP} \ \mathbf{P}_2) \\ = [\mathbf{Lemma} \ \mathbf{Compound} \ \mathbf{Process} \ \mathbf{B}.\mathbf{9}] \\ \mathbf{c}_1 \land \mathbf{c}_2 \Rightarrow \\ (\mathrm{Lift} \ (\mathrm{gA} \ (\mathbf{P}_1)) \land \mathrm{Lift} \ (\mathrm{gA} \ (\mathbf{P}_2)) \ ; \ \mathbf{P}_1 \ \mathrm{OP} \ \mathbf{P}_2 \sqsubseteq (\mathrm{Lift} \ (\mathrm{gA} \ (\mathbf{P}_1)) \land \mathrm{Lift} \ (\mathrm{gA} \ (\mathbf{P}_2)) \ ; \ \mathbf{P}_3 \ \mathrm{OP} \ \mathbf{P}_2)) \\ = [\mathbf{Be} \ \mathbf{L} = (\mathbf{Lift} \ (\mathbf{gA} \ (\mathbf{P}_1)) \land \mathbf{Lift} \ (\mathbf{gA} \ (\mathbf{P}_2))] \\ \mathbf{c}_1 \land \mathbf{c}_2 \Rightarrow \\ \mathbf{L} \ ; \ \mathbf{P}_1 \ \mathrm{OP} \ \mathbf{P}_2 \sqsubseteq \mathbf{L} \ ; \ \mathbf{P}_3 \ \mathrm{OP} \ \mathbf{P}_2 \\ = [\mathbf{Assumption} \ \mathbf{OP} = \Box] \\ \mathbf{c}_1 \land \mathbf{c}_2 \Rightarrow \end{array}$

L;
$$P_1 \square P_2 \sqsubseteq (L; P_3 \square P_2)$$

= $[P_1 \sqsubseteq P_3 \text{ (Assumption 5)} \land P_2 \sqsubseteq P_2, \text{ so } P_1 \square P_2 \sqsubseteq P_3 \square P_2 \text{ (B.2.22). } L \sqsubseteq L \land P_1 \square P_2 \sqsubseteq P_3 \square P_2, \text{ then (Monotonicity of Refinement 6) } L; P_1 \square P_2 \sqsubseteq L; P_3 \square P_2]$
 $c_1 \land c_2 \Rightarrow \text{true}$
= $(P \Rightarrow \text{true}) = \text{true}$
true

Sub-Rule 3.

Sequence Compound Process Left: $\frac{(c_1 \models P_1) \rightsquigarrow (c_2 \models P_3) \quad OP = ;}{(c_1 \models P_1 \ OP \ P_2) \rightsquigarrow (c_2 \models P_3 \ OP \ P_2)}$

Proof

 $(c_1 \models P_1 \text{ OP } P_2) \rightsquigarrow (c_2 \models P_3 \text{ OP } P_2)$ = [Lemma Compound Process **B.9**] $c_1 \wedge c_2 \Rightarrow$ $(\text{Lift}(\text{gA}(\text{P}_1)) \land \text{Lift}(\text{gA}(\text{P}_2)); \text{P}_1 \text{ OP } \text{P}_2 \sqsubseteq (\text{Lift}(\text{gA}(\text{P}_1)) \land \text{Lift}(\text{gA}(\text{P}_2)); \text{P}_3 \text{ OP } \text{P}_2))$ = [Be L = (Lift (gA (P₁)) \land Lift (gA (P₂))] $c_1 \wedge c_2 \Rightarrow$ L; P_1 OP $P_2 \sqsubseteq L$; P_3 OP P_2 = [Assumption OP = ;] $c_1 \wedge c_2 \Rightarrow$ L; P_1 ; $P_2 \sqsubseteq (L; P_3; P_2)$ = $[\mathbf{P}_1 \sqsubseteq \mathbf{P}_3 \text{ (Assumption 5)} \land \mathbf{P}_2 \sqsubseteq \mathbf{P}_2, \text{ so } \mathbf{P}_1 \text{ ; } \mathbf{P}_2 \sqsubseteq \mathbf{P}_3 \text{ ; } \mathbf{P}_2 \text{ (6)}].$ L \sqsubseteq L \land P₁ ; P₂ \sqsubseteq P_3 ; P_2 , then (Monotonicity of Refinement 6) L; P_1 ; $P_2 \sqsubseteq L$; P_3 ; P_2] $c_1 \wedge c_2 \Rightarrow true$ $= (\mathbf{P} \Rightarrow \mathbf{true}) = \mathbf{true}$ true = true

Sub-Rule 4.

Parallelism Compound Process Left:

$$\frac{(c_1 \models P_1) \rightsquigarrow (c_2 \models P_3) \qquad OP = \llbracket CS \rrbracket}{(c_1 \models P_1 \ OP \ P_2) \rightsquigarrow (c_2 \models P_3 \ OP \ P_2)}$$

Proof

 $(c_1 \models P_1 \text{ OP } P_2) \rightsquigarrow (c_2 \models P_3 \text{ OP } P_2)$

```
= [Lemma Compound Process B.9]
c_1 \wedge c_2 \Rightarrow
(\text{Lift} (\text{gA} (P_1)) \land \text{Lift} (\text{gA} (P_2)); P_1 \text{ OP } P_2 \sqsubseteq (\text{Lift} (\text{gA} (P_1)) \land \text{Lift} (\text{gA} (P_2)); P_3 \text{ OP } P_2))
= [Be L = (Lift (gA (P<sub>1</sub>)) \land Lift (gA (P<sub>2</sub>))]
c_1 \wedge c_2 \Rightarrow
L; P_1 OP P_2 \sqsubseteq L; P_3 OP P_2
= [Assumption OP = ||CS||]
c_1 \wedge c_2 \Rightarrow
L; P_1 \parallel CS \parallel P_2 \sqsubseteq (L; P_3 \parallel CS \parallel P_2)
= [\mathbf{P}_1 \sqsubseteq \mathbf{P}_3 \text{ (Assumption 5)} \land \mathbf{P}_2 \sqsubseteq \mathbf{P}_2, \text{ so } \mathbf{P}_1 \parallel \mathbf{CS} \parallel \mathbf{P}_2 \sqsubseteq \mathbf{P}_3 \parallel \mathbf{CS} \parallel \mathbf{P}_2 \text{ (B.2.21)}. \mathbf{L} \sqsubseteq \mathbf{L}
\wedge \mathbf{P}_1 \parallel \mathbf{CS} \parallel \mathbf{P}_2 \sqsubset \mathbf{P}_3 \parallel \mathbf{CS} \parallel \mathbf{P}_2, then (Monotonicity of Refinement 6) L; \mathbf{P}_1 \parallel \mathbf{CS} \parallel \mathbf{P}_2
\sqsubseteq L; P<sub>3</sub> \parallel CS \parallel P<sub>2</sub>]
c_1 \wedge c_2 \Rightarrow true
= (\mathbf{P} \Rightarrow \mathbf{true}) = \mathbf{true}
true
= true
```

Sub-Rule 5.

Interleave Compound Process Left:

 $\frac{(c_1 \models P_1) \rightsquigarrow (c_2 \models P_3) \qquad OP = |||}{(c_1 \models P_1 \ OP \ P_2) \rightsquigarrow (c_2 \models P_3 \ OP \ P_2)}$

Proof

 $\frac{(c_1 \models P_1) \rightsquigarrow (c_2 \models P_3) \quad OP = |||}{(c_1 \models P_1 \text{ OP } P_2) \rightsquigarrow (c_2 \models P_3 \text{ OP } P_2)}$

= [Interleaving is equivalent to Parallelism with an empty channel set]

 $\frac{(c_1 \models P_1) \rightsquigarrow (c_2 \models P_3) \qquad OP = [[\{\}]]}{(c_1 \models P_1 \text{ OP } P_2) \rightsquigarrow (c_2 \models P_3 \text{ OP } P_2)}$ = Parallelism Compound Process Left [4]

true

Attached Rule 36.

Compound Process Right (for $OP \in \{ \Box, \sqcap, || CS]|, ||| \}$): $\frac{(c_1 \models P_1) \rightsquigarrow (c_2 \models P_3) \qquad OP \in \{ \Box, \sqcap, || CS]|, ||| \}}{(c_1 \models P_1 \ OP \ P_2) \rightsquigarrow (c_2 \models P_1 \ OP \ P_3)}$

As, except for Sequence, all compound operators are commutative, the proof for attached rule 36 will be done re-using attached rule 35 as a theorem. The proof for Sequence

will be done on sub-rule 6.

Proof

 $\begin{array}{l} \underbrace{(c_1 \models P_1) \rightsquigarrow (c_2 \models P_3) & OP \in \{ \Box, \sqcap, [\![CS]\!], \|\!| \} \}}{(c_1 \models P_1 \ OP \ P_2) \rightsquigarrow (c_2 \models P_1 \ OP \ P_3)} \\ = \begin{bmatrix} \textbf{Except for Sequence, all compound operators are commutative} (\Box, \sqcap, [\![CS]\!], \|\!|) \end{bmatrix} \\ \underbrace{(c_1 \models P_1) \rightsquigarrow (c_2 \models P_3) & OP \in \{ \Box, \sqcap, [\![CS]\!], \|\!| \} \}}{(c_1 \models P_2 \ OP \ P_1) \rightsquigarrow (c_2 \models P_3 \ OP \ P_1)} \\ = \begin{bmatrix} \textbf{Compound Process Left 35} \end{bmatrix} \\ \textbf{true} \\ \end{array}$

Sub-Rule 6.

Sequence Compound Process Right:

 $\frac{(c_1 \models P_1) \rightsquigarrow (c_2 \models P_3) \quad OP = ;}{(c_1 \models P_1 \ OP \ P_2) \rightsquigarrow (c_2 \models P_1 \ OP \ P_3)}$

In order to facilitate the proof, we will create and prove lemma B.10 and then prove sub-rule 6.

Proof

 $(c_1 \models P_1 \text{ OP } P_2) \rightsquigarrow (c_2 \models P_1 \text{ OP } P_3)$ = [Lemma Compound Process **B.10**] $c_1 \land c_2 \Rightarrow (\text{Lift } (\text{gA} (P_1)) \land \text{Lift } (\text{gA} (P_2)); P_1 \text{ OP } P_2 \sqsubseteq (\text{Lift } (\text{gA} (P_1)) \land \text{Lift } (\text{gA} (P_2));$ $P_1 OP P_3)$ = [Be L = (Lift (gA (P₁)) \land Lift (gA (P₂))] $c_1 \wedge c_2 \Rightarrow L$; $P_1 \text{ OP } P_2 \sqsubseteq L$; $P_1 \text{ OP } P_3$ = [Assumption OP = ;] $c_1 \wedge c_2 \Rightarrow L ; P_1 ; P_2 \sqsubseteq (L ; P_1 ; P_3)$ = $[\mathbf{P}_1 \sqsubseteq \mathbf{P}_3 \text{ (Assumption 5)} \land \mathbf{P}_2 \sqsubseteq \mathbf{P}_2, \text{ so } \mathbf{P}_1; \mathbf{P}_2 \sqsubseteq \mathbf{P}_1; \mathbf{P}_3 \text{ (6)}]$ $c_1 \wedge c_2 \Rightarrow L$; P_1 ; $P_2 \sqsubseteq L$; P_1 ; P_3 [having P_1 ; $P_2 \sqsubseteq P_1$; P_3] = $[L \sqsubseteq L \land P_1; P_2 \sqsubseteq P_1; P_3, \text{ then (Monotonicity of Refinement 6) } L; P_1; P_2 \sqsubseteq L$; **P**₁ ; **P**₃] $c_1 \wedge c_2 \Rightarrow true$ $= (\mathbf{P} \Rightarrow \mathbf{true}) = \mathbf{true}$ true = true

B.3.18 Hide Process

Attached Rule 37.

Hiding Advance:

 $\frac{(c_1 \models P_1) \rightsquigarrow (c_2 \models P_2)}{(c_1 \models P_1 \setminus S) \rightsquigarrow (c_2 \models P_2 \setminus S)}$

From Assumptions **B.19**:

[Assumption 1]: $(c_1 \models P_1) \rightsquigarrow (c_2 \models P_2)$ [Assumption 2]: Lift (getAssignments (P_1)) = Lift (getAssignments (P_2)) [Assumption 3]: Lift (getAssignments (P_1)); P_1 \sqsubseteq Lift (getAssignments (P_2)); P_2) [Assumption 4]: Lift (getAssignments (P_2)); P_1 Lift (getAssignments (P_2)); P_2 [Assumption 5]: P_1 \sqsubseteq P_2

Proof

 $(c_1 \models P_1 \setminus S) \rightsquigarrow (c_2 \models P_2 \setminus S)$ = [Definition of Syntactic Transition **B.27**] \forall w . c₁ \land c₂ \Rightarrow ((Lift (getAssignments ($P_1 \setminus S$)); $P_1 \setminus S \sqsubseteq$ Lift (getAssignments ($P_2 \setminus S$)); $P_2 \setminus S$)) \wedge Lift (getAssignments (P₁ \ S)) = Lift (getAssignments (P₂ \ S)) = [w is universally quantified, so we abstract it] $c_1 \wedge c_2 \Rightarrow$ ((Lift (getAssignments ($P_1 \setminus S$)); $P_1 \setminus S \sqsubseteq$ Lift (getAssignments ($P_2 \setminus S$)); $P_2 \setminus S$)) \wedge Lift (getAssignments (P₁ \ S)) = Lift (getAssignments (P₂ \ S)) = [Definition of getAssignments ($P \setminus CS$) **B.1**] $c_1 \wedge c_2 \Rightarrow$ ((Lift (getAssignments (P₁)); P₁ \setminus S \sqsubseteq Lift (getAssignments (P₂)); P₂ \setminus S)) \wedge Lift (getAssignments (P₁)) = Lift (getAssignments (P₂)) = [Assumption 2] $c_1 \wedge c_2 \Rightarrow$ ((Lift (getAssignments (P₁)); P₁ \setminus S \sqsubseteq Lift (getAssignments (P₂)); P₂ \setminus S)) \wedge true $= [\mathbf{P} \land \mathbf{true} = \mathbf{P}]$ $c_1 \wedge c_2 \Rightarrow$ ((Lift (getAssignments (P₁)); P₁ \setminus S \sqsubseteq Lift (getAssignments (P₂)); P₂ \setminus S)) = [Assumption 2 again]

 $c_1 \land c_2 \Rightarrow$ ((Lift (getAssignments (P₁)) ; P₁ \ S \sqsubseteq Lift (getAssignments (P₁)) ; P₂ \ S)) = [Assumption 5 and Hiding Monotonic B.2.9 \Rightarrow P₁ \ S \sqsubseteq P₂ \ S. That with General Monotonicity of Refinement \Rightarrow L ; P \sqsubseteq L ; Q] $c_1 \land c_2 \Rightarrow$ true = [Predicate Calculus: P \Rightarrow true = true] \forall w . true = true \Box Attached Rule 38. Hiding Basic Process: $(c \models (begin state ST PARS \bullet A end) \setminus S)$ \rightsquigarrow $(c \mid s \models begin state ST PARS \bullet (A \setminus S) end)$

```
Be HP = (begin state ST PARS • A end) \setminus S
```

and

```
HB = begin state ST PARS \bullet (A \setminus S) end
Proof
```

```
\begin{pmatrix} (c \models (\text{begin state } ST PARS \bullet A \text{ end}) \setminus S) \\ \sim \\ (c \mid s \models \text{begin state } ST PARS \bullet (A \setminus S) \text{ end}) \end{pmatrix}
= [Sigma Equal Basic Process 4 (having, from law B.2.19, that HP = HB]
true
```

B.3.19 Rename Process

Attached Rule 39.

Rename Advance:

$$\frac{(c_1 \models P_1) \rightsquigarrow (c_2 \models P_2)}{(c_1 \models P_1 \ [a_1, a_2, \dots = b_1, b_2, \dots]) \rightsquigarrow (c_2 \models P_2 \ [a_1, a_2, \dots = b_1, b_2, \dots])}$$

From Assumptions **B.19**:

[Assumption 1]: $(c_1 \models P_1) \rightsquigarrow (c_2 \models P_2)$ [Assumption 2]: Lift $(gA(P_1)) = Lift (gA(P_2))$ [Assumption 3]: Lift $(gA(P_1))$; $P_1 \sqsubseteq Lift (gA(P_2))$; P_2) [Assumption 4]: Lift $(gA(P_2))$; P_1 Lift $(gA(P_2))$; P_2 [Assumption 5]: $P_1 \sqsubseteq P_2$

Proof

 $\begin{aligned} &(c_1 \models P_1 \ [a_1, a_2, ... = b_1, b_2, ...]) \rightsquigarrow (c_2 \models P_2 \ [a_1, a_2, ... = b_1, b_2, ...]) \\ = &[\textbf{Definition of Syntactic Transition B.27}] \\ &\forall w. c_1 \land c_2 \Rightarrow \\ & \left(\begin{pmatrix} (Lift (gA (P_1 \ [a_1, a_2, ... = b_1, b_2, ...])); \ P_1 \ [a_1, a_2, ... = b_1, b_2, ...]) \\ & \subseteq (Lift (gA (P_2 \ [a_1, a_2, ... = b_1, b_2, ...])); \ P_2 \ [a_1, a_2, ... = b_1, b_2, ...]) \end{pmatrix} \\ & \land Lift (gA (P_1 \ [a_1, a_2, ... = b_1, b_2, ...])) = Lift (gA (P_2 \ [a_1, a_2, ... = b_1, b_2, ...])) \\ & \land Lift (gA (P_1 \ [a_1, a_2, ... = b_1, b_2, ...])); \ P_1 \ [a_1, a_2, ... = b_1, b_2, ...]) \end{pmatrix} \\ & = &[\textbf{w} \text{ is universally quantified, so we abstract it]} \\ & c_1 \land c_2 \Rightarrow \\ & \left(\begin{pmatrix} (Lift (gA (P_1 \ [a_1, a_2, ... = b_1, b_2, ...])); \ P_2 \ [a_1, a_2, ... = b_1, b_2, ...]) \\ & \vdash (Lift (gA (P_1 \ [a_1, a_2, ... = b_1, b_2, ...])); \ P_2 \ [a_1, a_2, ... = b_1, b_2, ...]) \end{pmatrix} \\ & \land Lift (gA (P_1 \ [a_1, a_2, ... = b_1, b_2, ...])) = Lift (gA (P_2 \ [a_1, a_2, ... = b_1, b_2, ...])) \end{pmatrix} \\ & = &[\textbf{Definition of gA (P \ [a_1, a_2, ... = b_1, b_2, ...]) \\ & \qquad ((Lift (gA (P_1))); \ P_1 \ [a_1, a_2, ... = b_1, b_2, ...]) \\ & \qquad ((Lift (gA (P_1))); \ P_2 \ [a_1, a_2, ... = b_1, b_2, ...]) \\ & \qquad (Lift (gA (P_1))) = Lift (gA (P_2)) \\ & \qquad (Lift (gA (P_1))) = Lift (gA (P_2)) \\ & \qquad (Lift (gA (P_1))) = Lift (gA (P_2)) \\ & \qquad (Lift (gA (P_1))) = Lift (gA (P_2)) \\ & \qquad (Lift (gA (P_1))) = Lift (gA (P_2)) \\ & = &[\textbf{Assumption 2] \\ & (Lift (gA (P_1))); \ P_1 \ [a_1, a_2, ... = b_1, b_2, ...]) \subseteq (Lift (gA (P_2)); \ P_2 \ [a_1, a_2, ... = b_1, b_2, ...])) \\ & \land h \text{ twe} \\ & \textbf{R} \text{ wis the Gold base Detetered Detetetered Detetered Detetered Detetered Detetetered De$

= [Predicate Calculus: P \lapha true = P]

 $c_1 \wedge c_2 \Rightarrow$ $((Lift(gA(P_1)); P_1[a_1, a_2, ... = b_1, b_2, ...] \sqsubseteq Lift(gA(P_2)); P_2[a_1, a_2, ... = b_1, b_2, ...]))$ = [Assumption 2 again] $c_1 \wedge c_2 \Rightarrow$ $((Lift(gA(P_1)); P_1[a_1, a_2, ... = b_1, b_2, ...] \sqsubseteq Lift(gA(P_1)); P_2[a_1, a_2, ... = b_1, b_2, ...]))$ = [Assumption 5 and Rename Monotonic \Rightarrow P₁ [a₁, a₂, ... = b₁, b₂, ...] \sqsubseteq P₂ [a₁, a₂, ... = b₁, b₂, ...]. That with General Monotonicity of Refinement \Rightarrow L ; P \sqsubseteq L ; Q] $c_1 \wedge c_2 \Rightarrow true$ = [Predicate Calculus: $P \Rightarrow true = true$] true Attached Rule 40.

Rename Basic Process:

 $(c \models (\text{begin state } ST PARS \bullet A \text{ end}) [a_1, a_2, \dots = b_1, b_2, \dots])$ $\sim \rightarrow$

```
(c \mid s \models \text{begin state } ST PARS \bullet A [a_1, a_2, ... = b_1, b_2, ...] \text{ end})
```

Proof

Be

$$RP = (begin state ST PARS \bullet A end) [a_1, a_2, ... = b_1, b_2, ...]$$

and

RB = begin state ST PARS • A $[a_1, a_2, ... = b_1, b_2, ...]$ end

$$\begin{pmatrix} (c \models (\text{begin state } ST PARS \bullet A \text{ end}) [a_1, a_2, ... = b_1, b_2, ...]) \\ \sim \\ (c \mid s \models \text{begin state } ST PARS \bullet (A [a_1, a_2, ... = b_1, b_2, ...]) \text{ end} \end{pmatrix}$$

= [Sigma Equal Basic Process 4 (having, from law B.2.18, that RP = RB]

true
B.3.20 Call Process

Attached Rule 41.

Parameterless Call Process: $(c \models P) \rightsquigarrow (c \models Content (P))$

Proof $(c \models P) \rightsquigarrow (c \models Content (P))$ = [Definition B.8] $(c \models Content (P)) \rightsquigarrow (c \models Content (P))$ = [Sigma Equal Sides 3] true

Attached Rule 42.

Call Process with normal parameters: $(c \mid s \models P(N+)) \rightsquigarrow (c \models ParamContent(P, [N+]))$

Proof

 $(c \models P) \rightsquigarrow (c \models Content (P, [N+]))$ = [Definition B.9] $(c \models ParamContent (P, [N+])) \rightsquigarrow (c \models ParamContent (P, [N+]))$ true

Attached Rule 43.

Call Process with indexed parameters: $(c \models P \mid N+ \mid) \rightsquigarrow (c \models IndexedContent (P, [N+]))$

Proof

(c ⊨ P [N+]) → (c ⊨ IndexedContent (P, [N+])) = [Definition B.10] (c ⊨ IndexedContent (P, [N+])) → (c ⊨ IndexedContent (P, [N+])) = [Sigma Equal Sides 3] true

Attached Rule 44.

Call Process with generic parameters: $(c \models P [N+]) \rightsquigarrow (c \models GenericContent (P, [N+]))$

Proof

 $(c \models P [N+]) \rightsquigarrow (c \models GenericContent (P, [N+]))$

```
= [Definition B.11]
(c ⊨ GenericContent (P, [N+])) ~→ (c ⊨ GenericContent (P, [N+]))
= [Sigma Equal Sides 3]
true
```

B.3.21 Iterated Process

Attached Rule 45.

Iterated Processes: $(c \models OP \ Decl \bullet P) \rightsquigarrow (c \models IteratedExpansion (P, Decl, ITOPFLAG))$ IteratedExpansion is defined on B.3.

Proof (c \models OP Decl • P) \rightsquigarrow (c \models IteratedExpansion (P, Decl, ITOPFLAG))

= [Definition of Iterated Operator **B.3**]

(c ⊨ IteratedExpansion (P, Decl, ITOPFLAG)) → (c ⊨ IteratedExpansion (P, Decl, ITOPFLAG))

= [Silent Transition Equal Sides 3]

true

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